

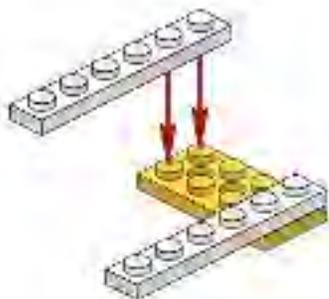


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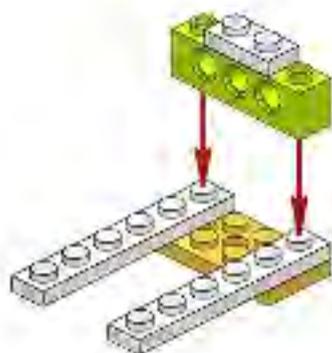


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1x

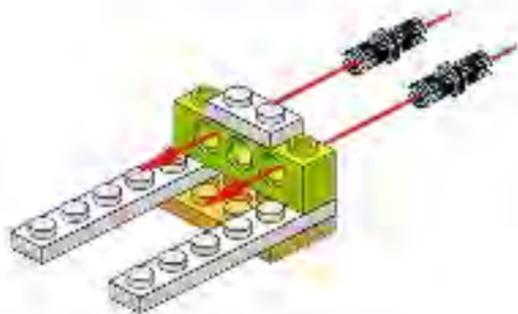
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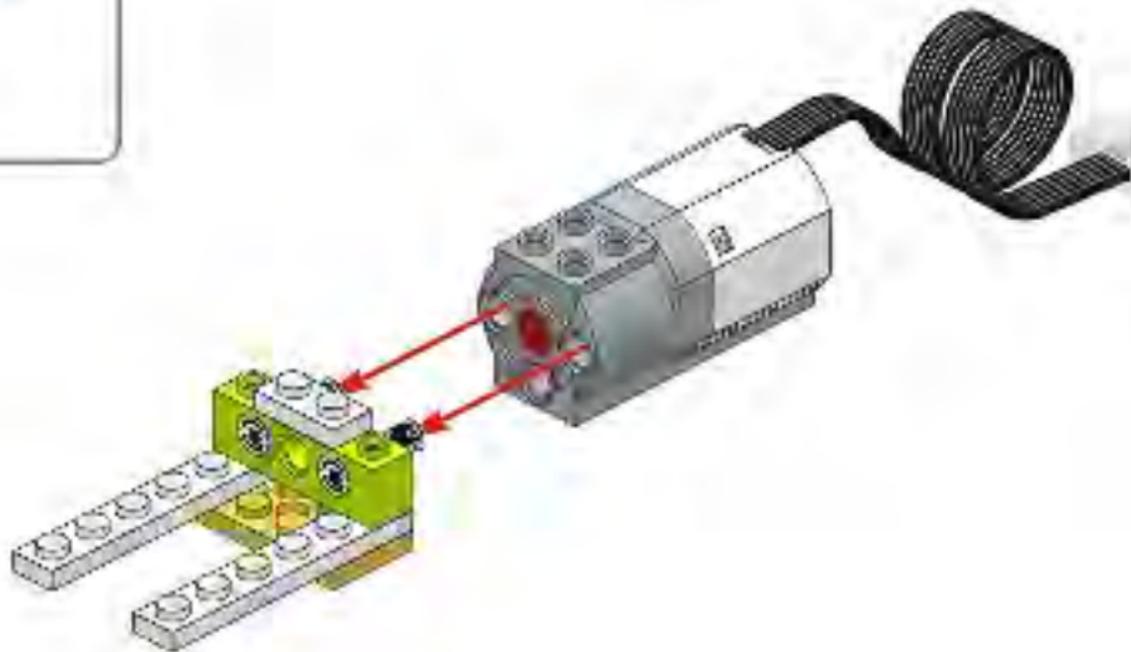
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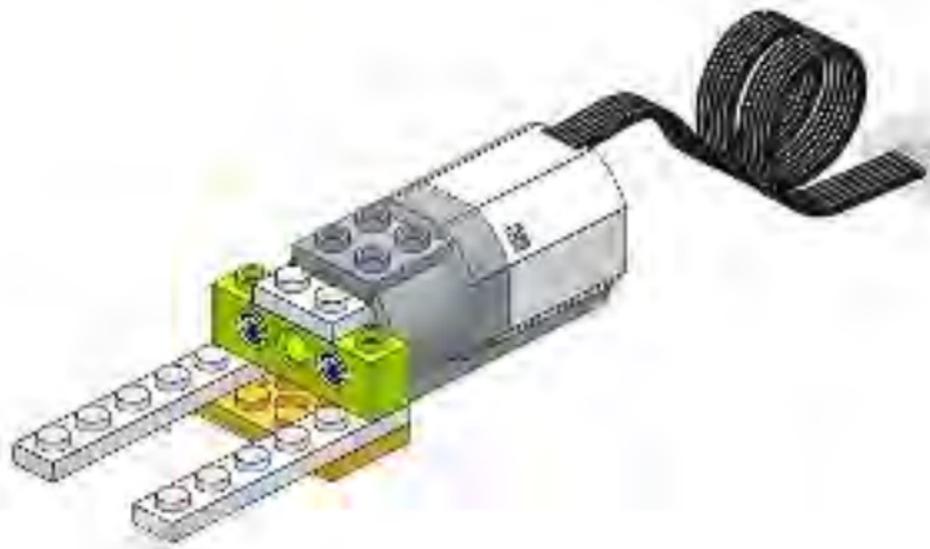




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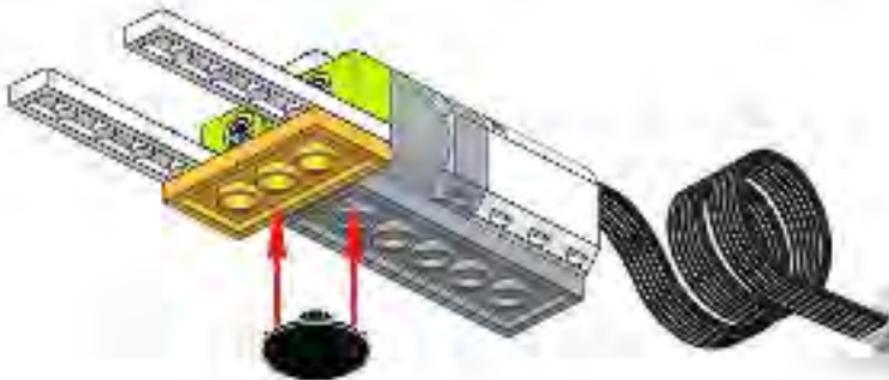


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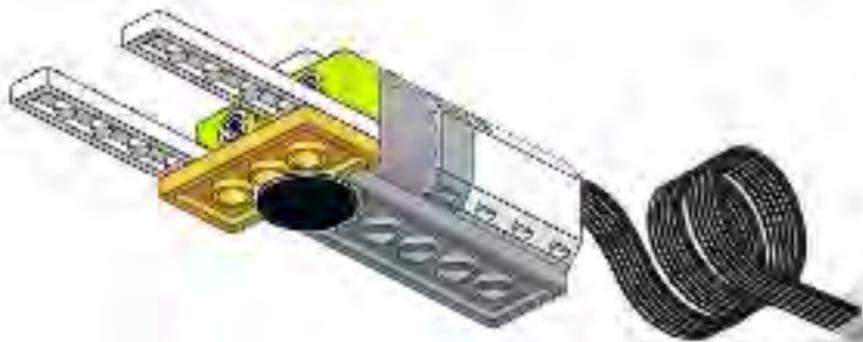




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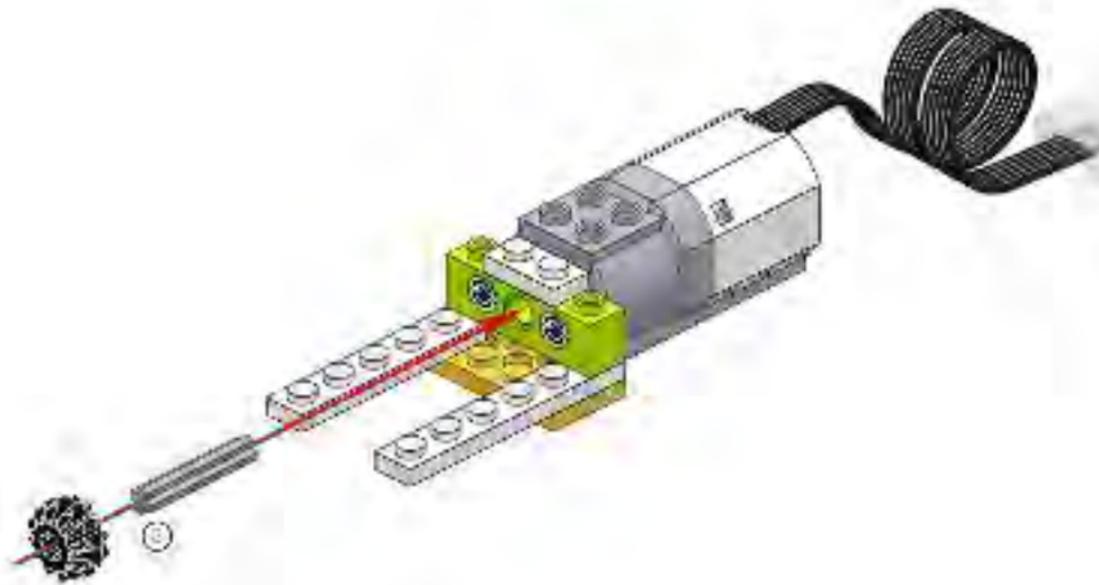


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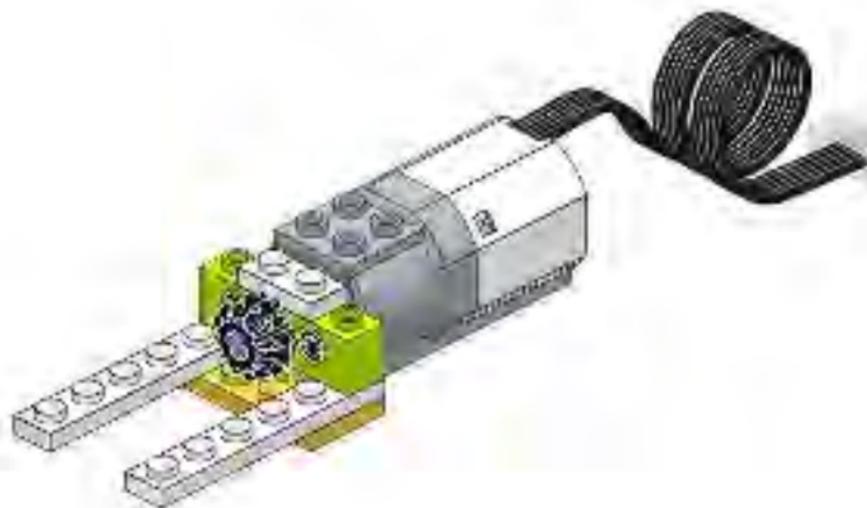




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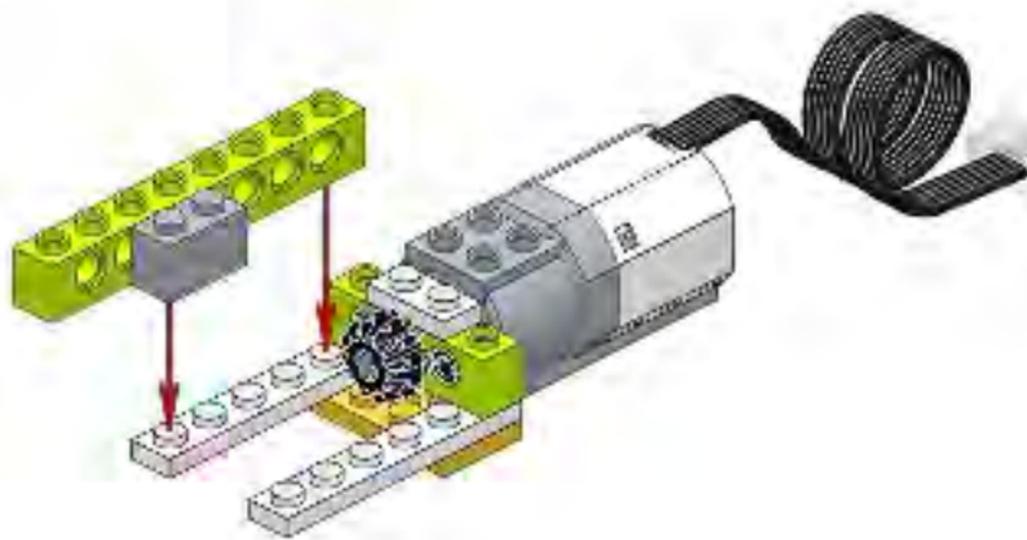


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1x

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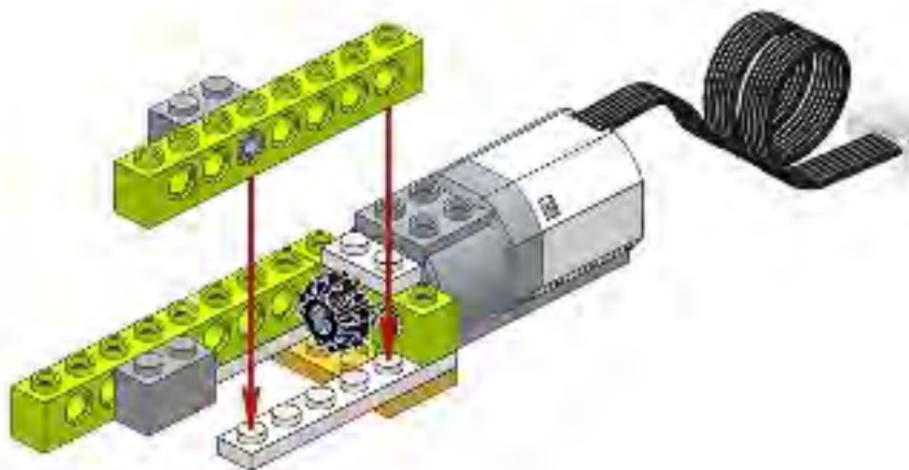




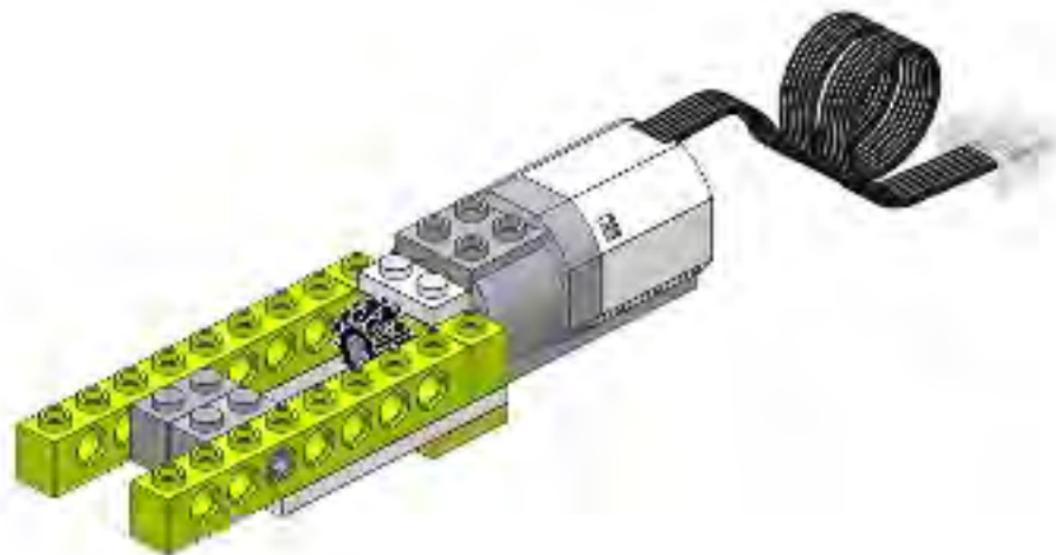
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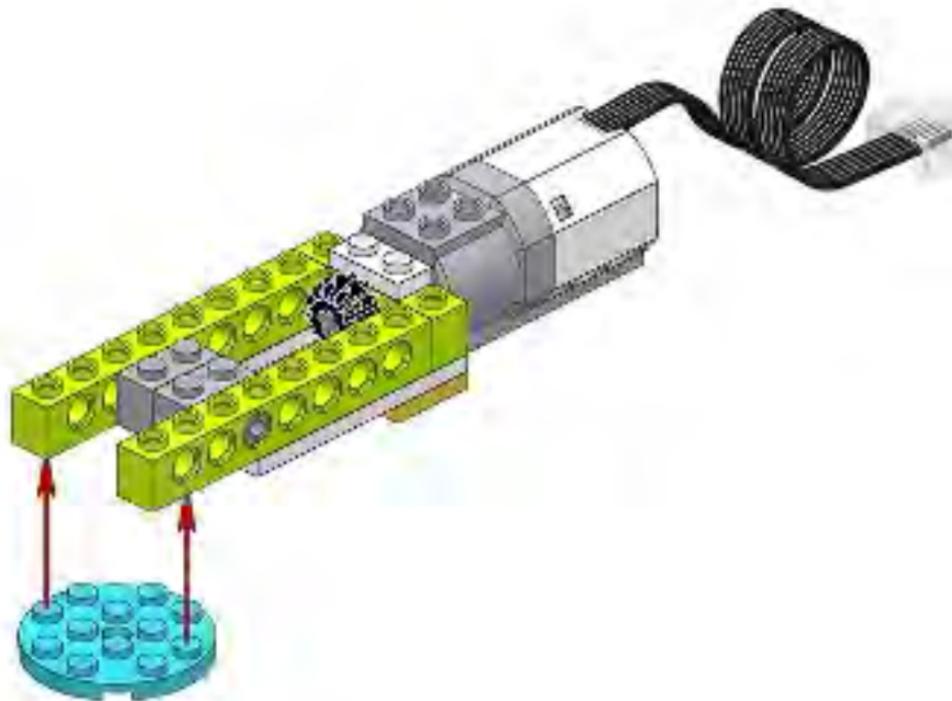
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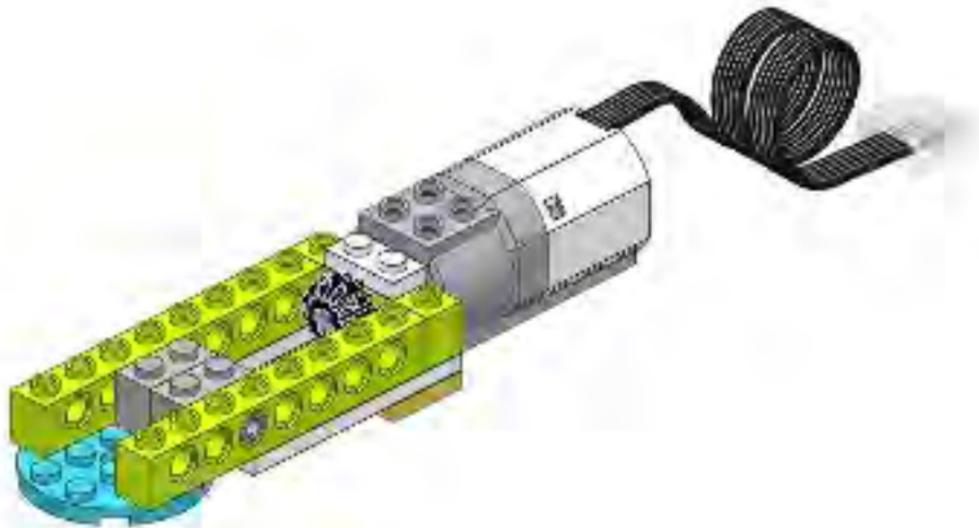


