

mech walker robot
unofficial building instruction

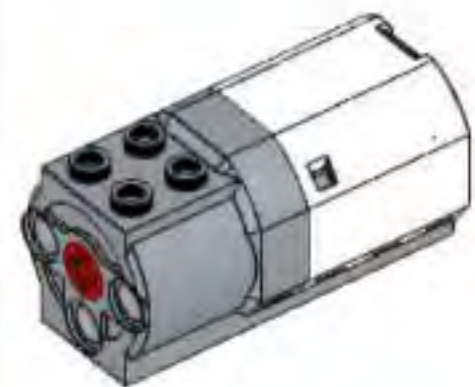


Mech Walker

for Lego® WeDo 2.0
45300



1x



1x



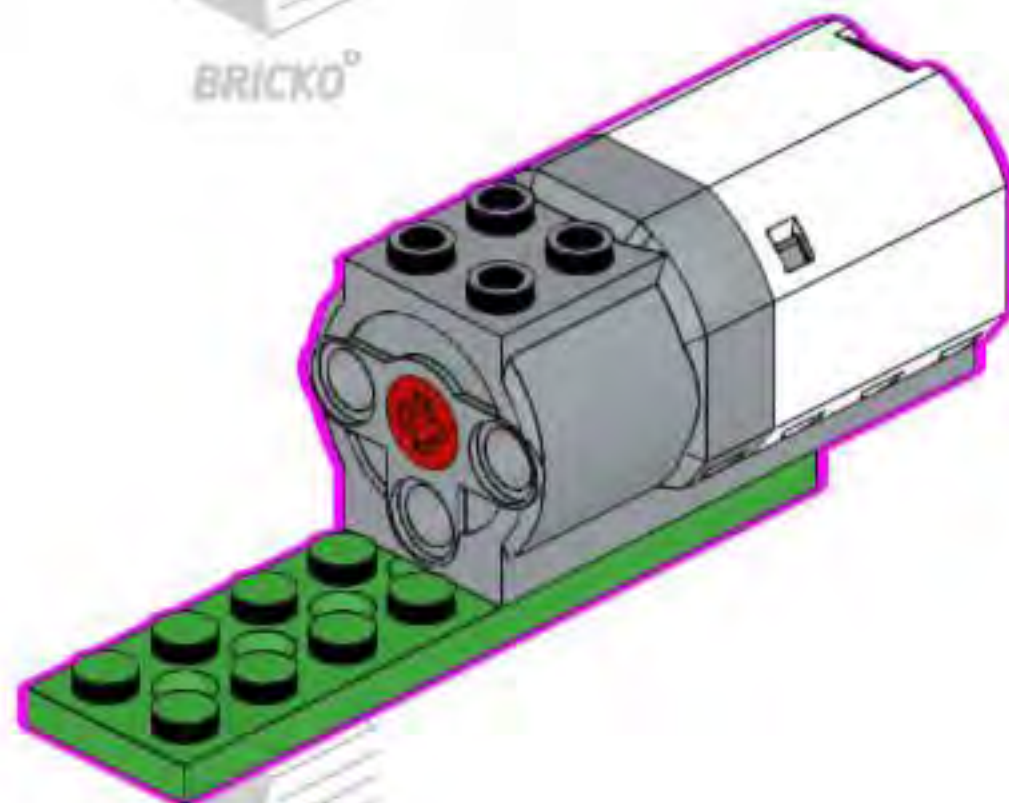
BRICKO[®]



BRICKO[®]



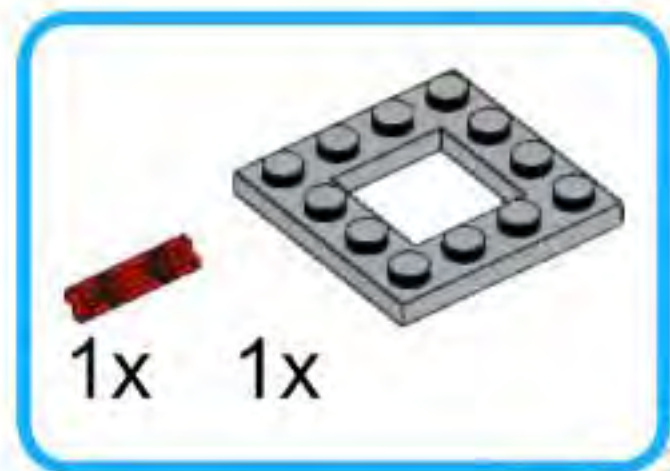
BRICKO[®]



BRICKO[®]



BRICKO[®]



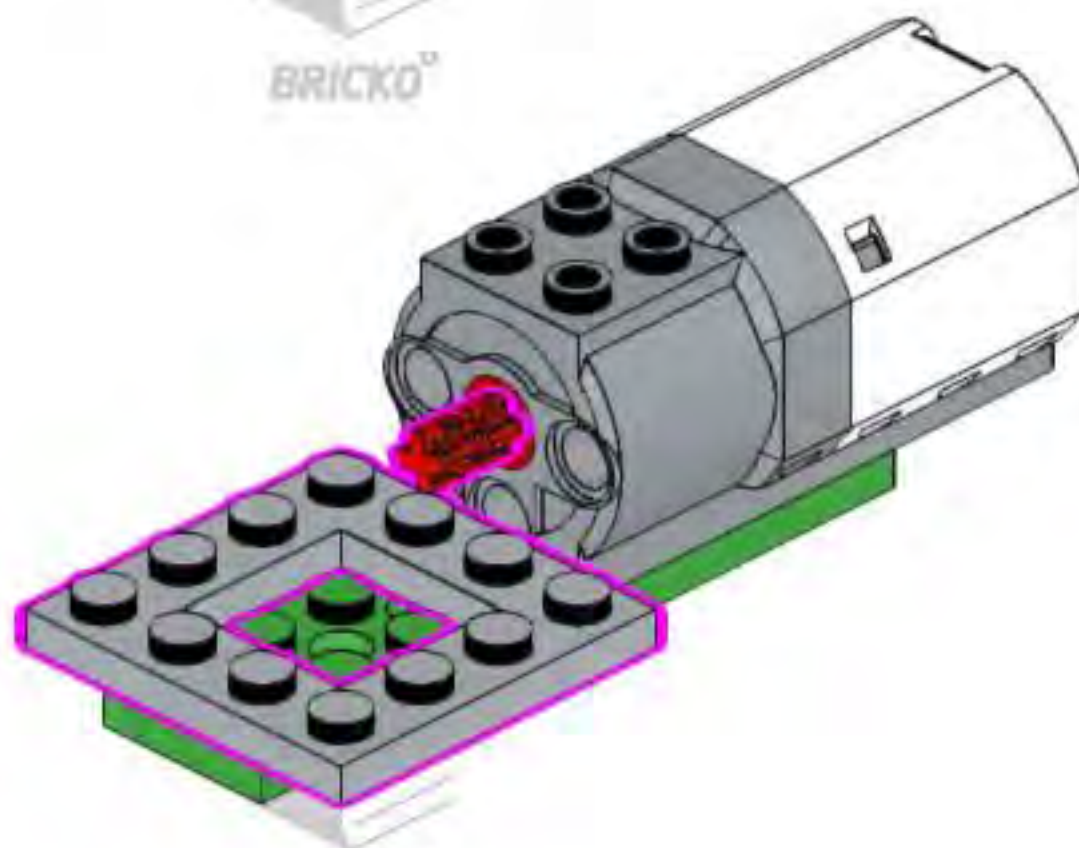
BRICKO[®]



BRICKO[®]



BRICKO[®]

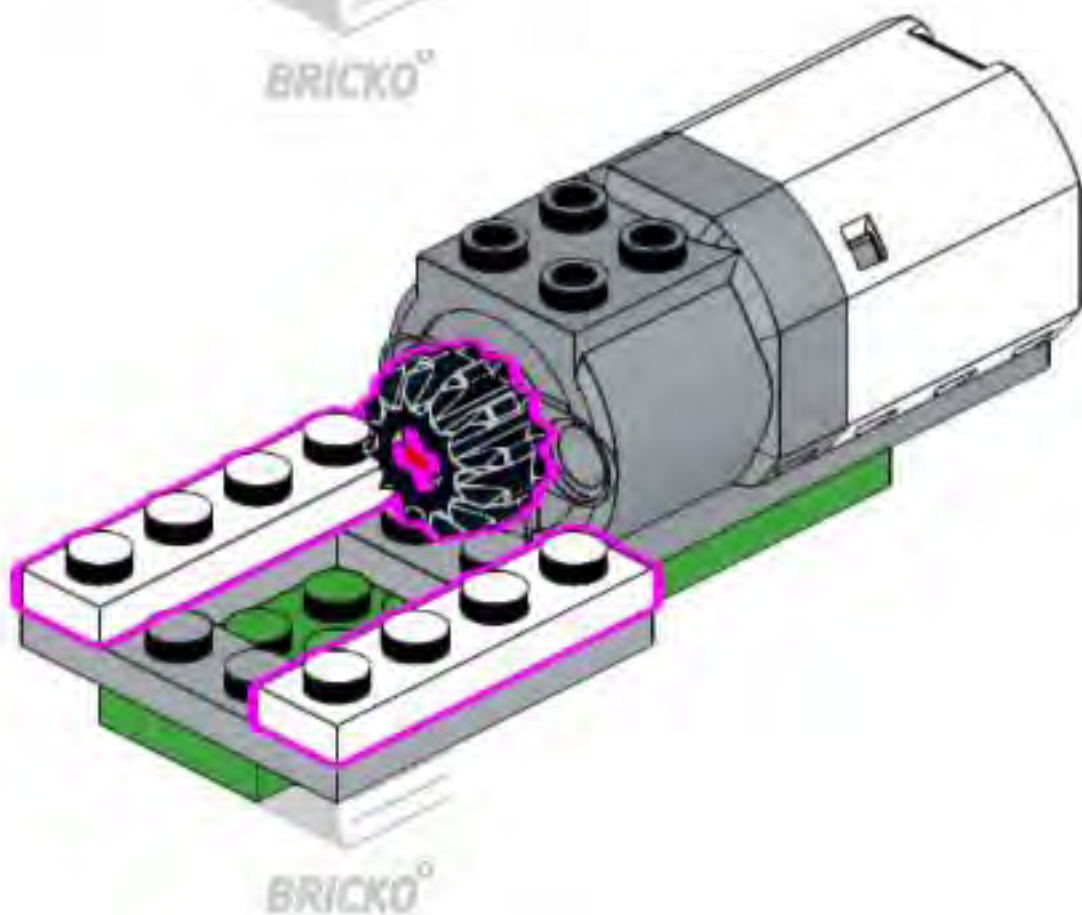
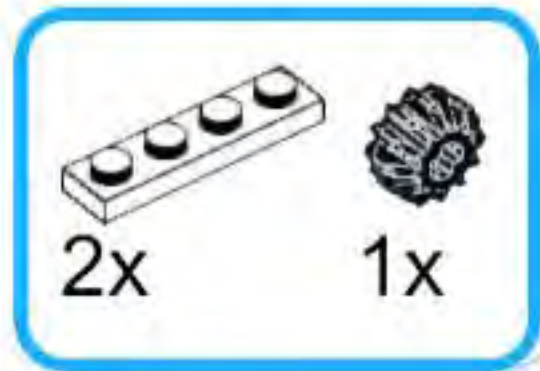


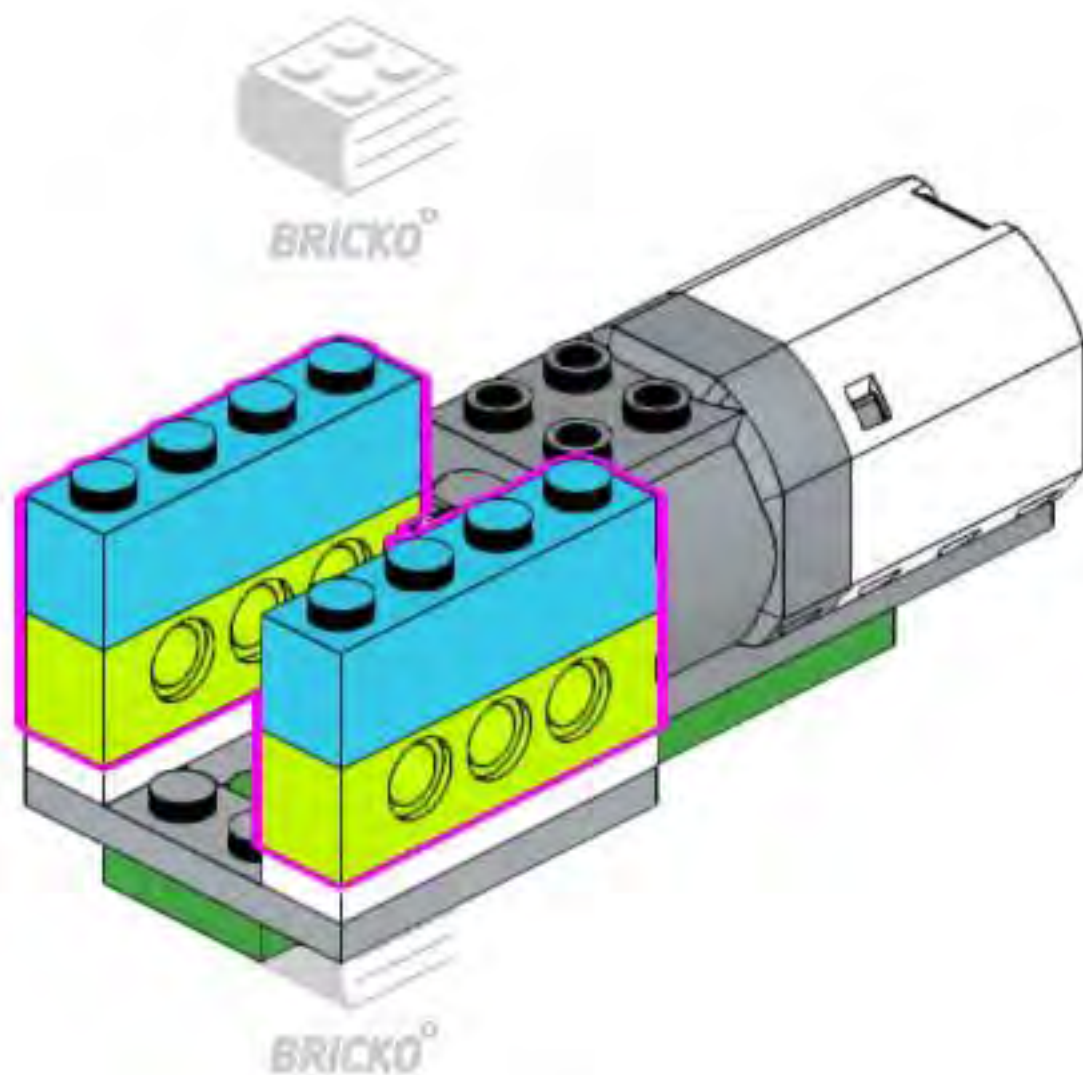
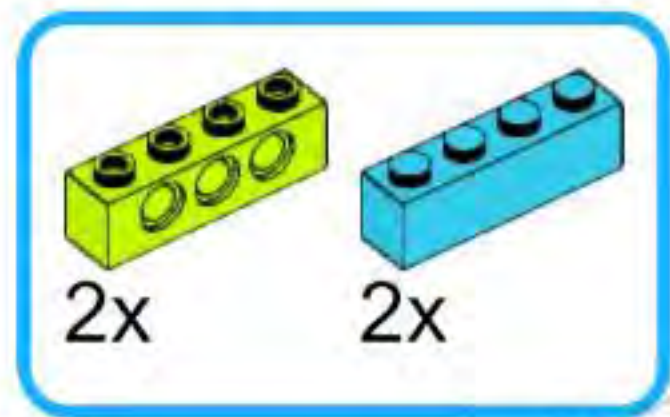
BRICKO[®]