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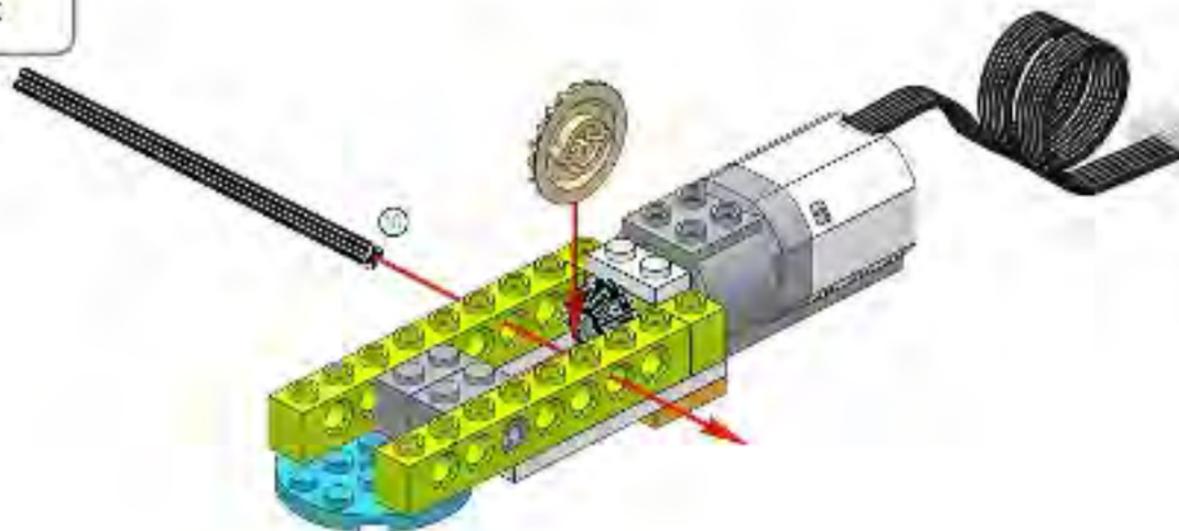


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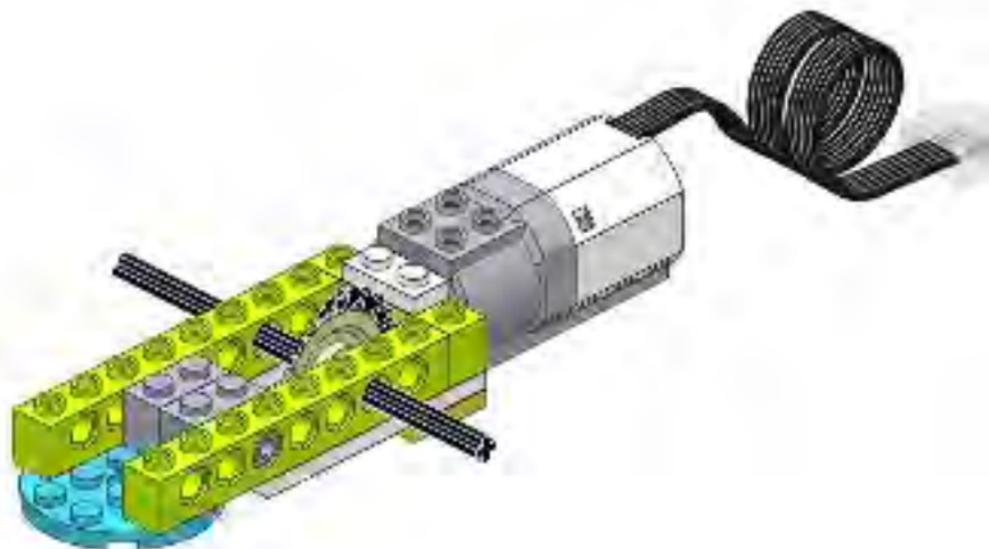




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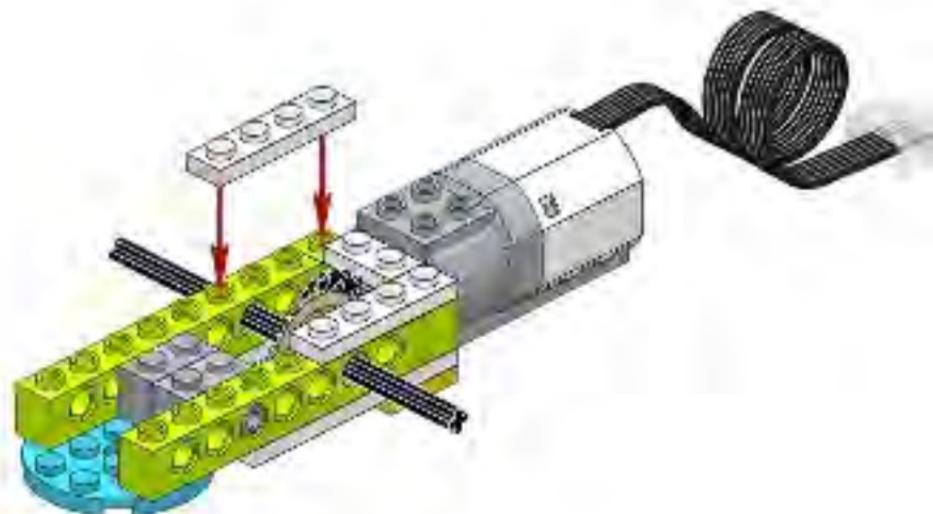
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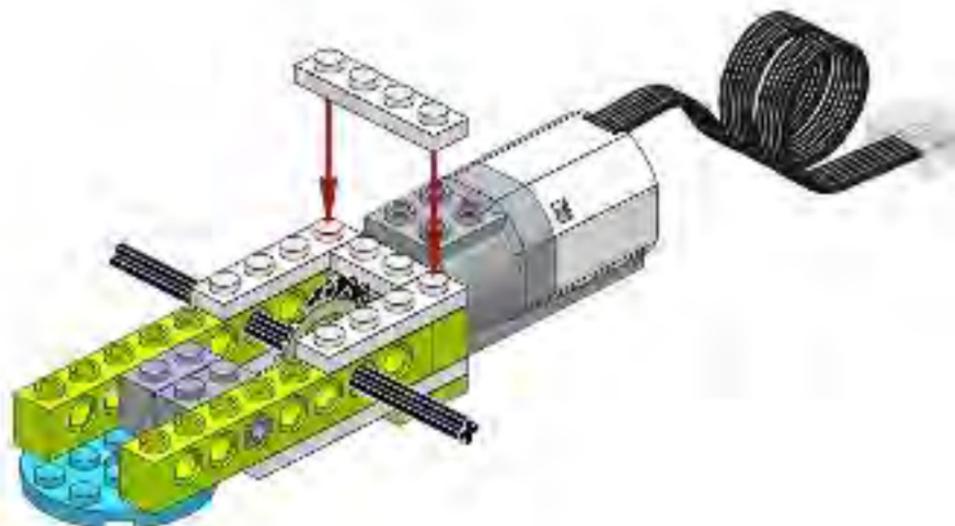
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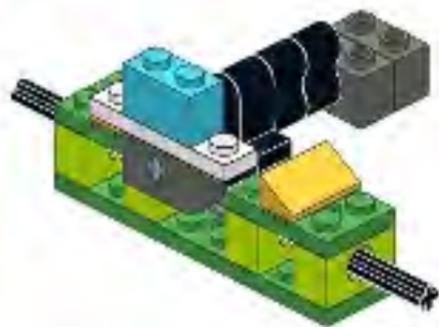


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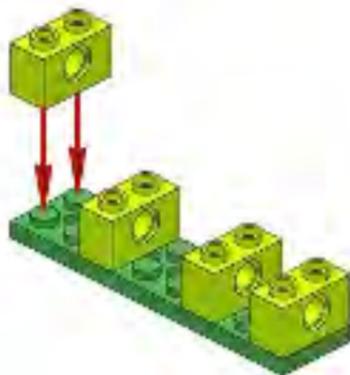


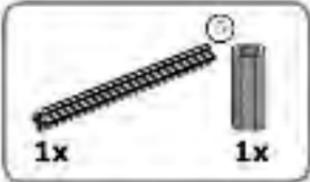
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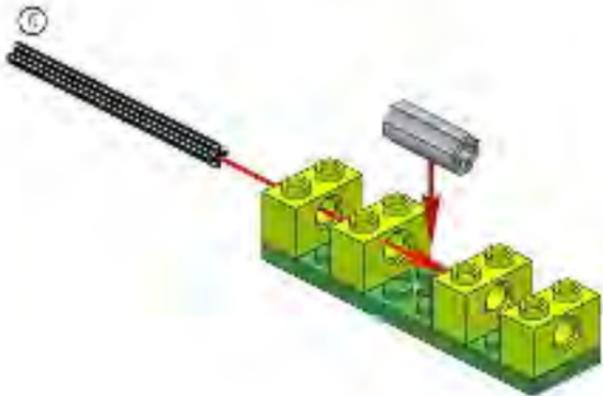
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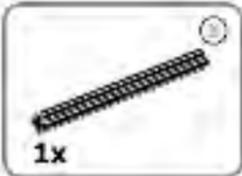
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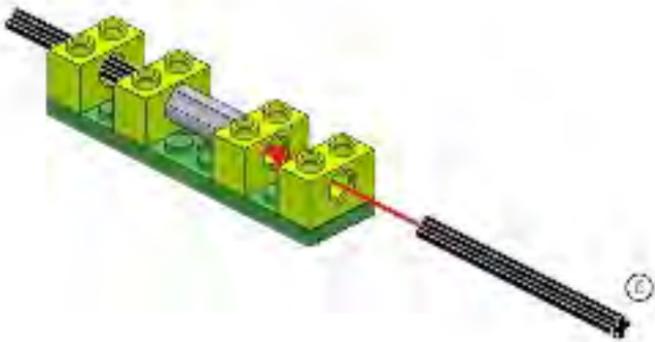


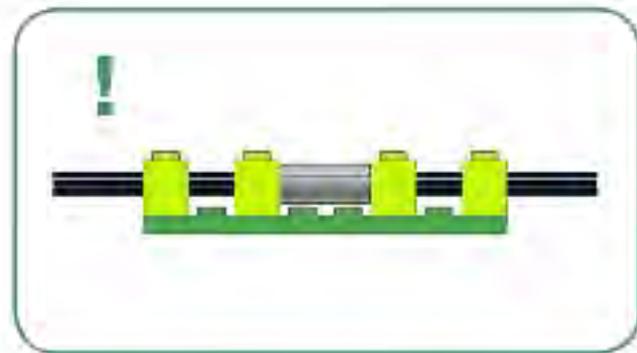
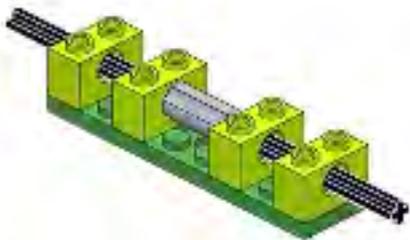
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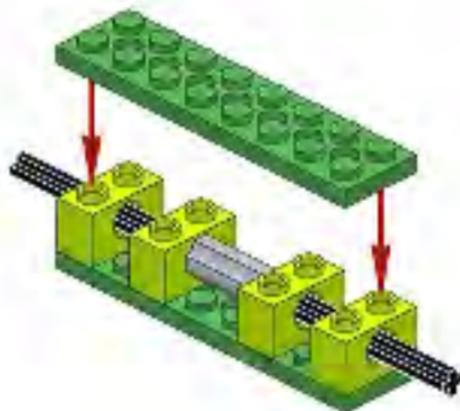




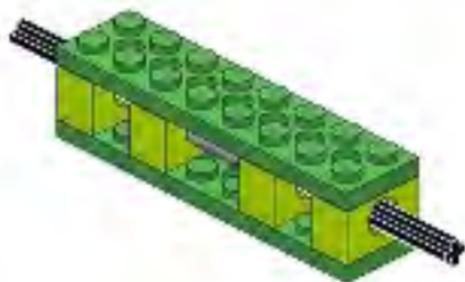


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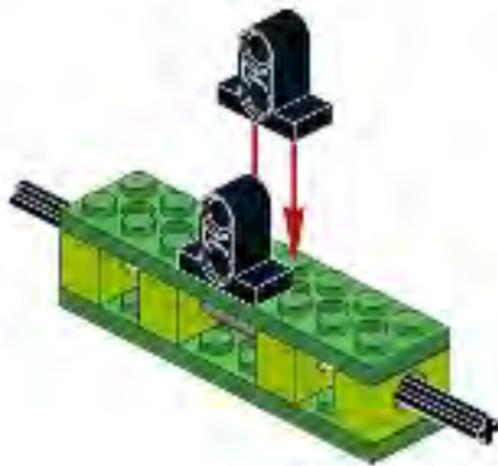
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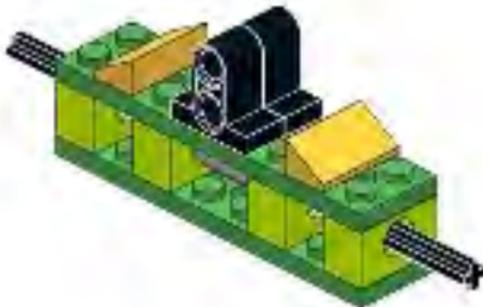
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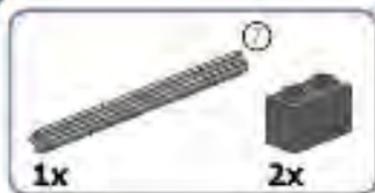




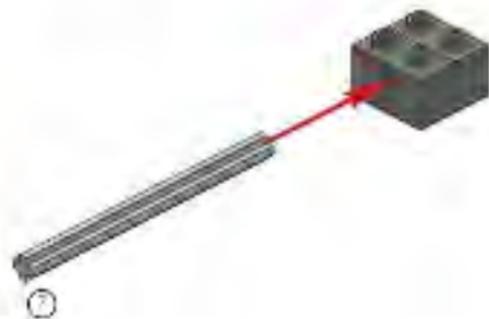
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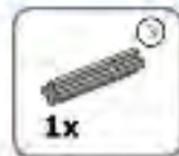




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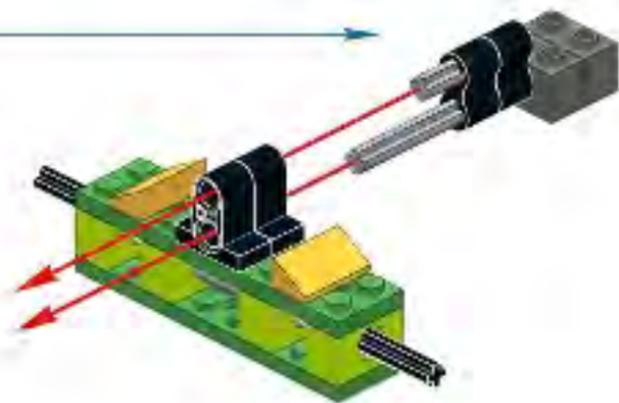
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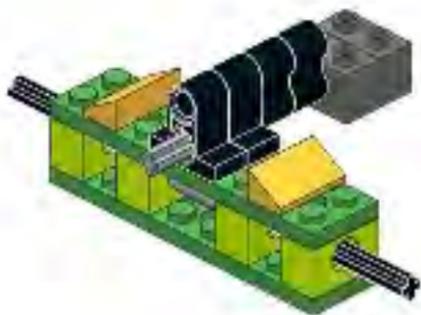
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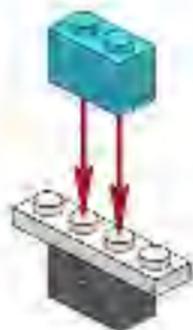




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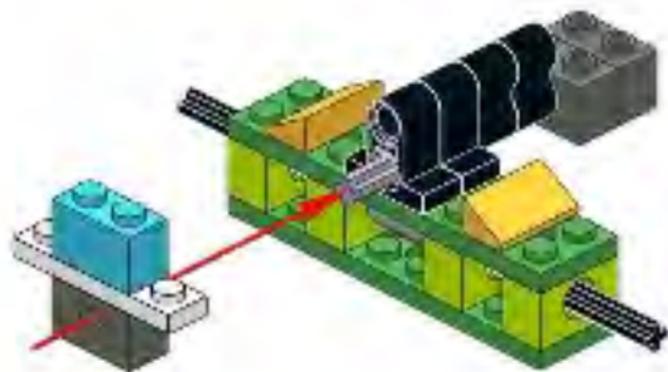
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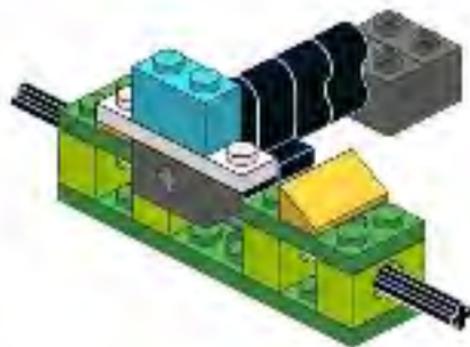
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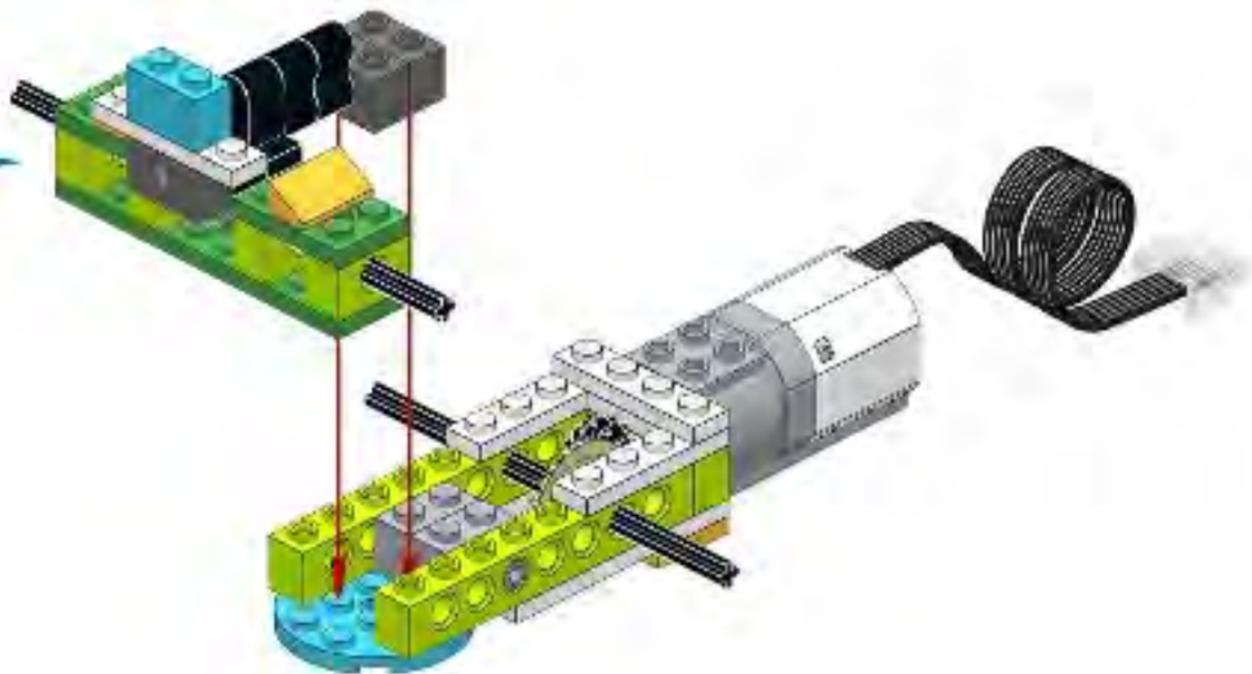
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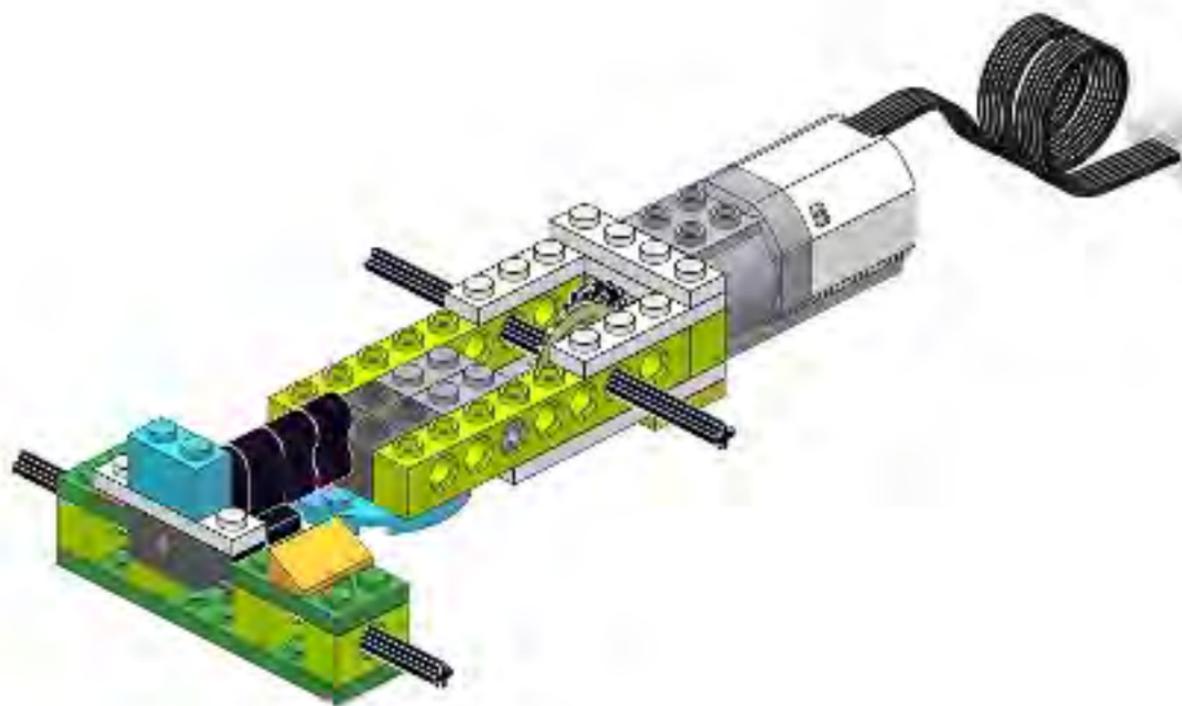
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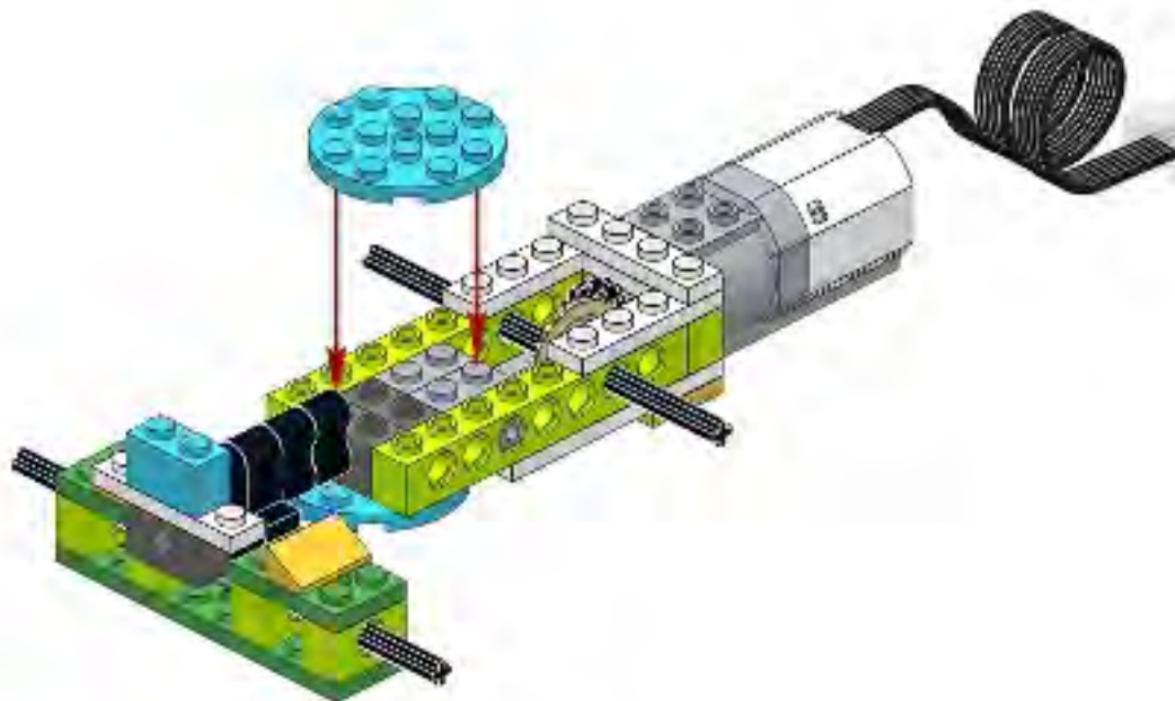
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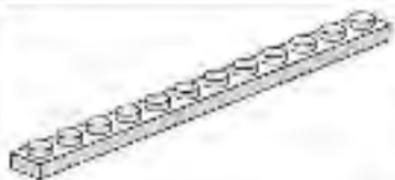


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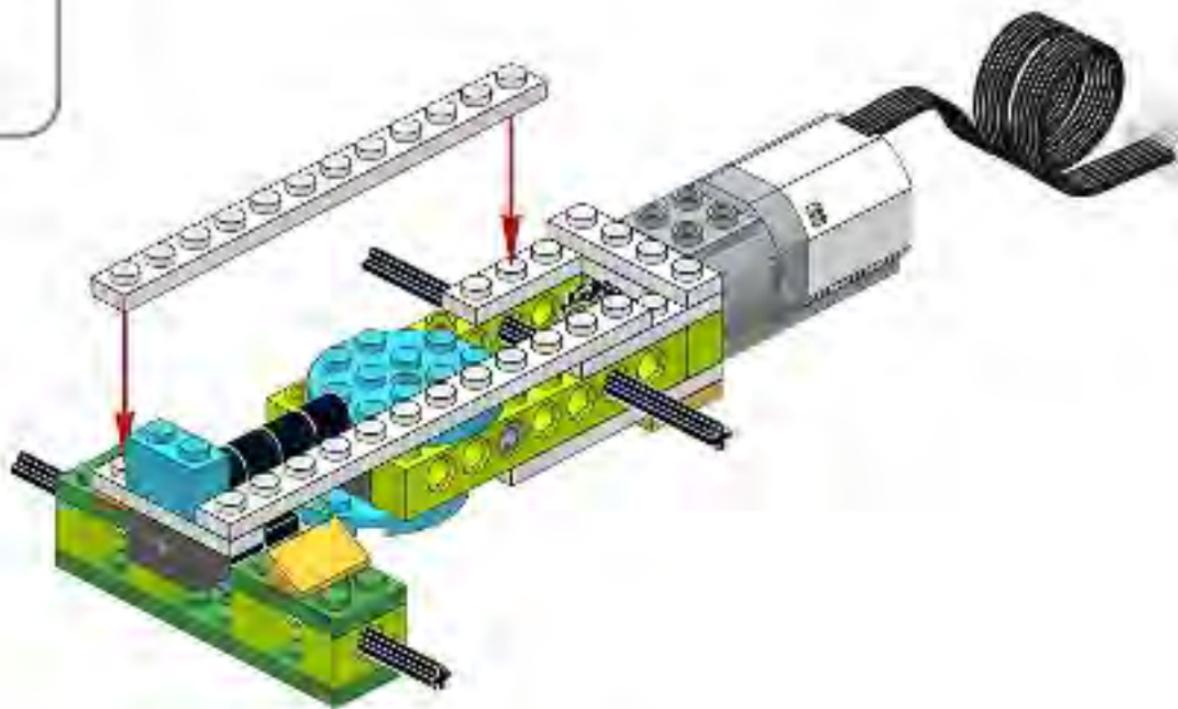