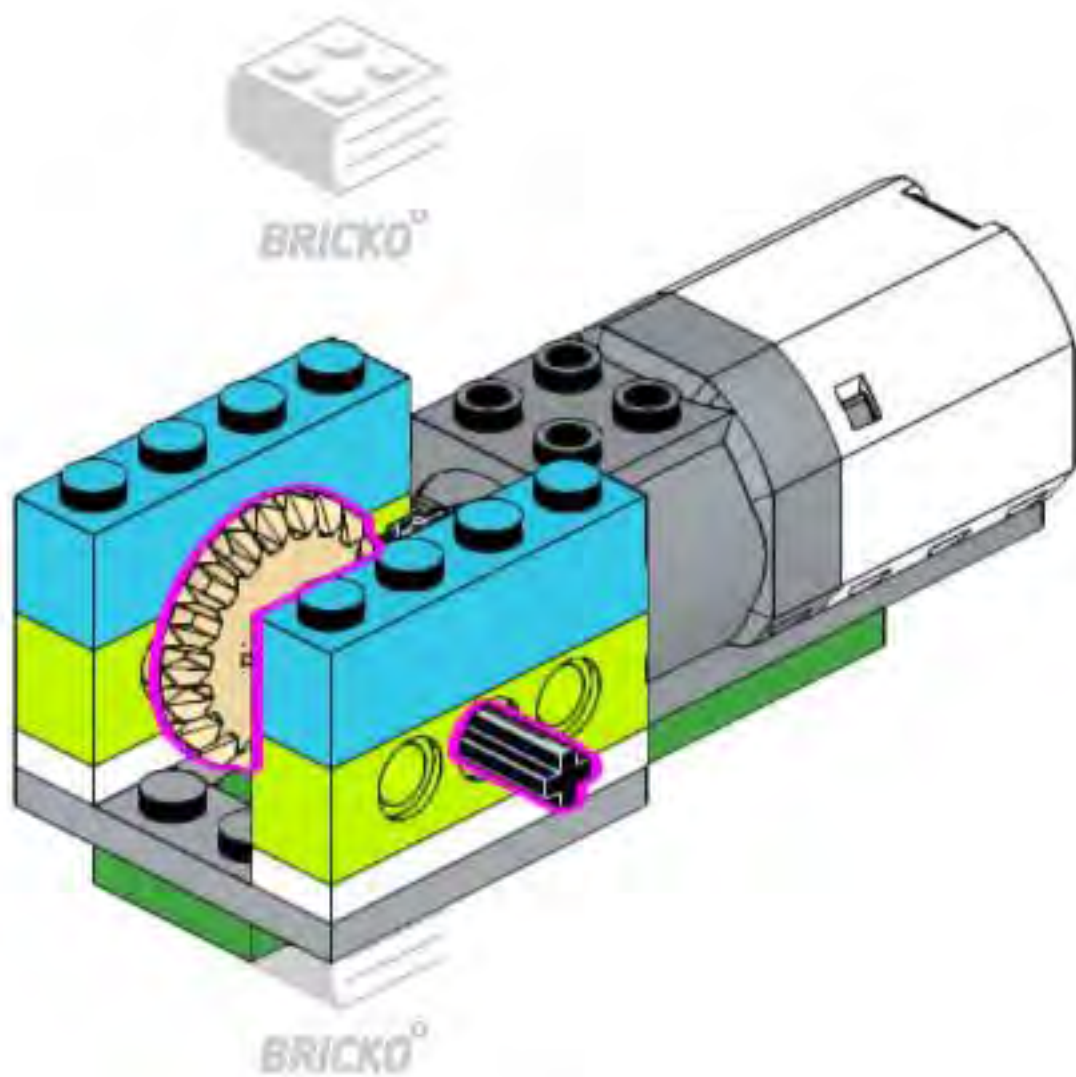
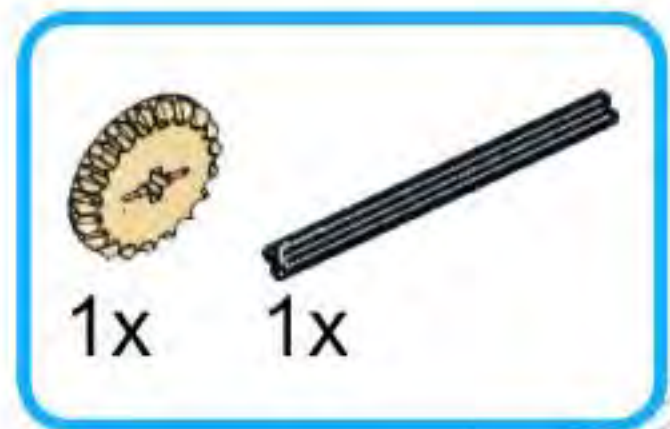
BRICKO[®]

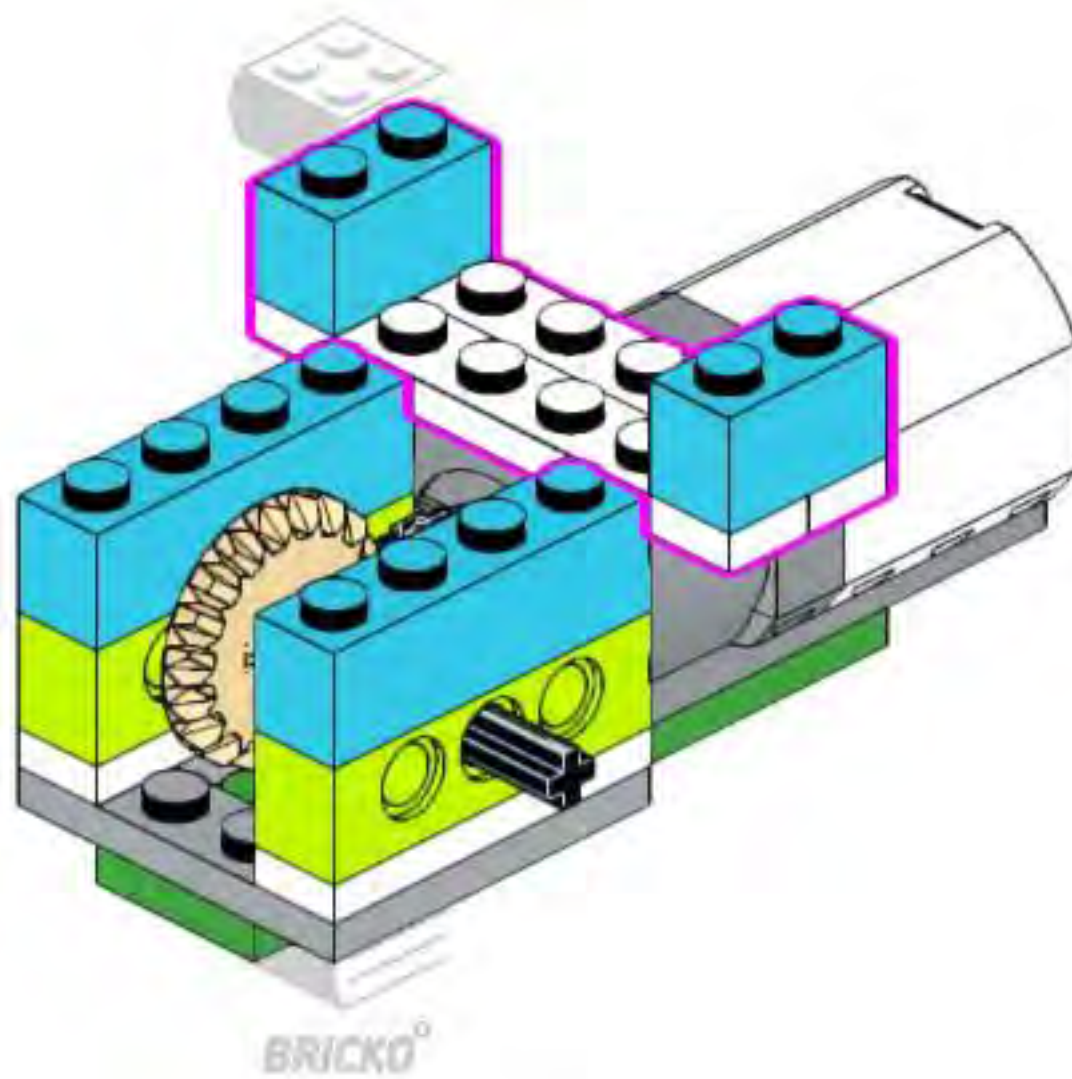
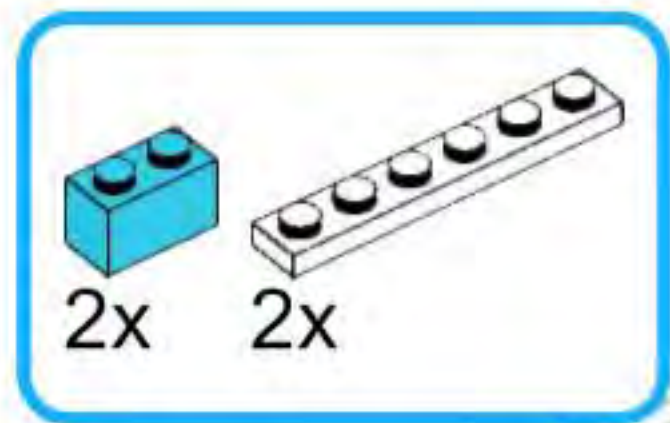