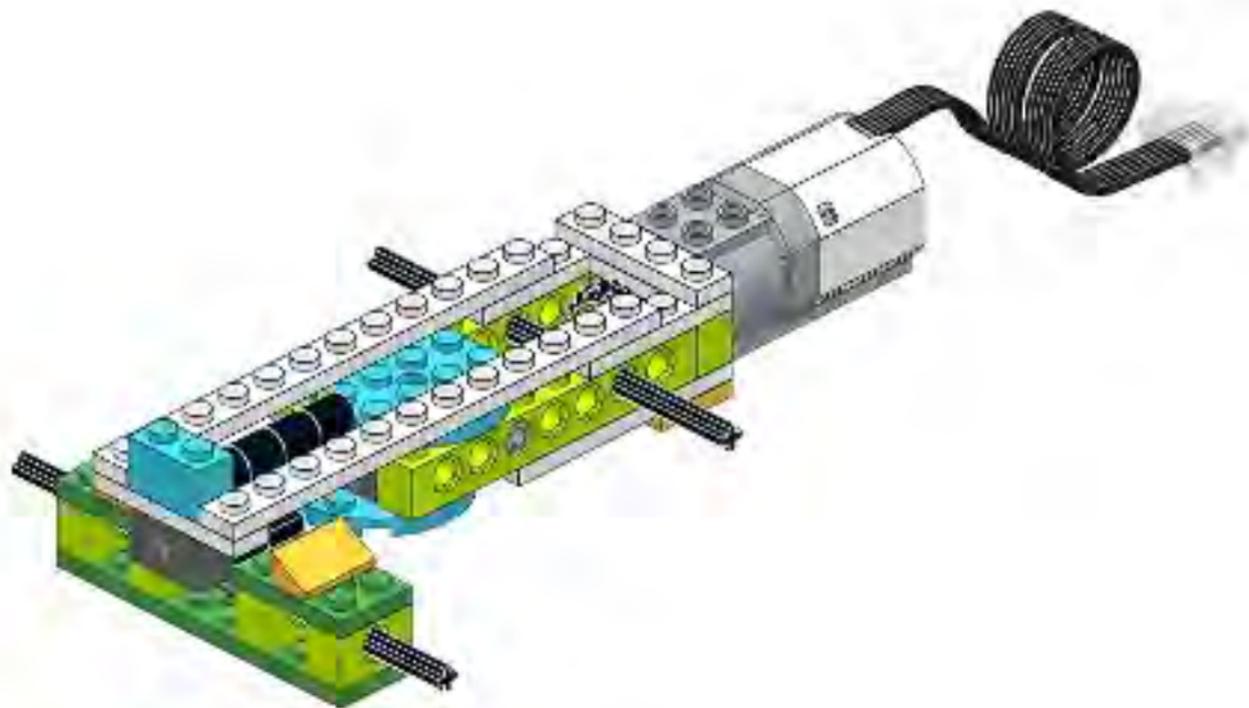


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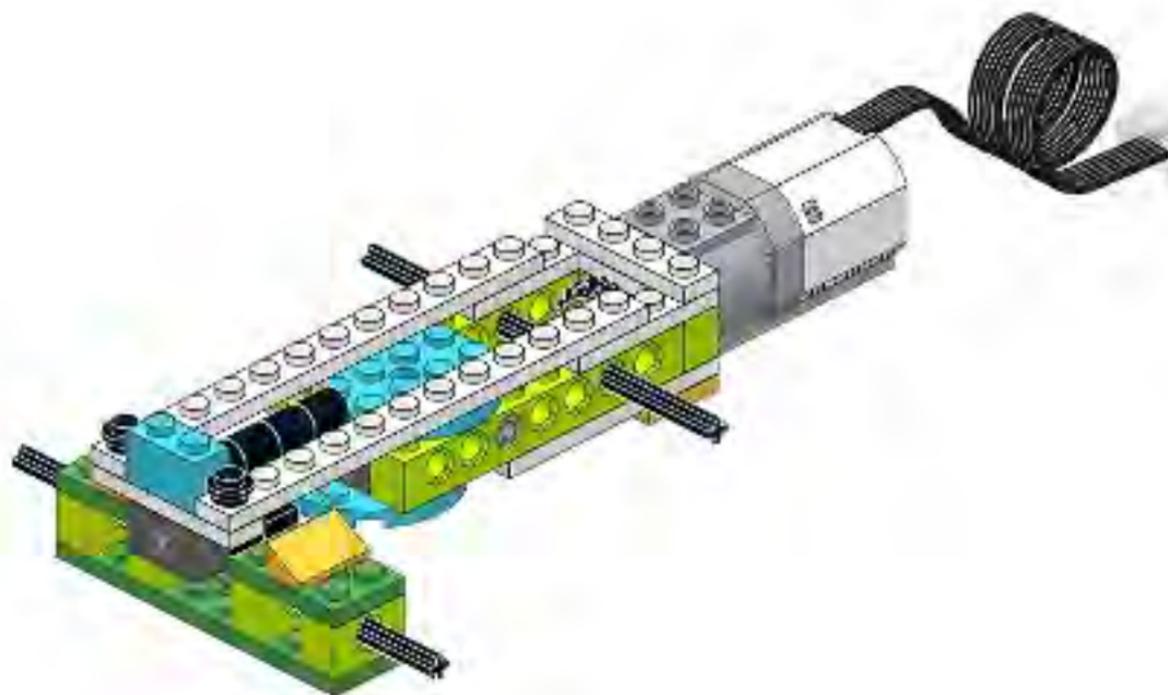
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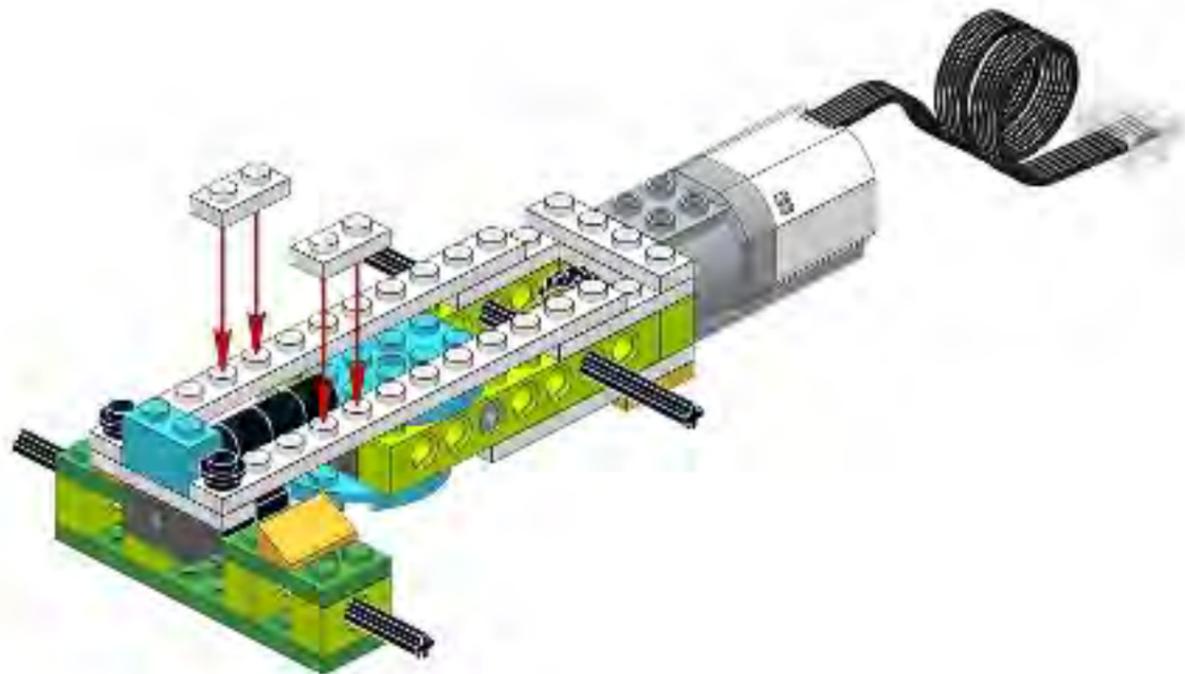
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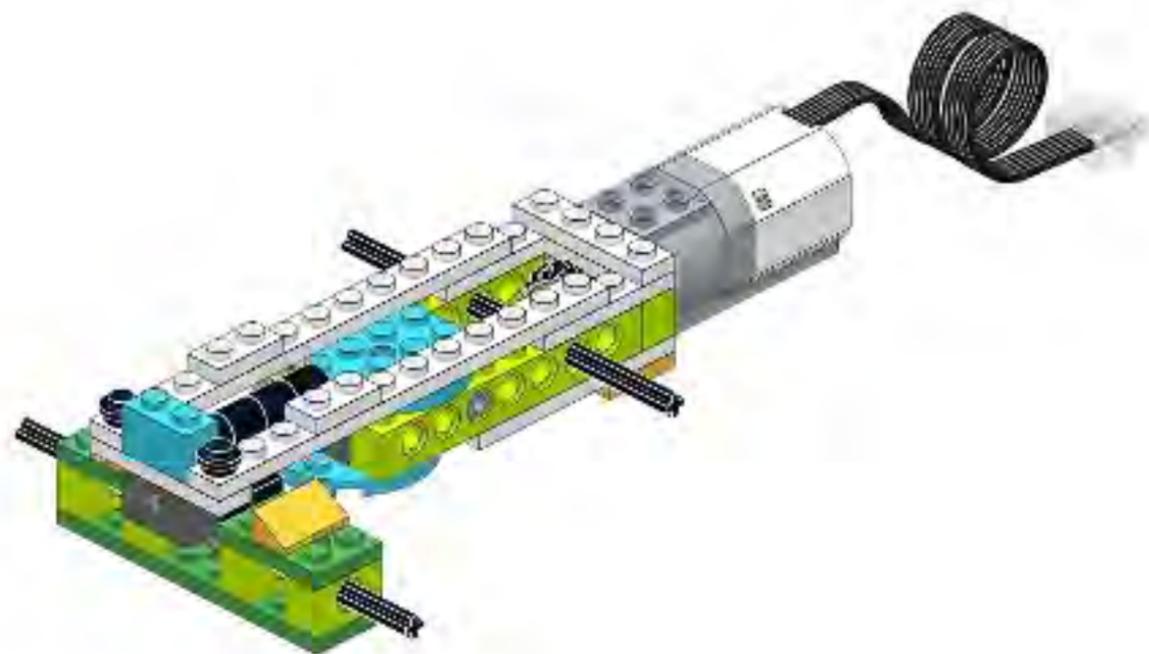


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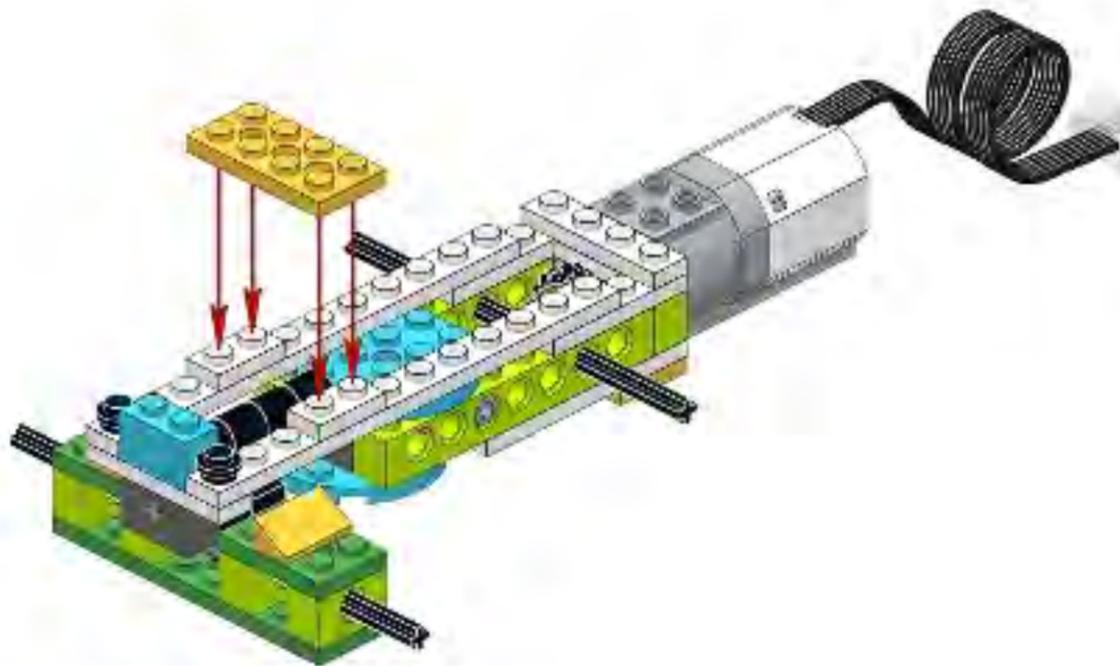
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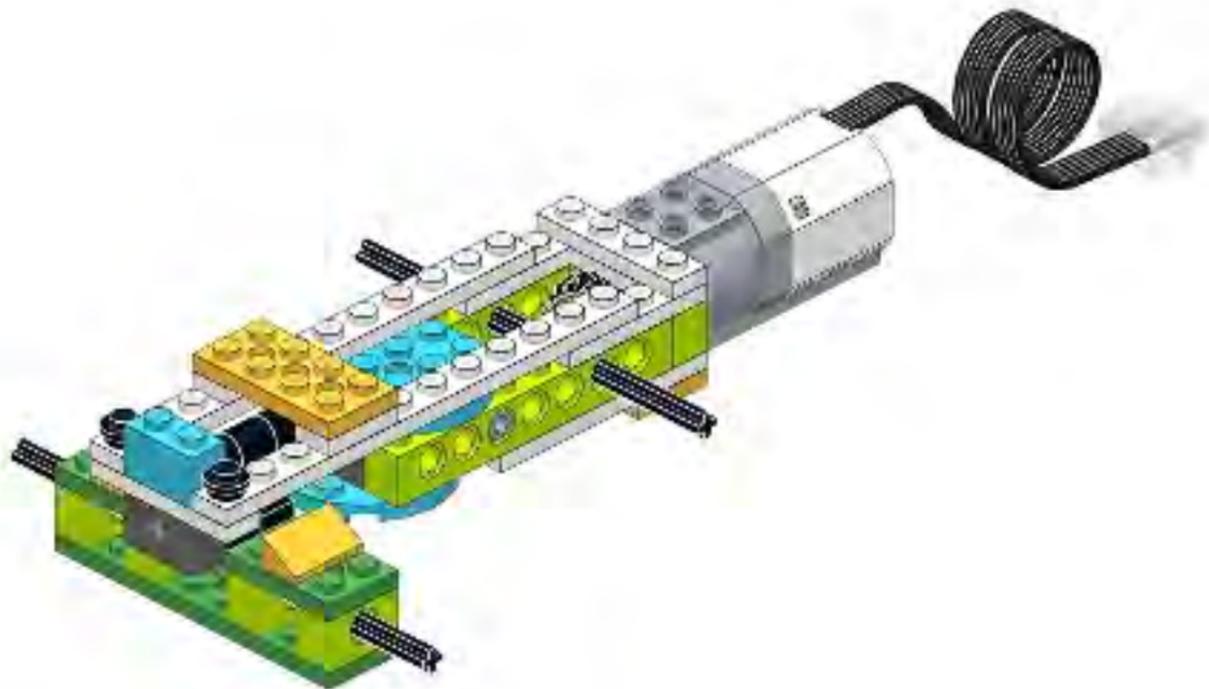


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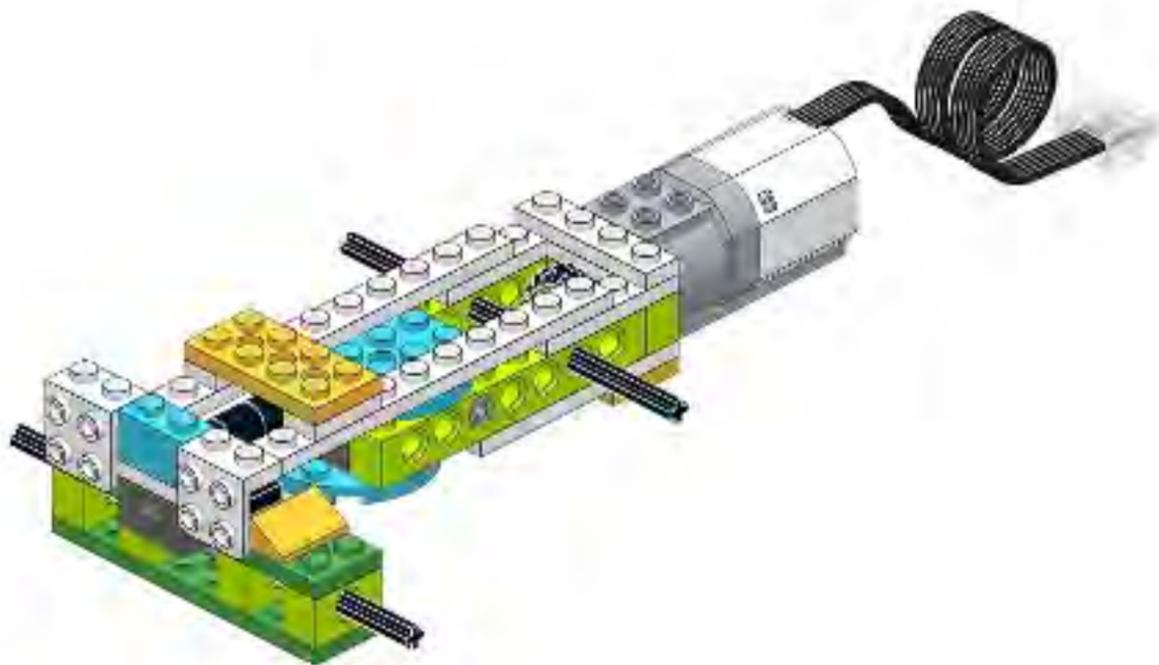


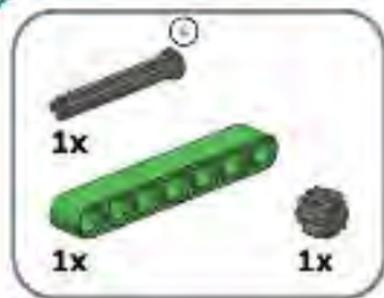
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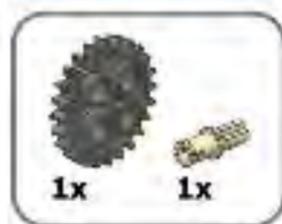


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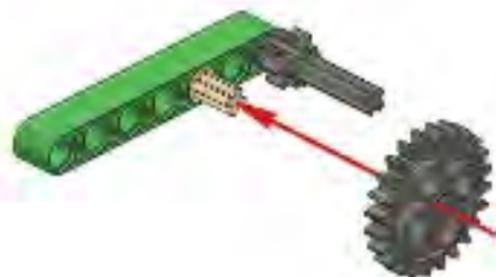




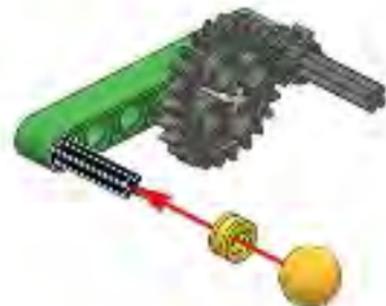
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2



3





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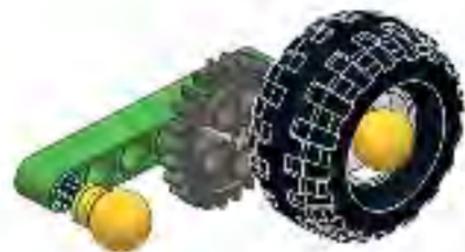