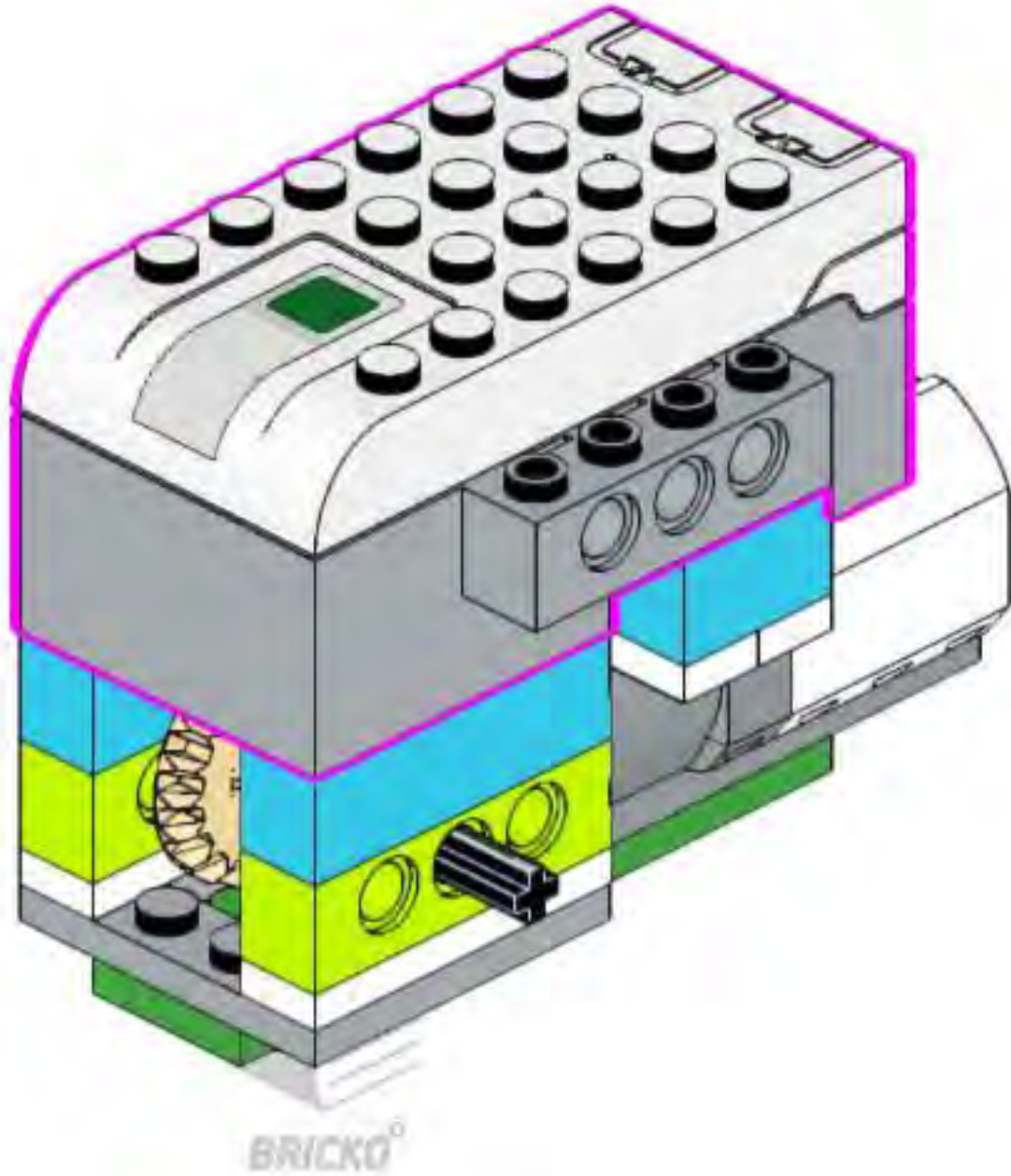
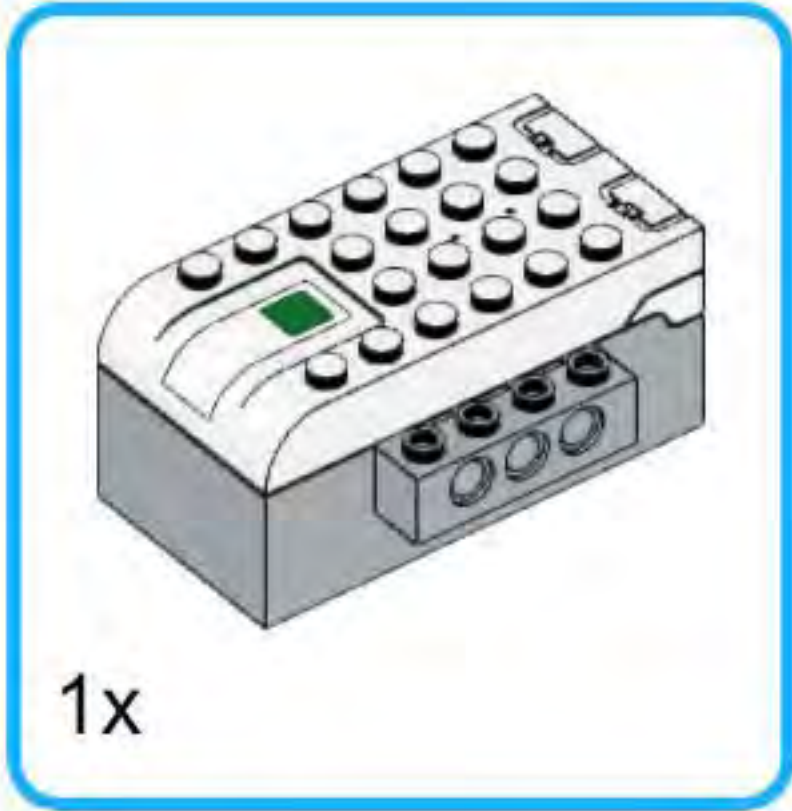
BRICKO[®]

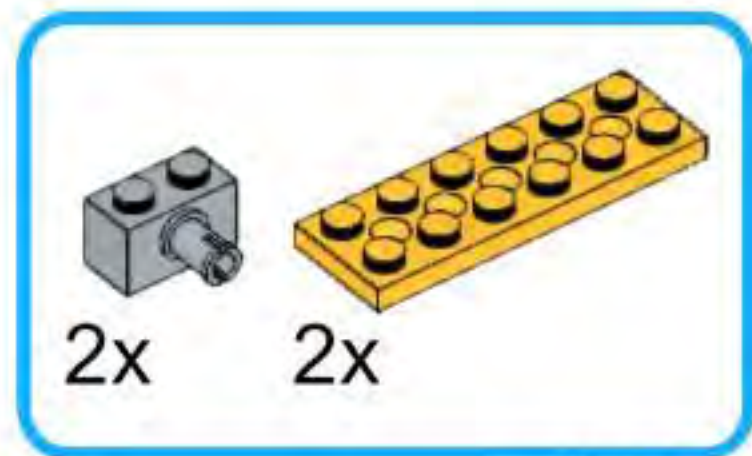








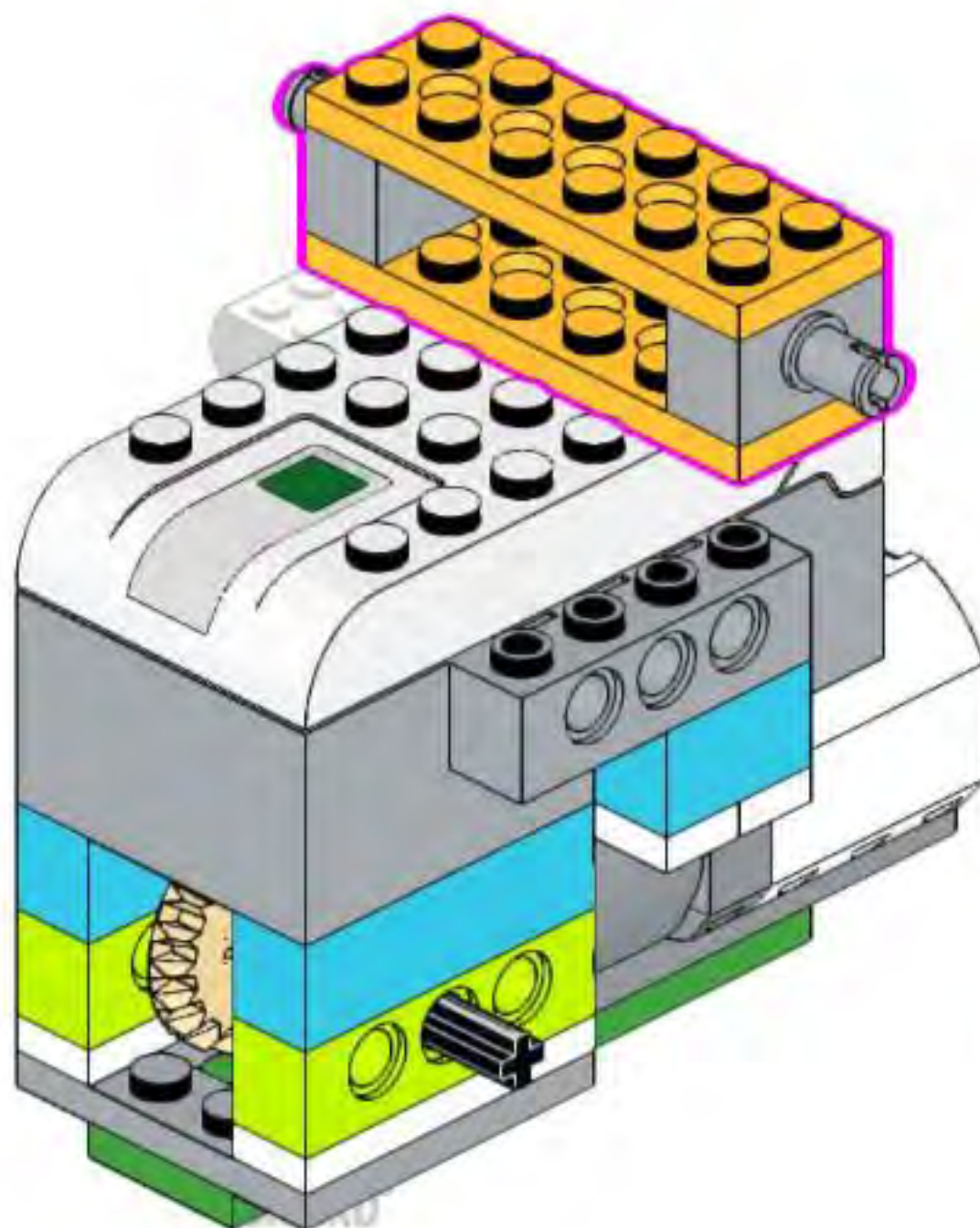




BRICKO[®]



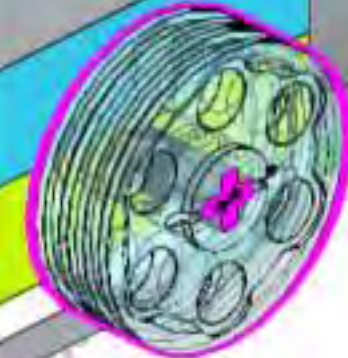
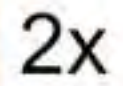
BRICKO[®]

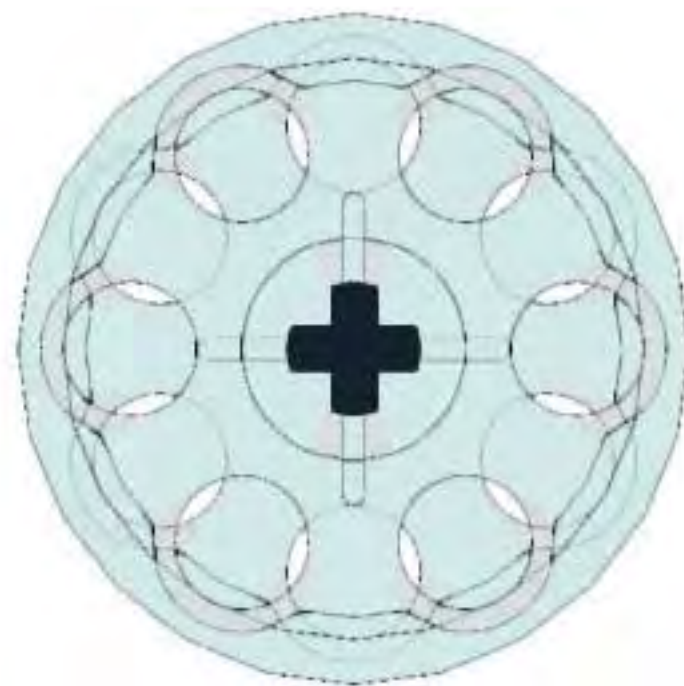
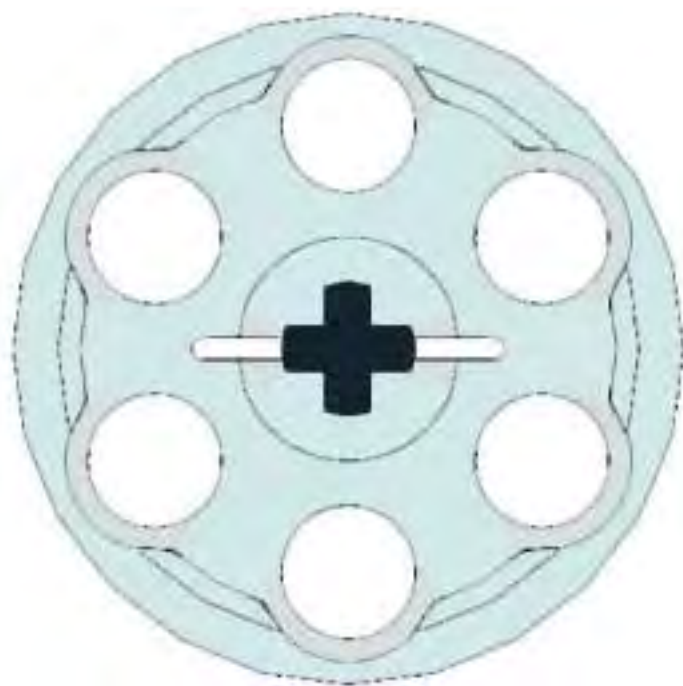