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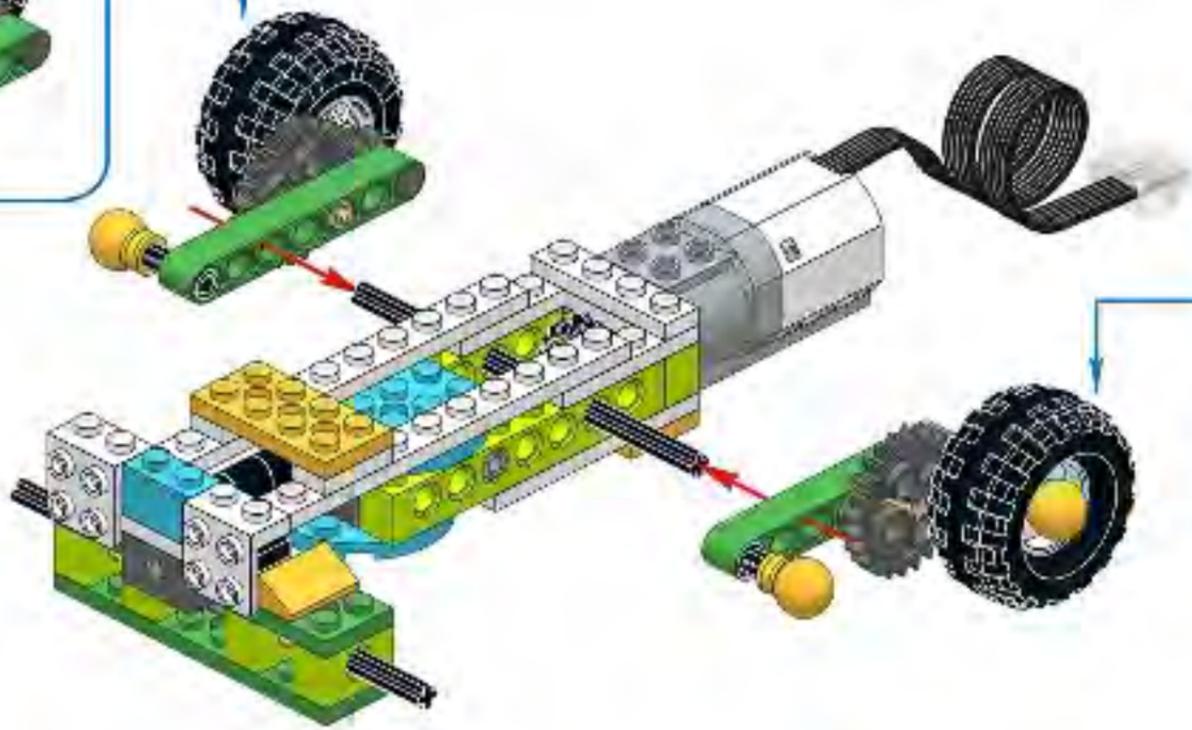
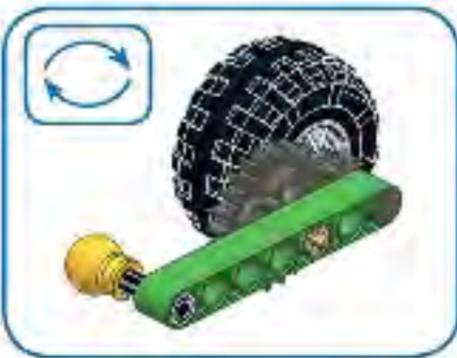
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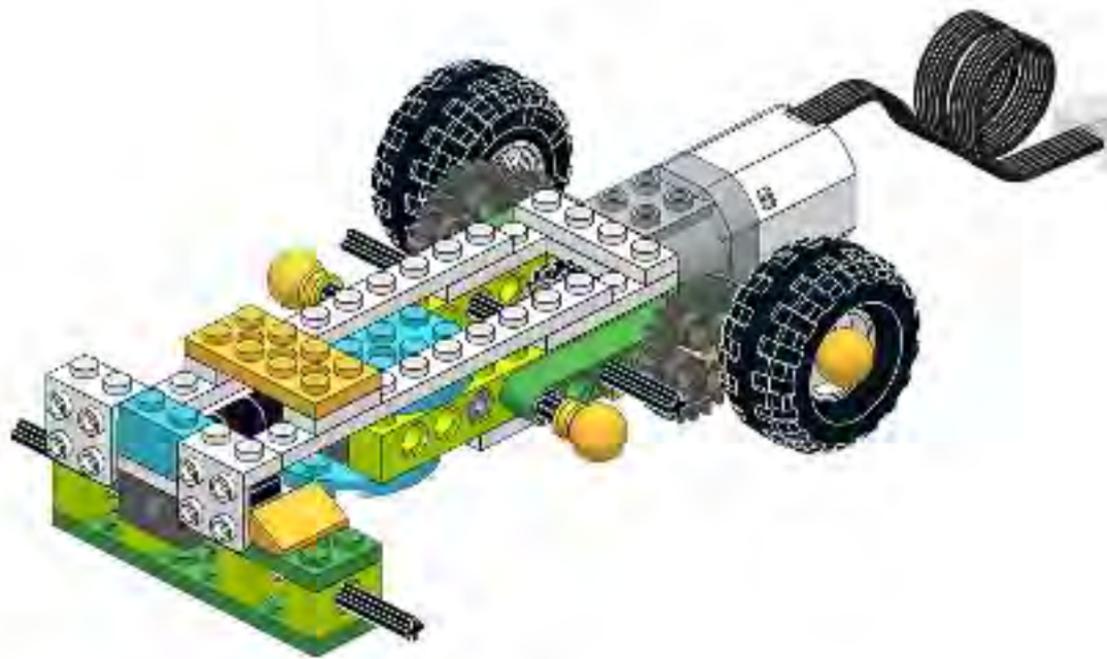
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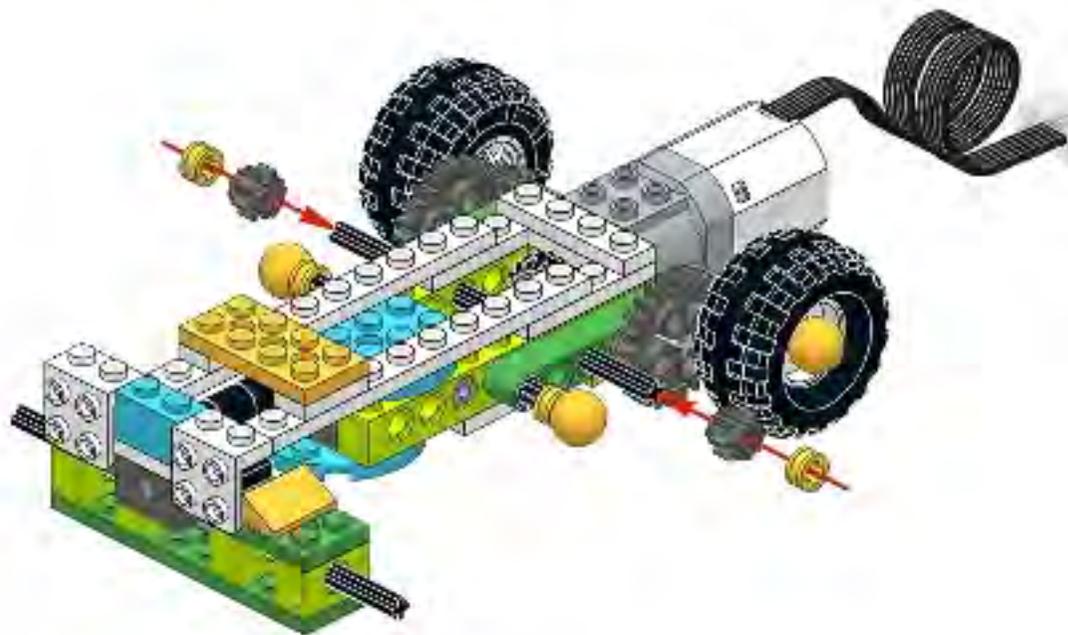


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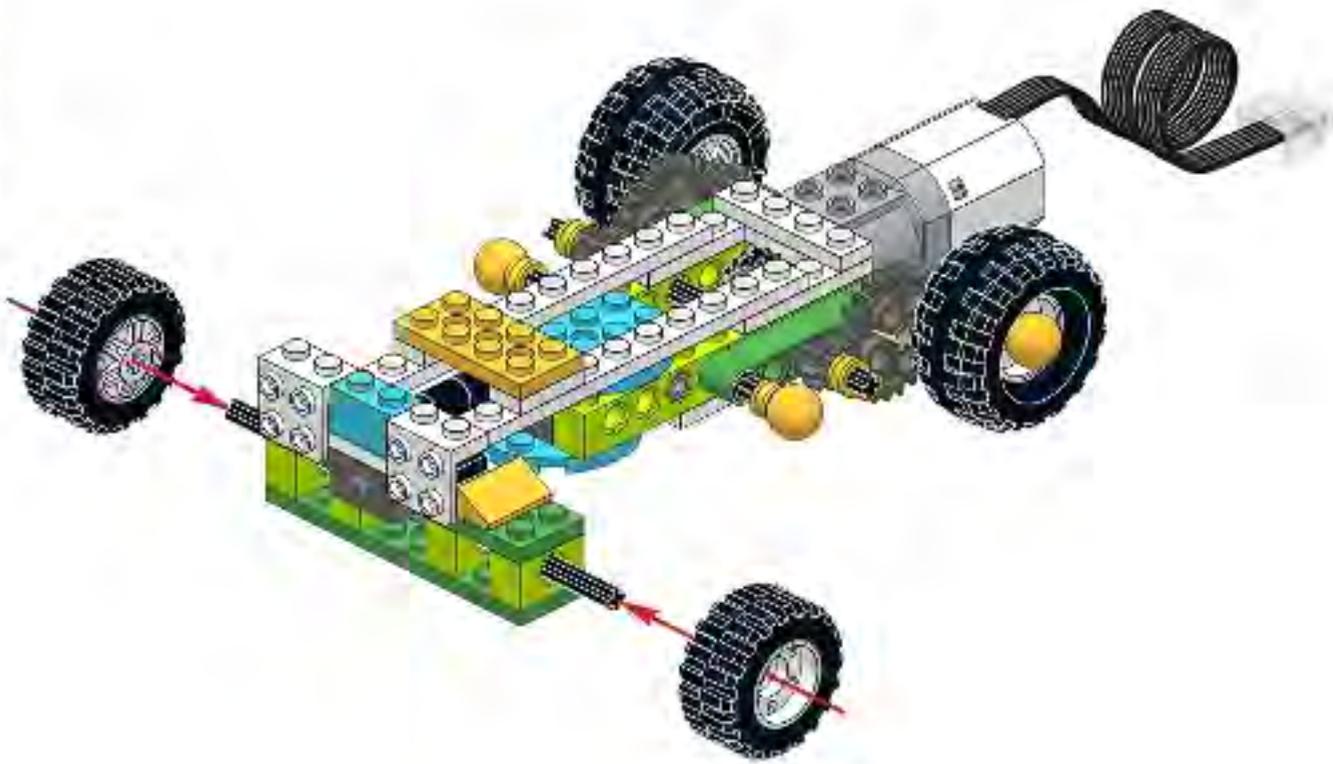
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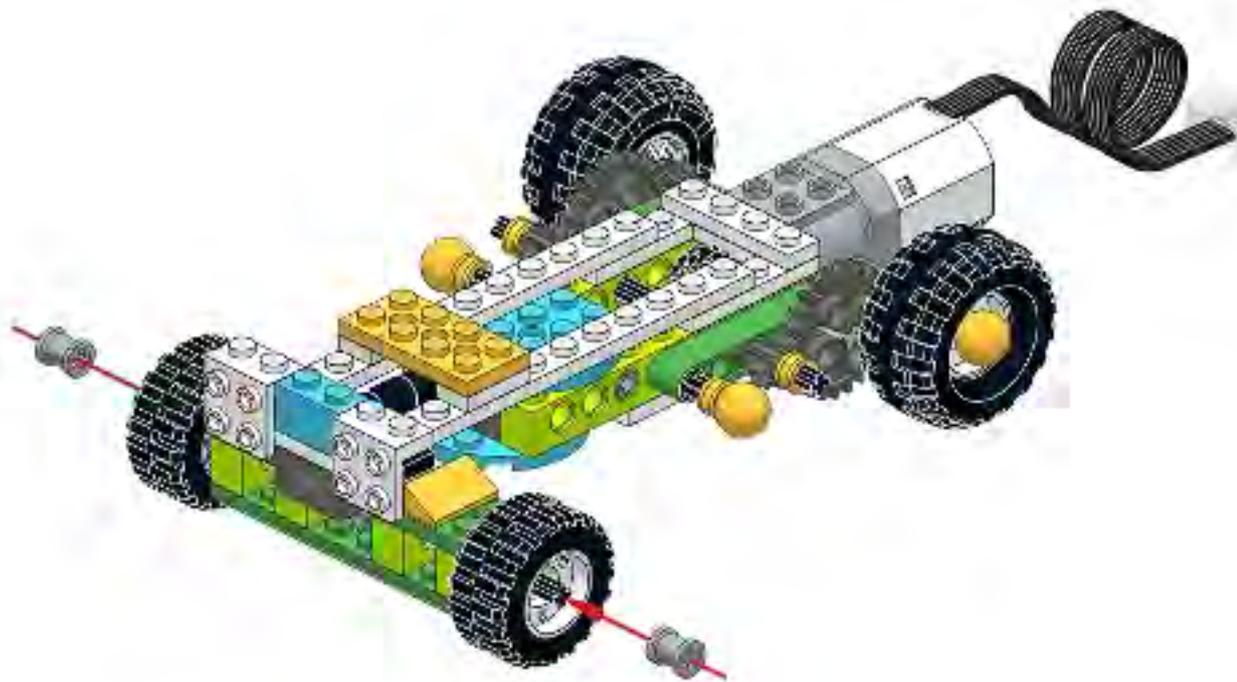
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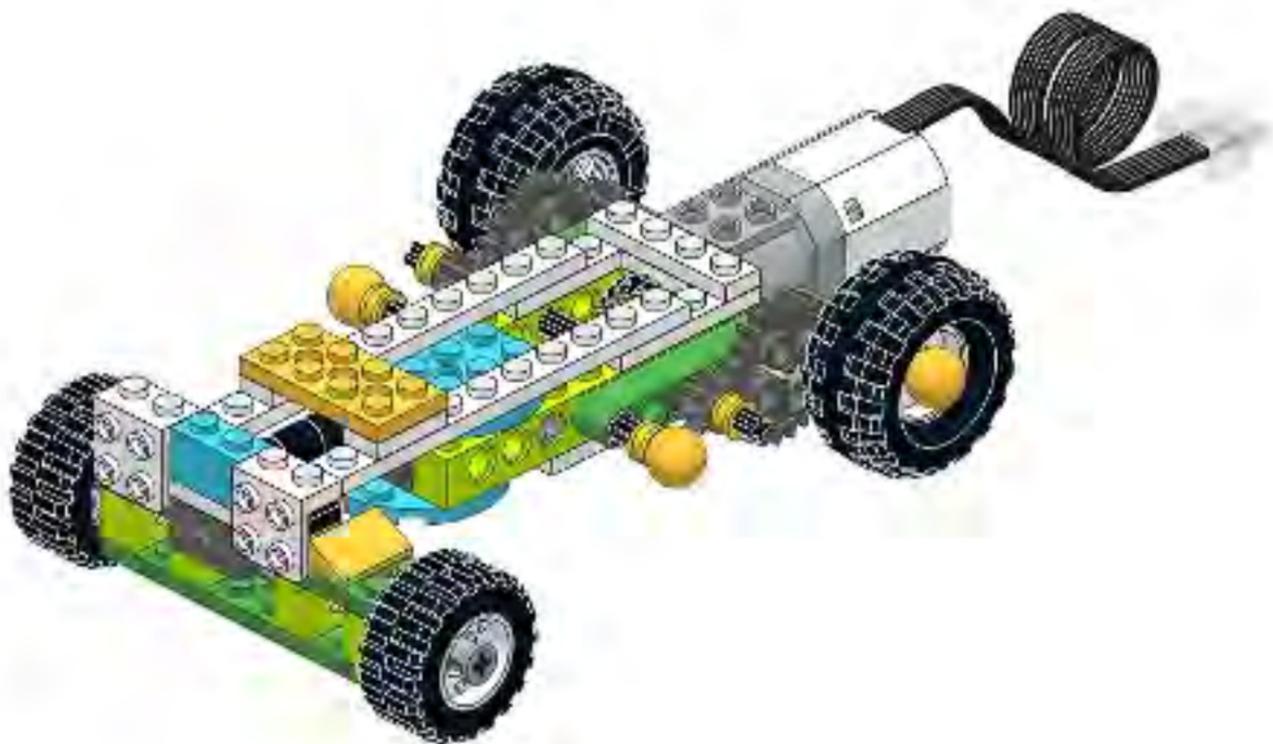


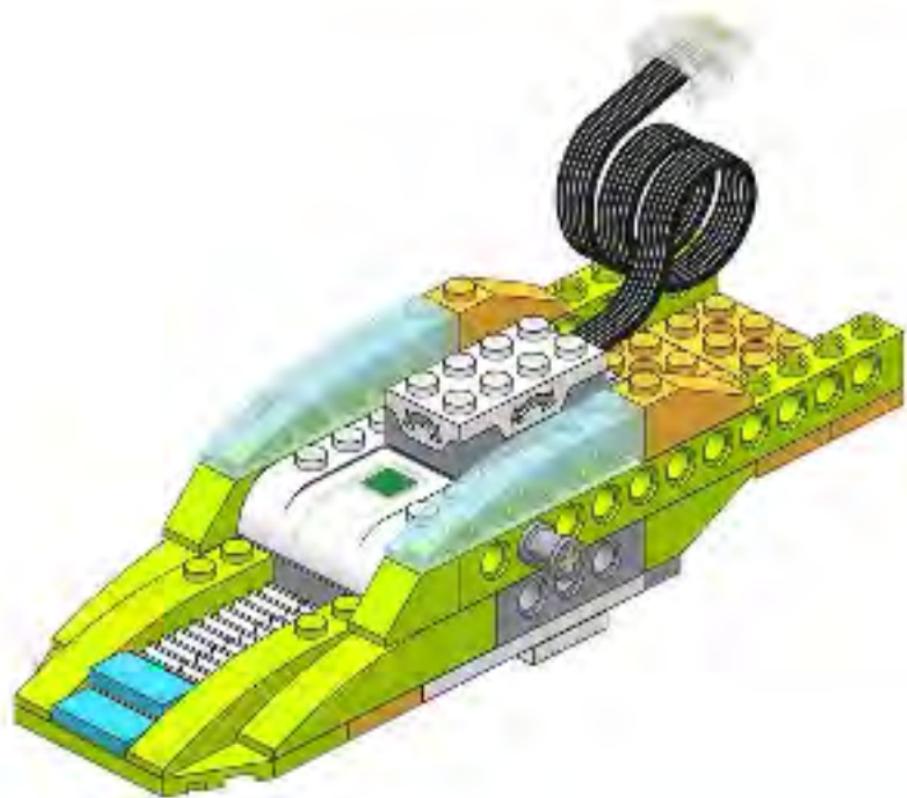
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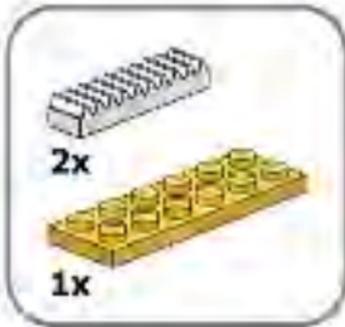
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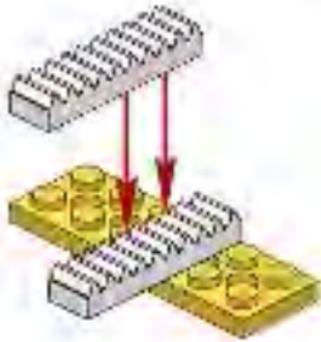
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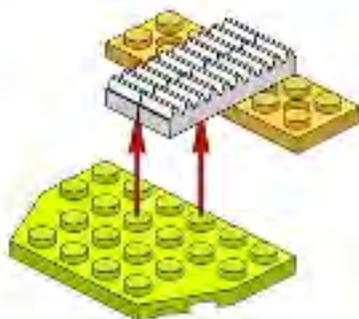
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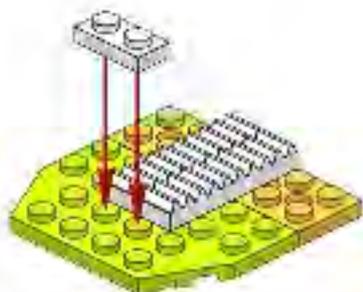
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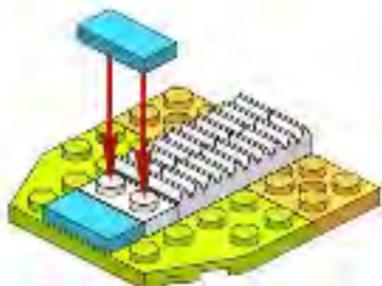
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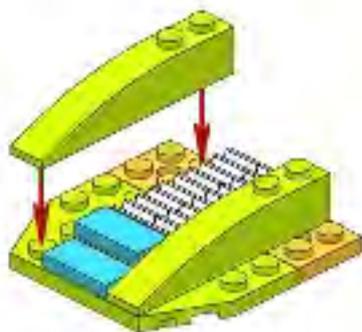
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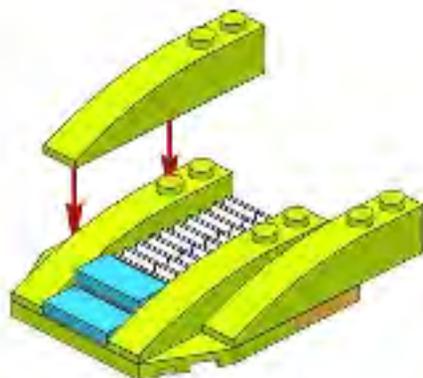
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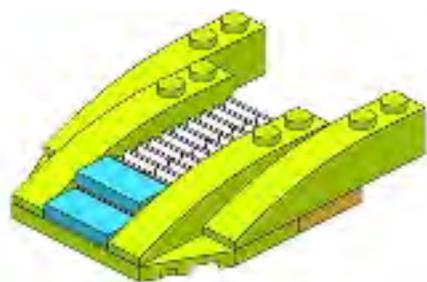


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62



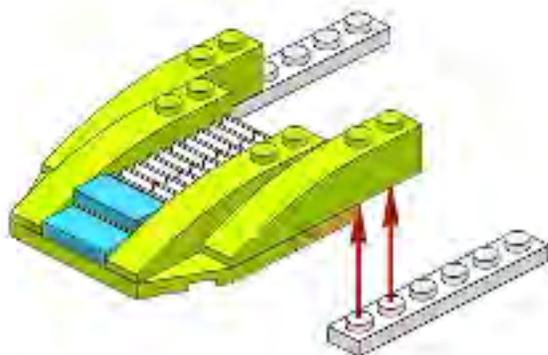
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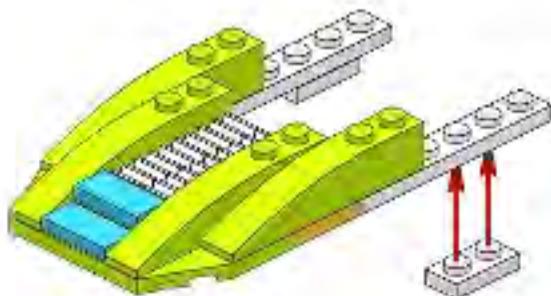
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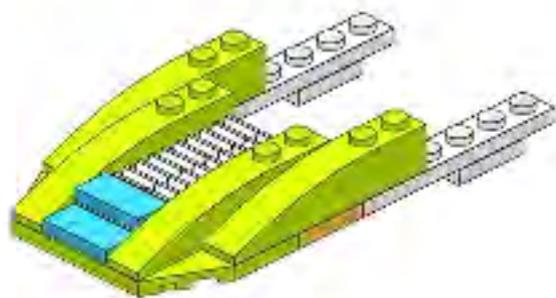


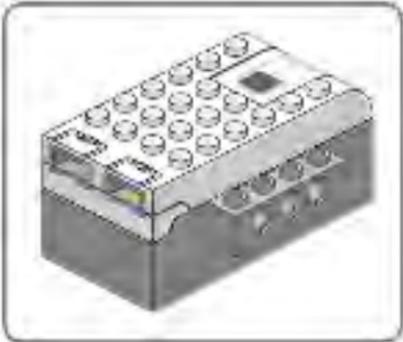
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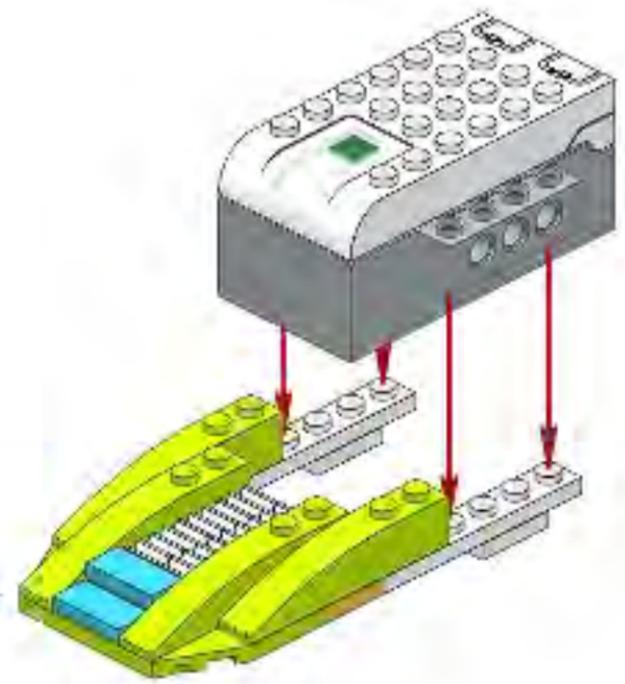


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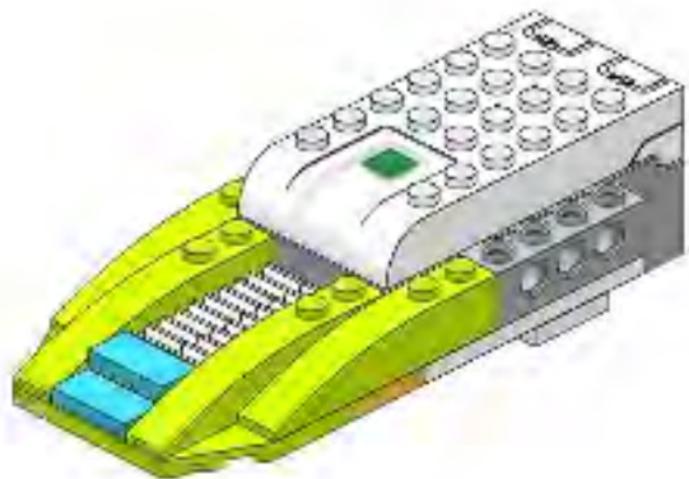


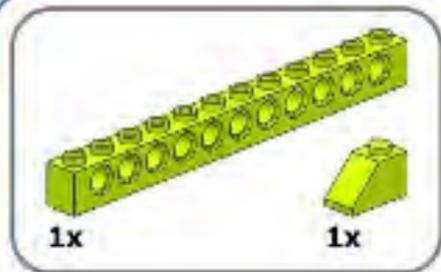


**67**

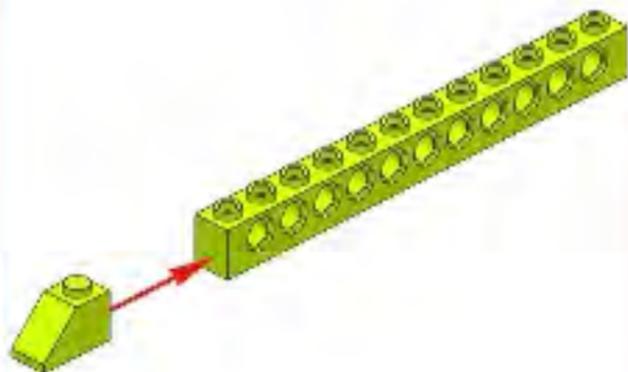


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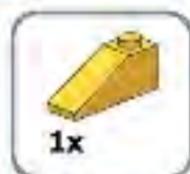
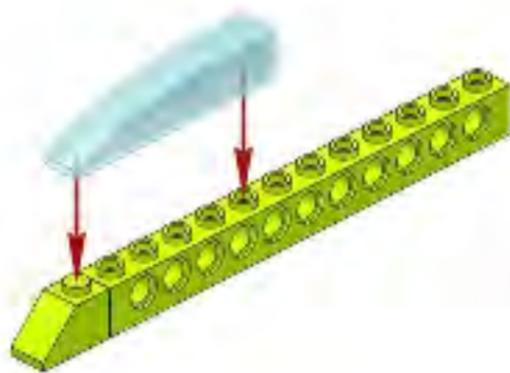




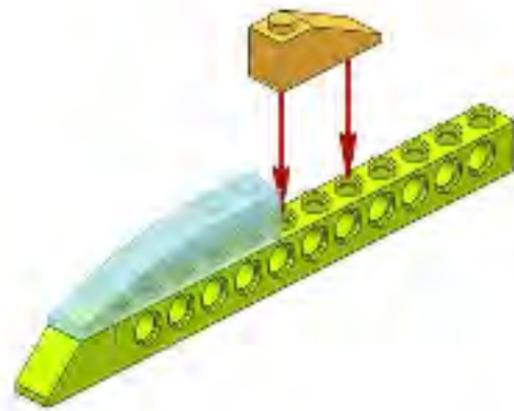
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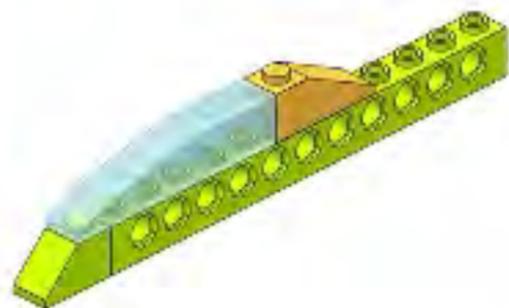
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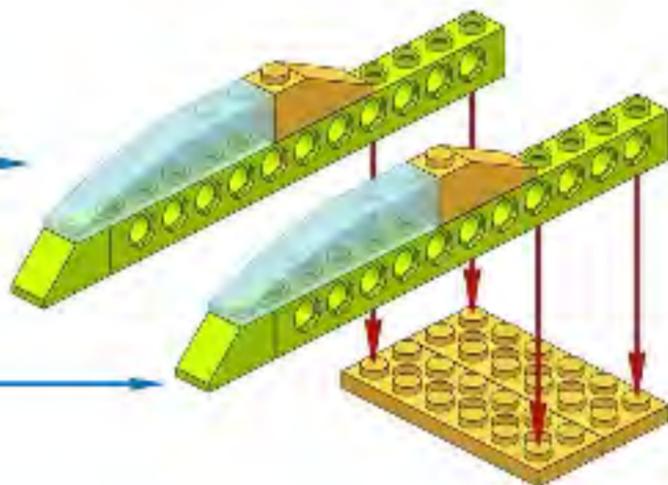
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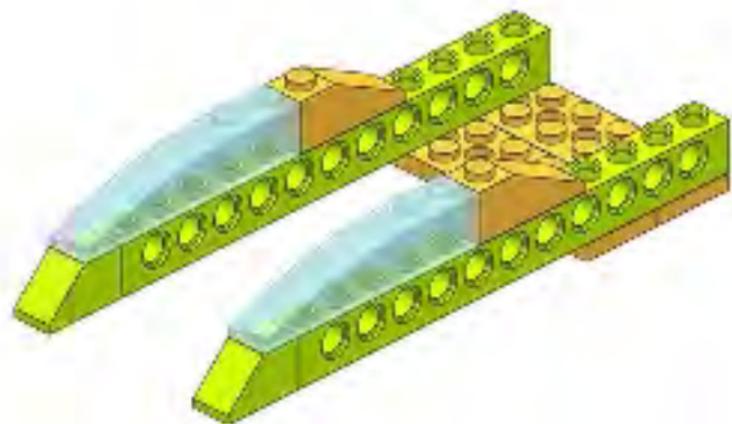
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2x