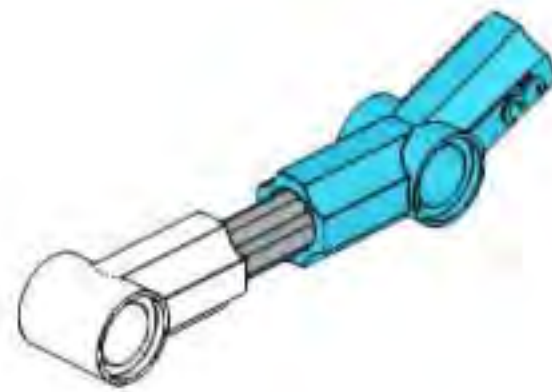
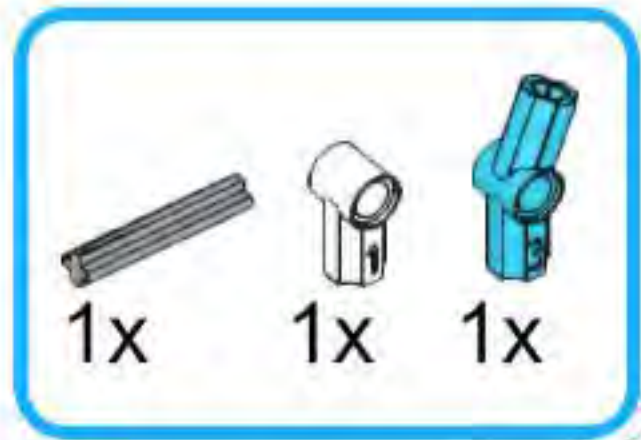
BRICKO[®]

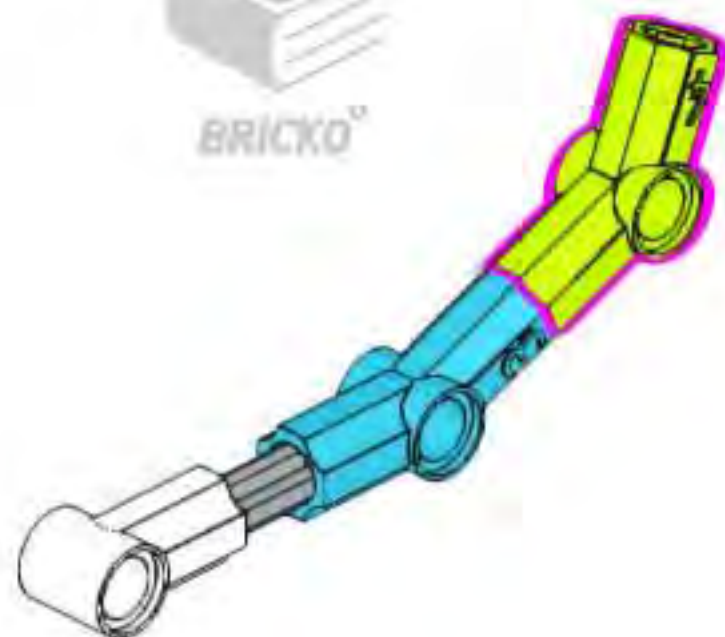


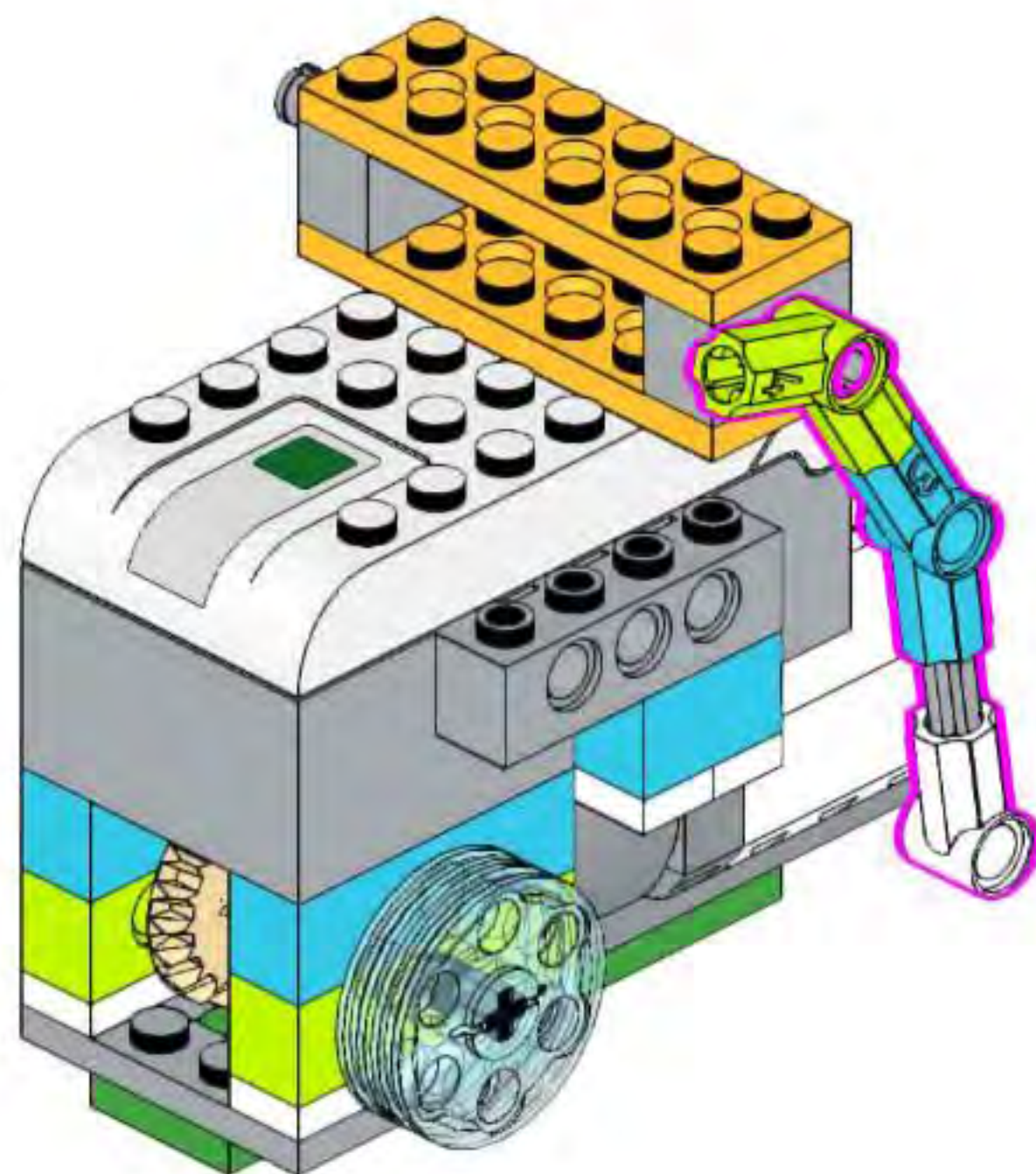
BRICKO[®]