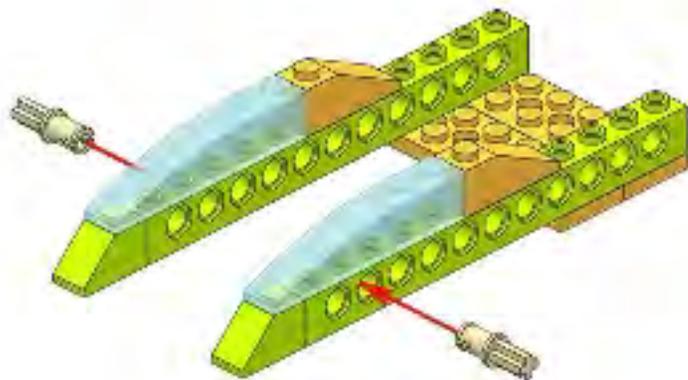
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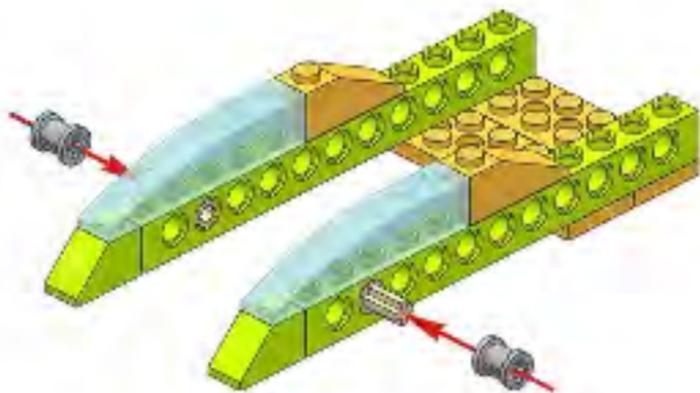
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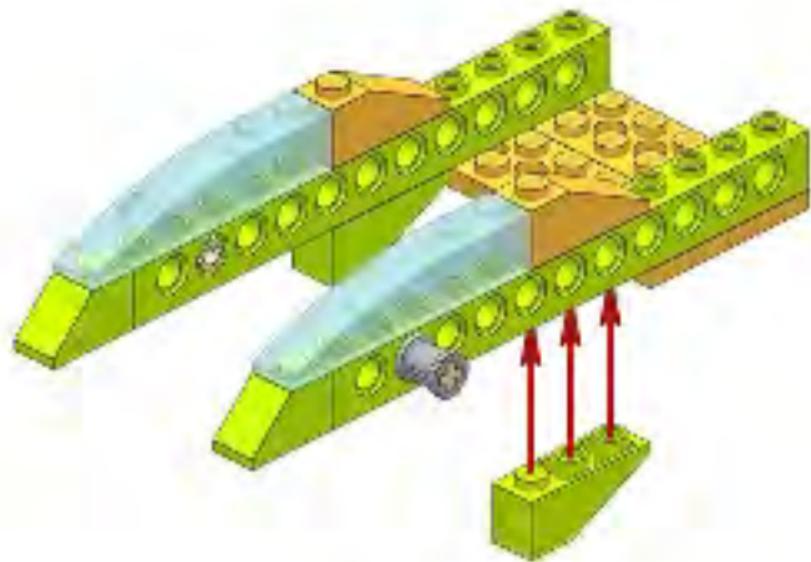
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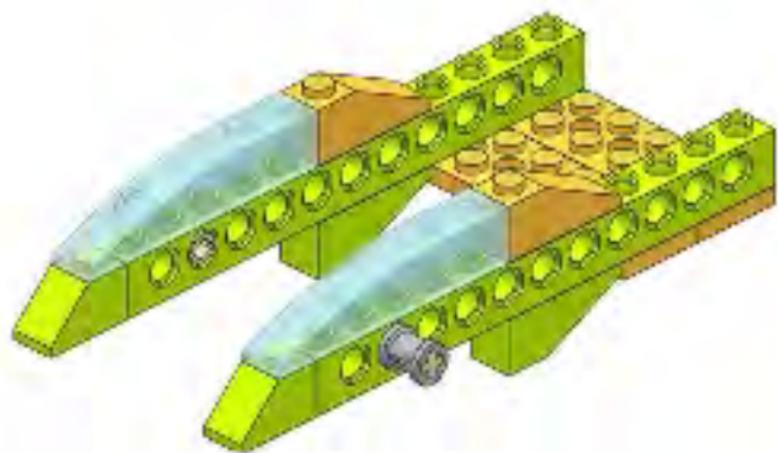


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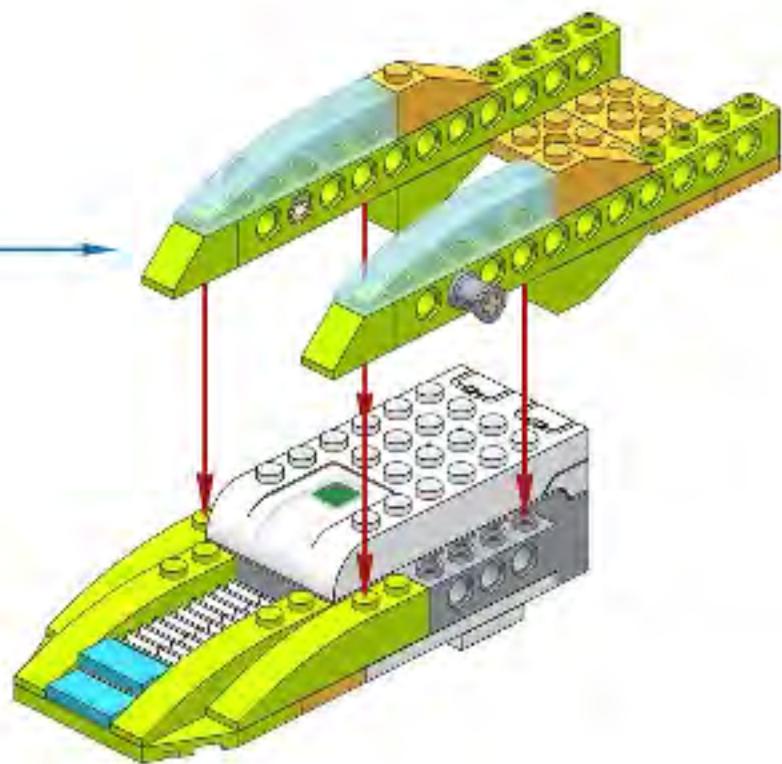
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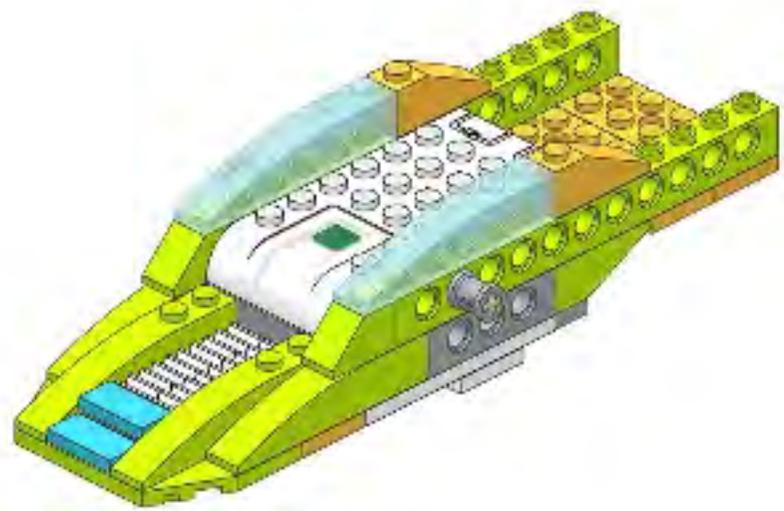
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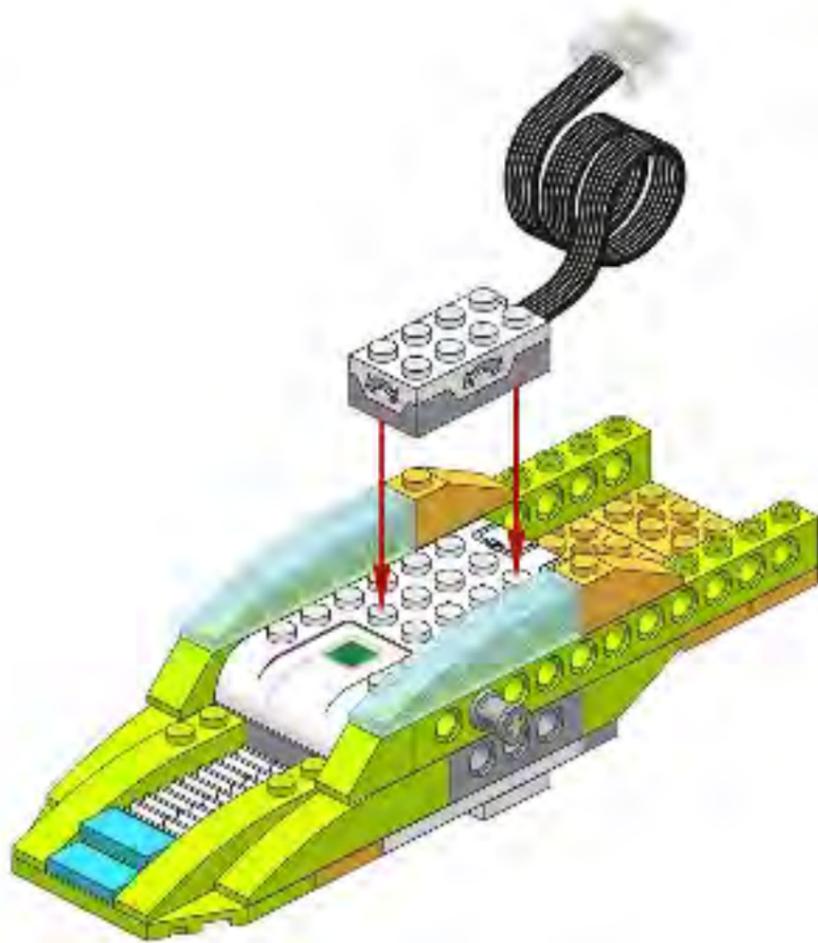


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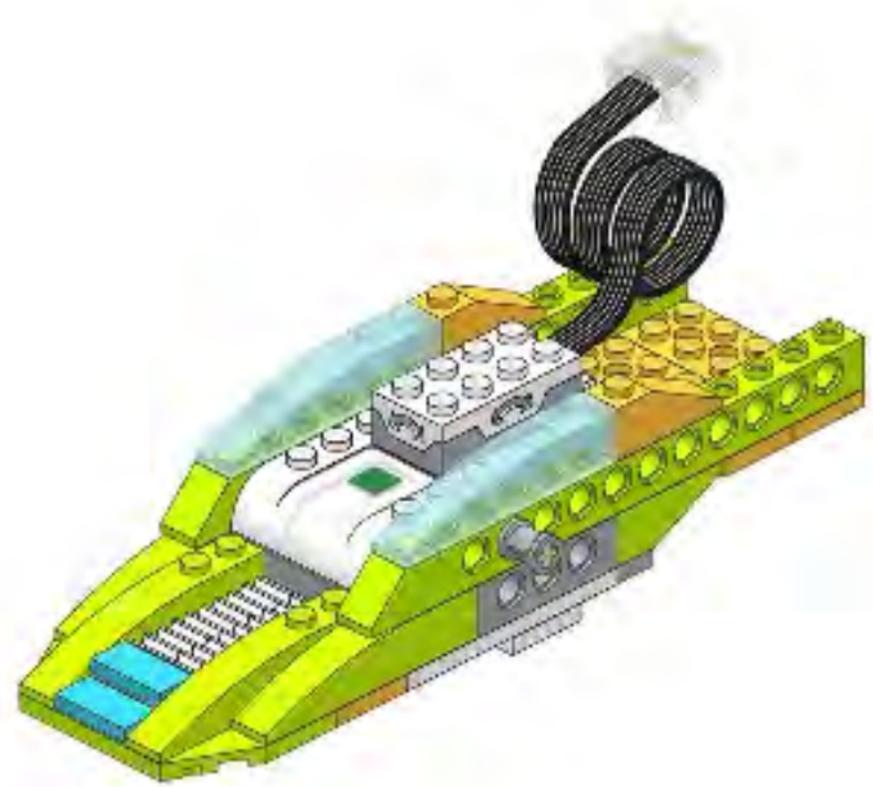




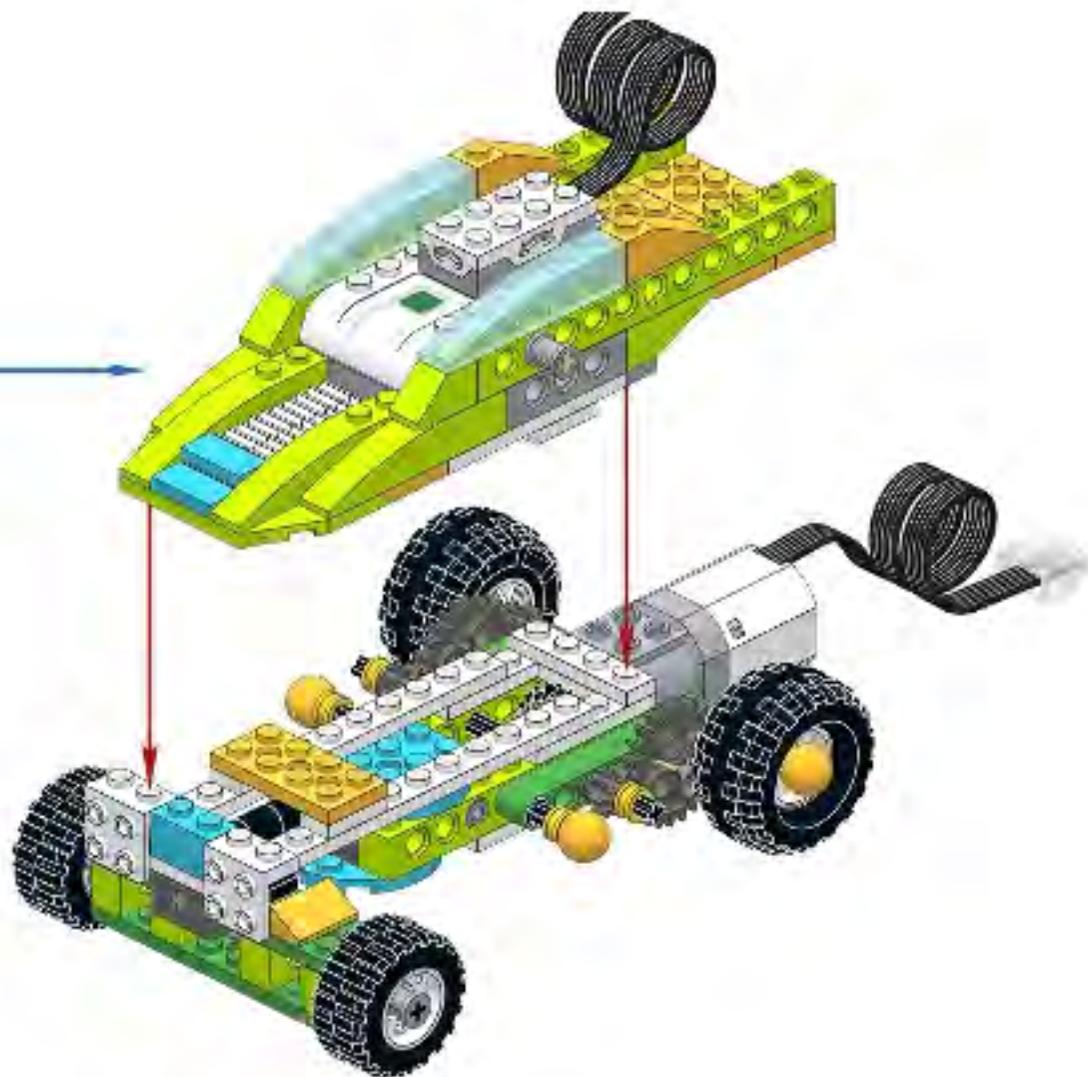
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79