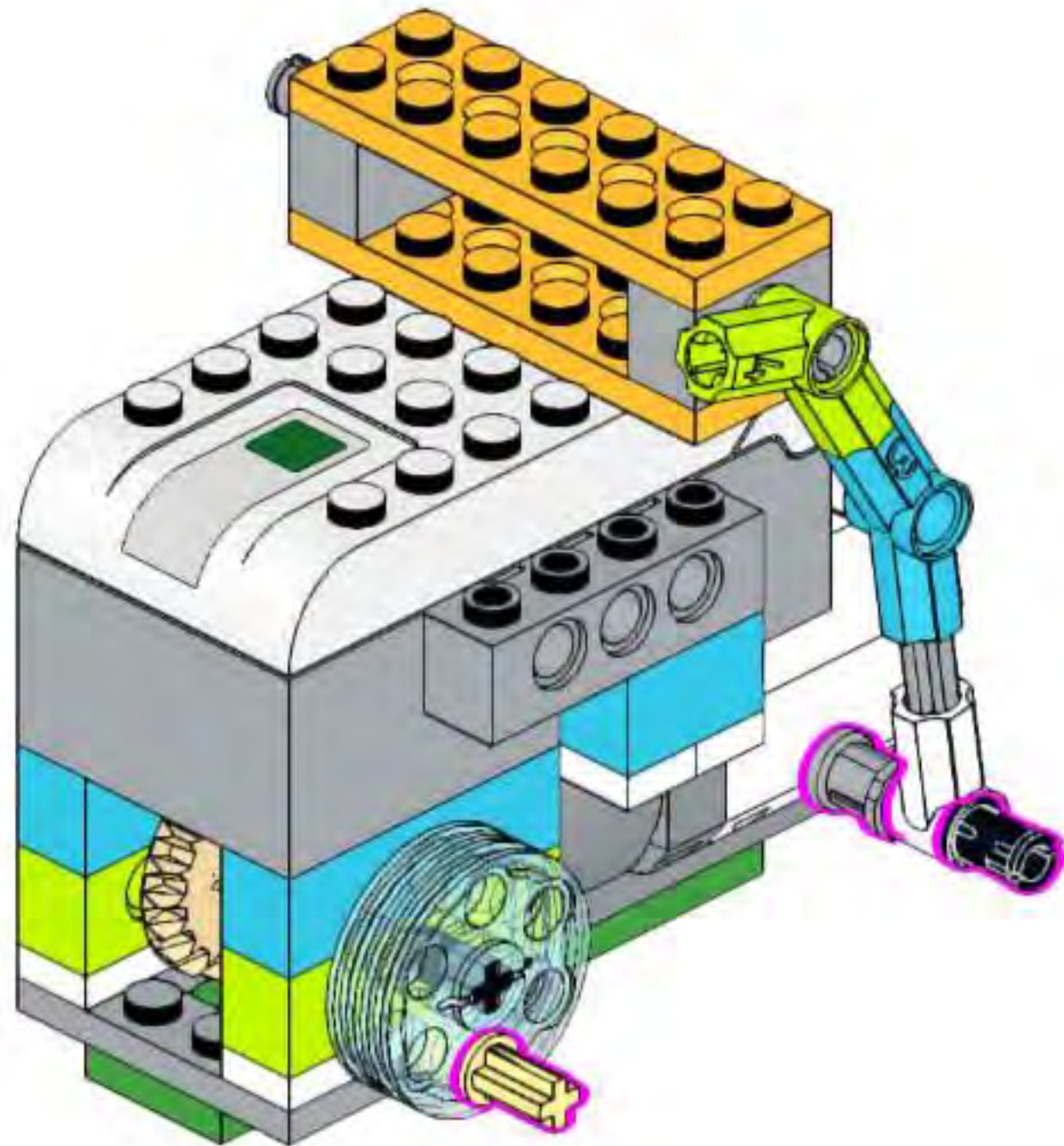
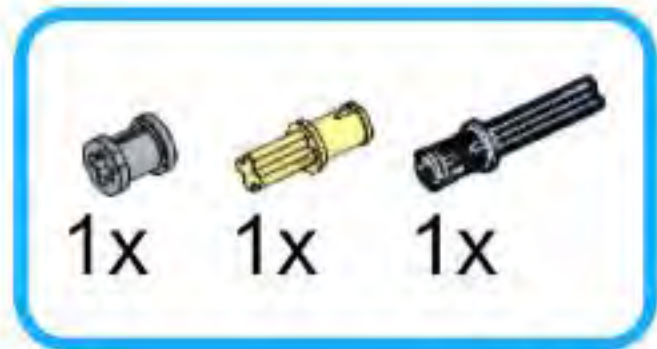


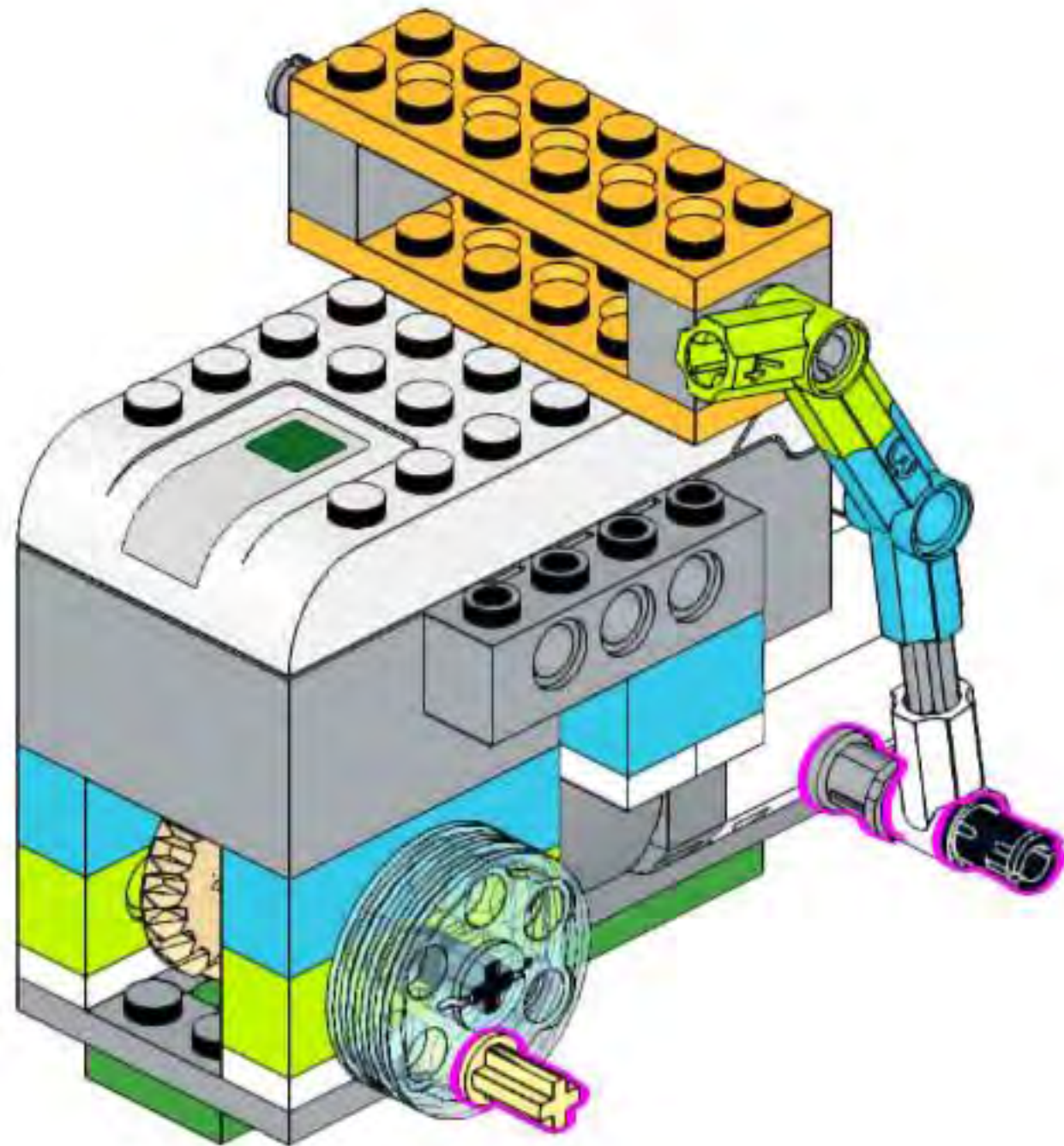
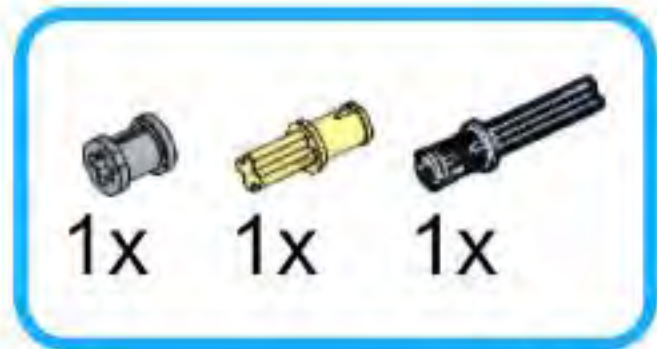