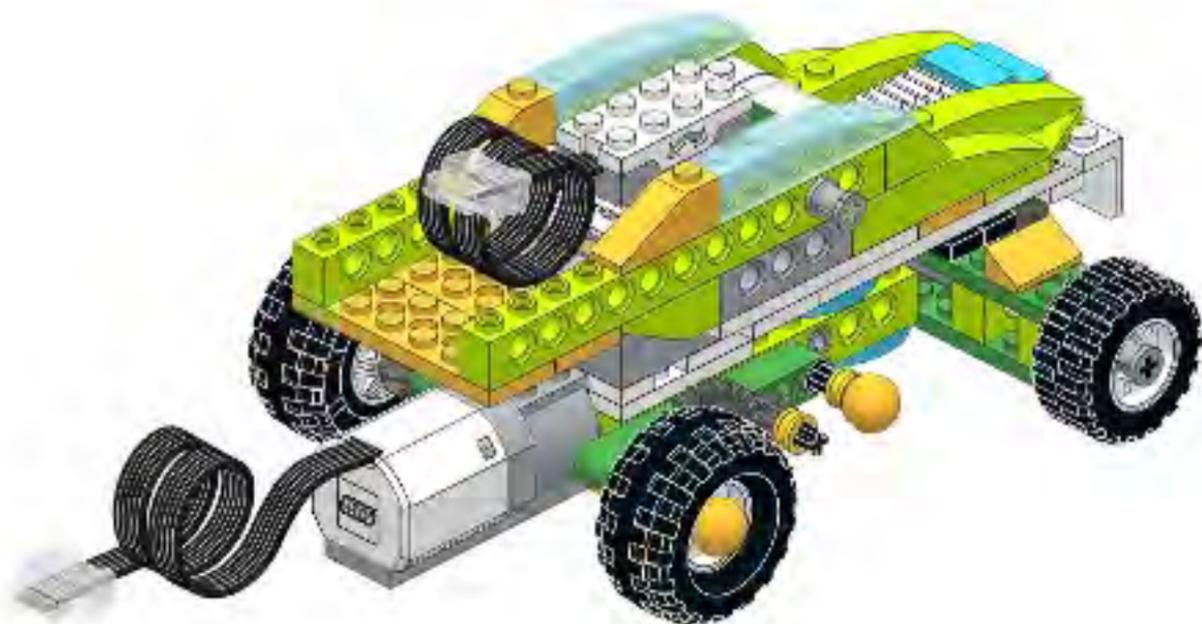


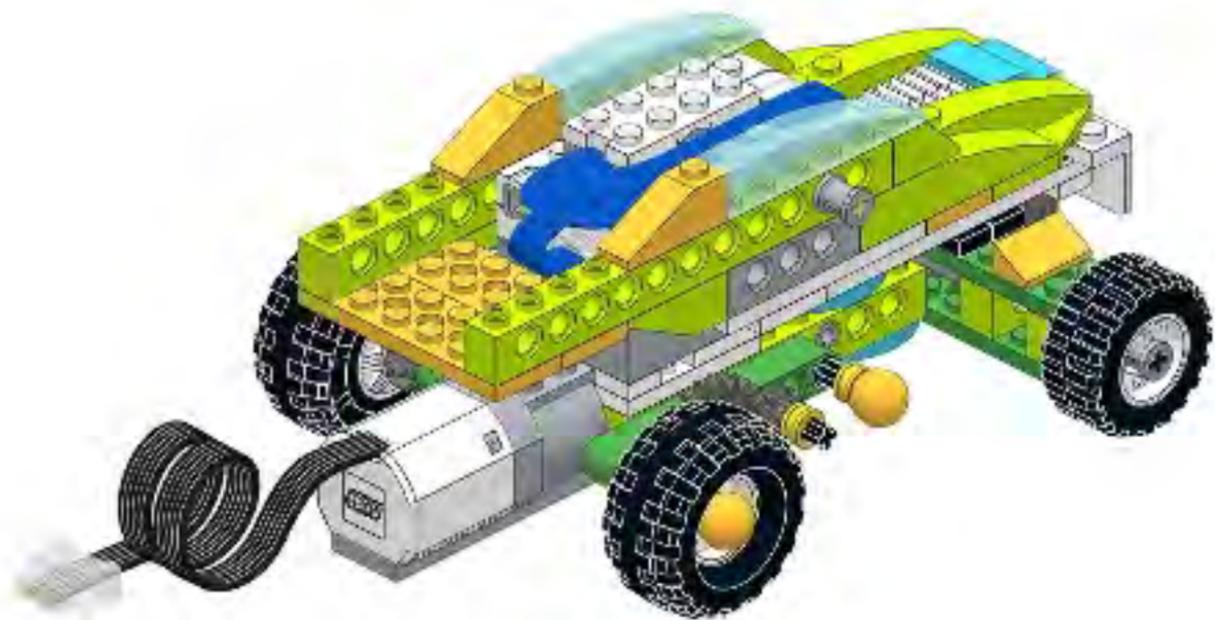
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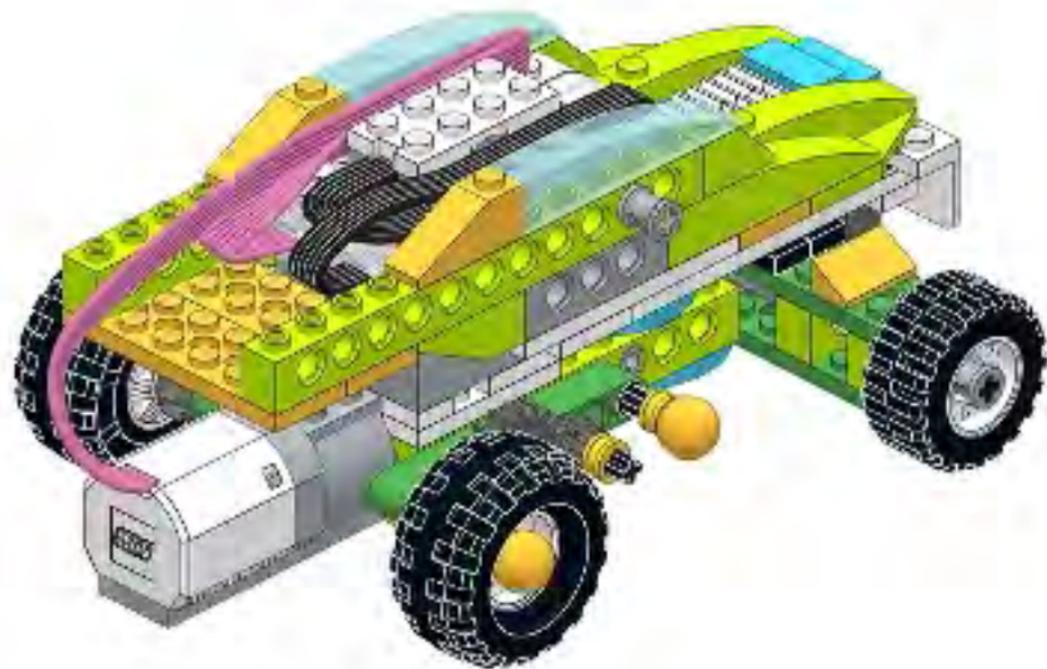


81







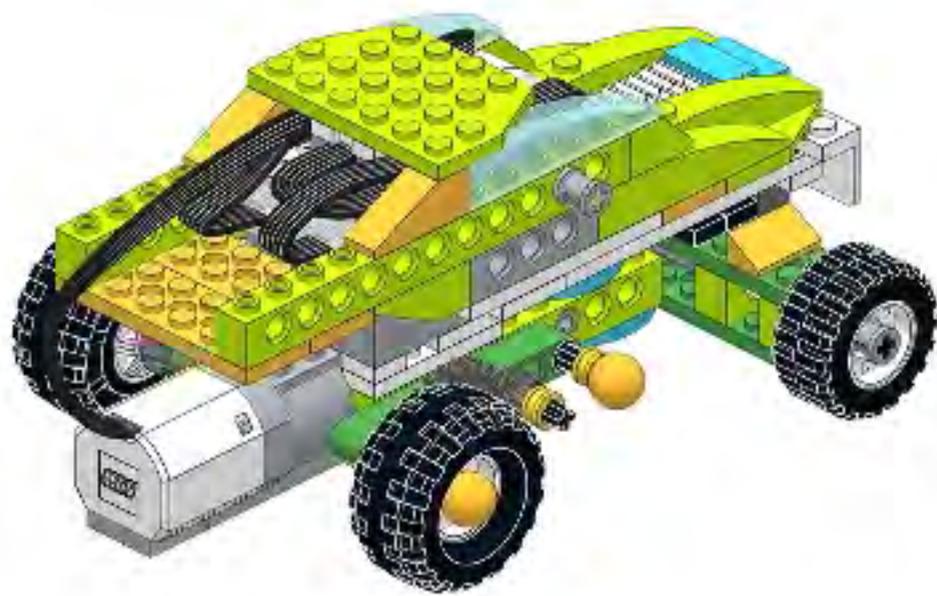




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85

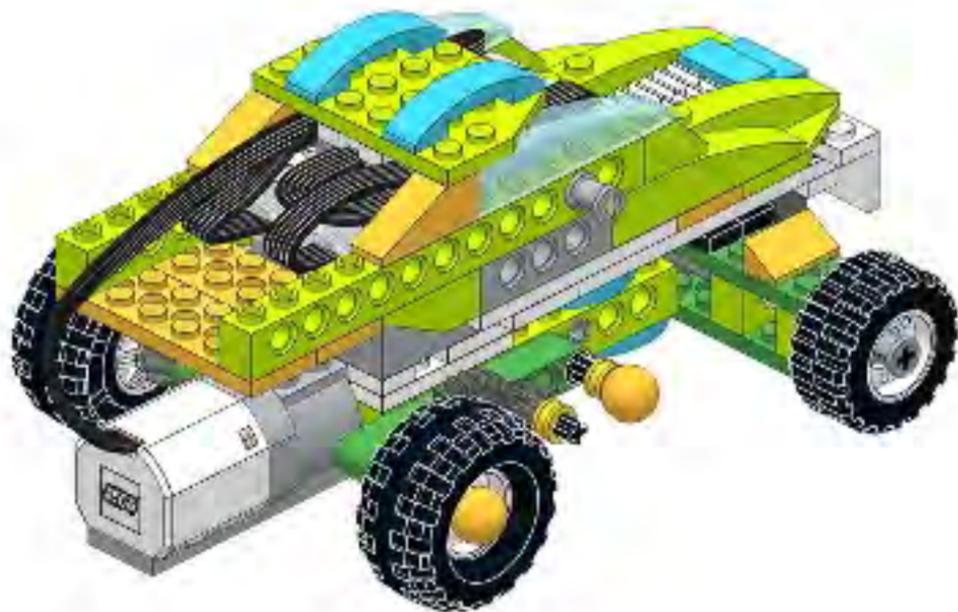






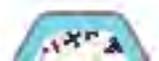
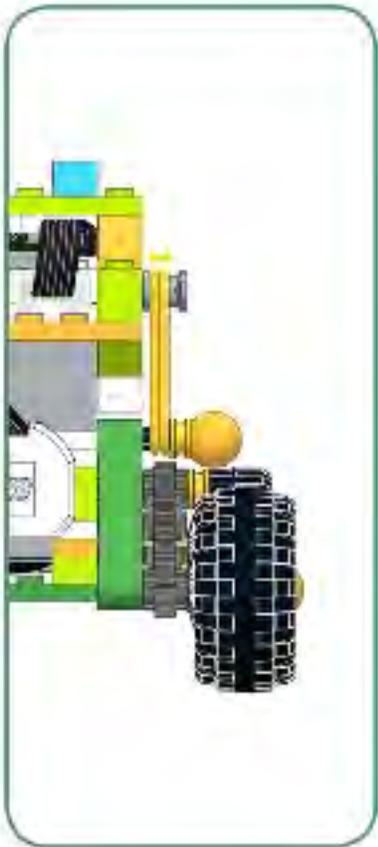
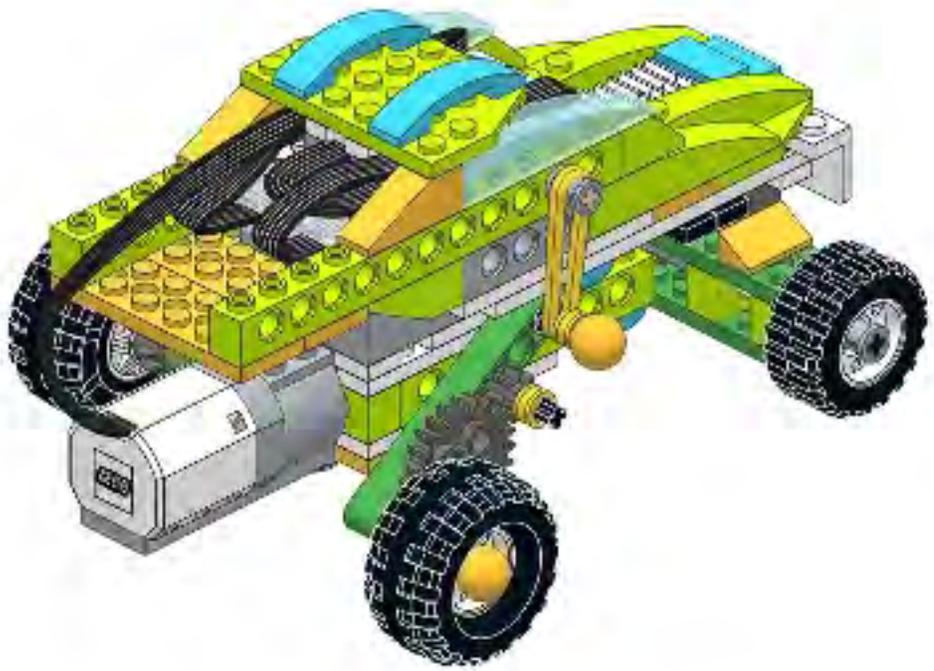
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87





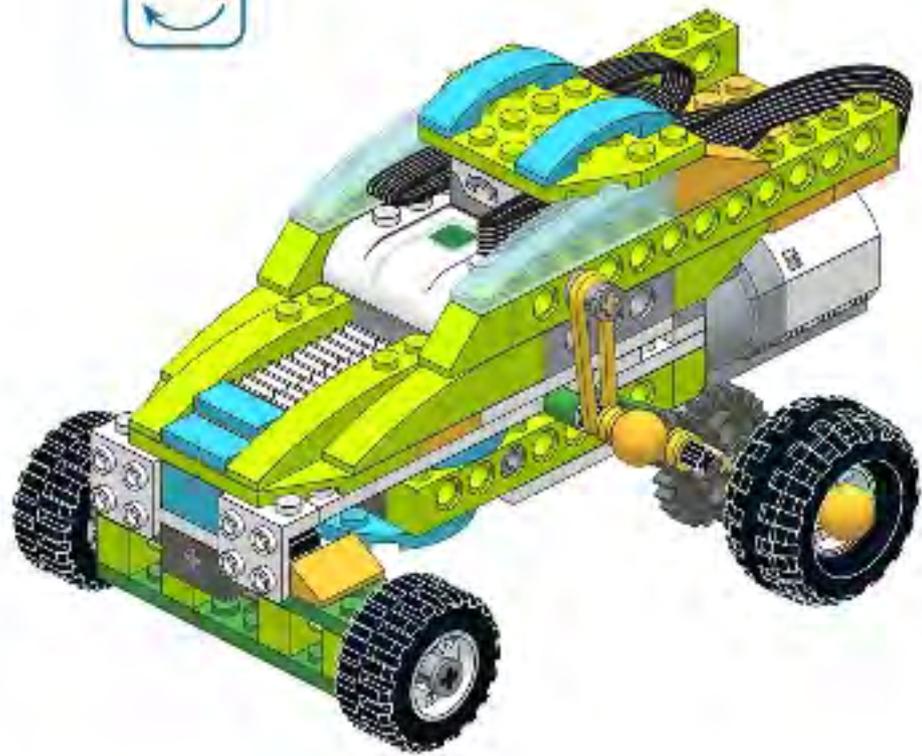
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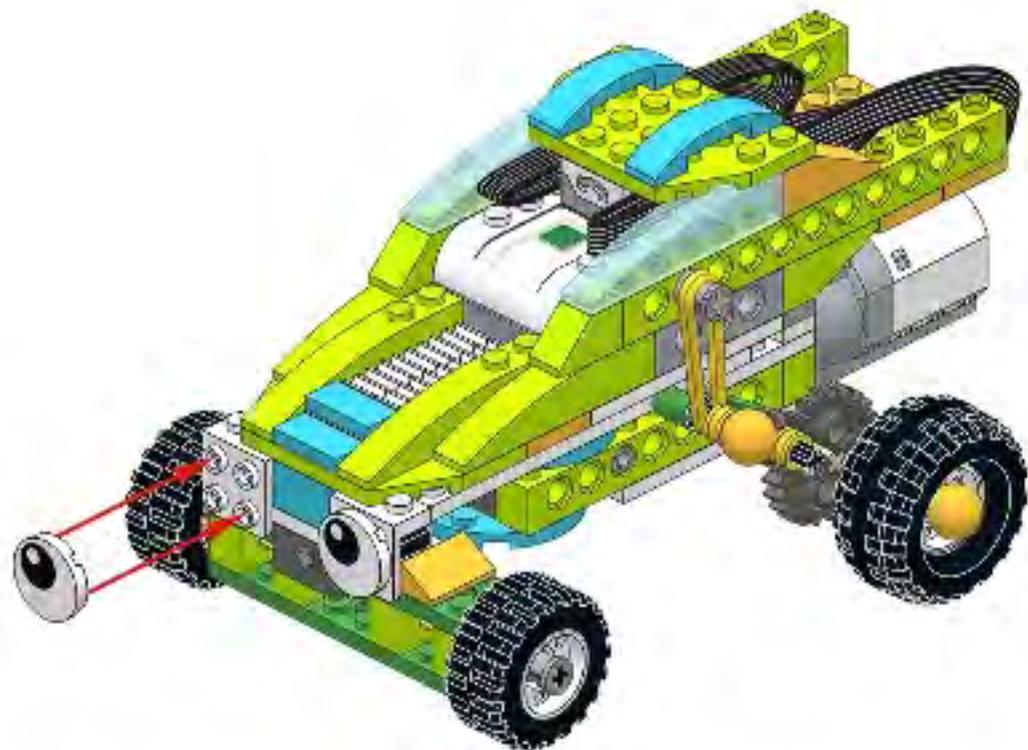


90



!





2x

92

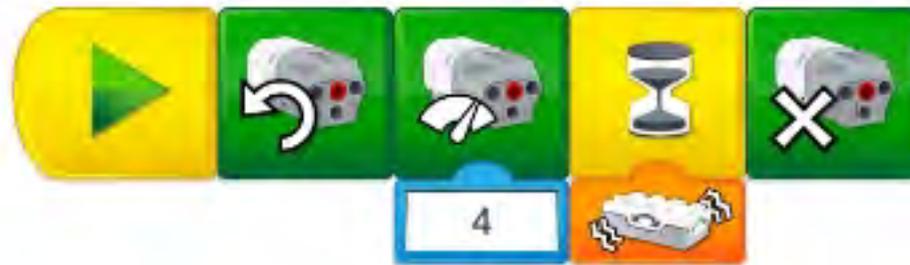
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# Task 1

Program the robot's stop when any change of sensor value is detected.





## Task 2. Program

Write a robot program for the example below.



This program constantly sends tilt sensor data



And these three programs receive messages. It works out whose name coincided with the message.



## Task 3. Program

Add the programs shown below:



The sound signal pays attention to the fact that there is a danger of the robot's rollover.



## Task 3. Questions

What program block repeats to send the datas of tilt sensor?