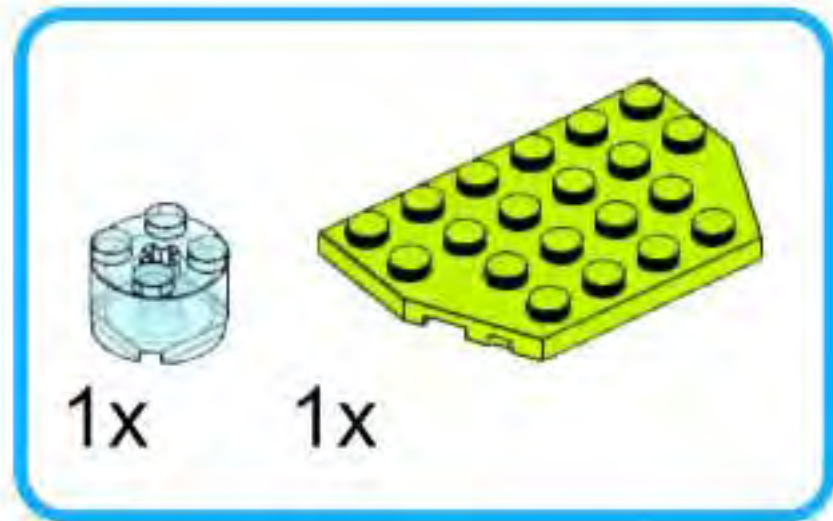












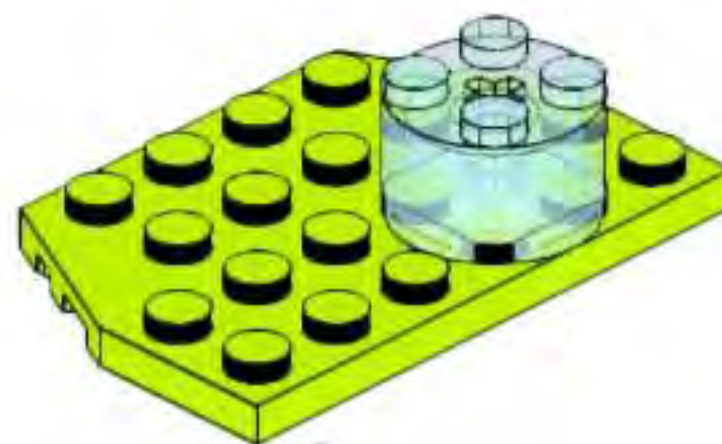
BRICKO[®]



BRICKO[®]



BRICKO[®]



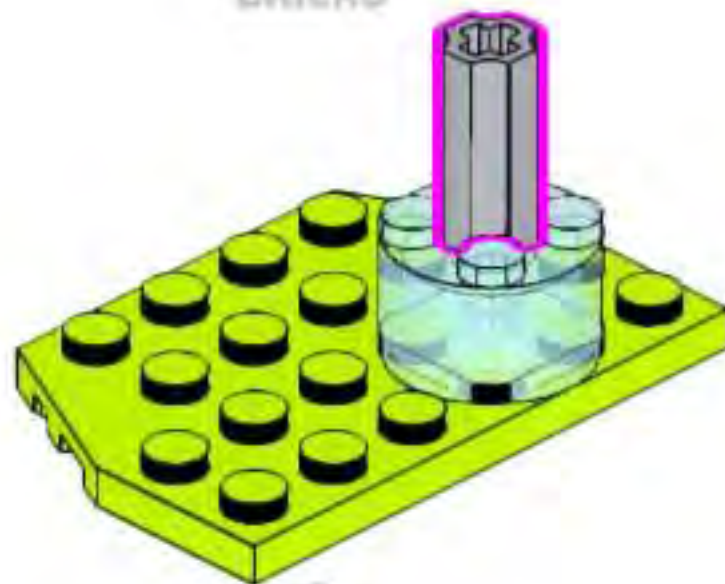
BRICKO[®]

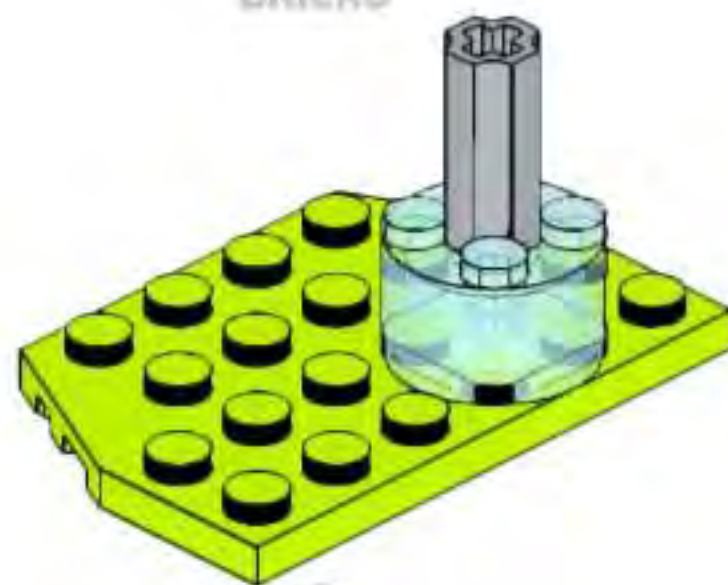


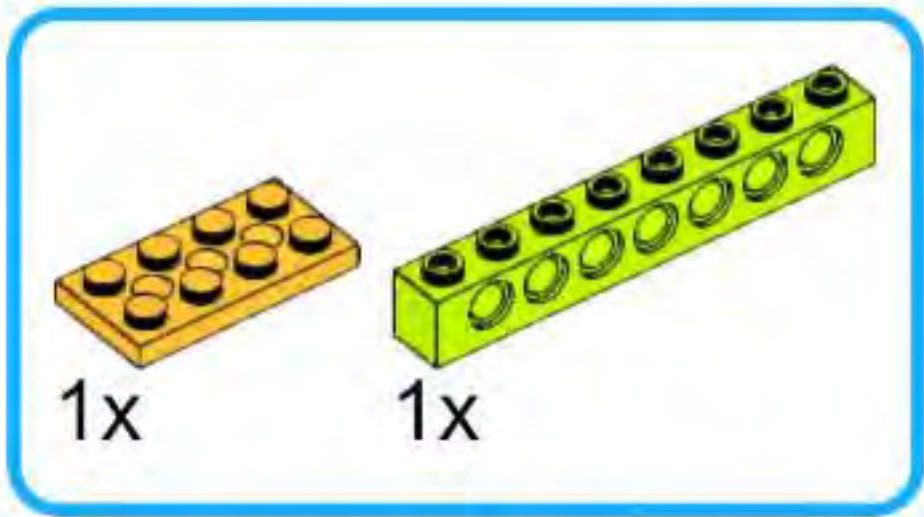
BRICKO[®]



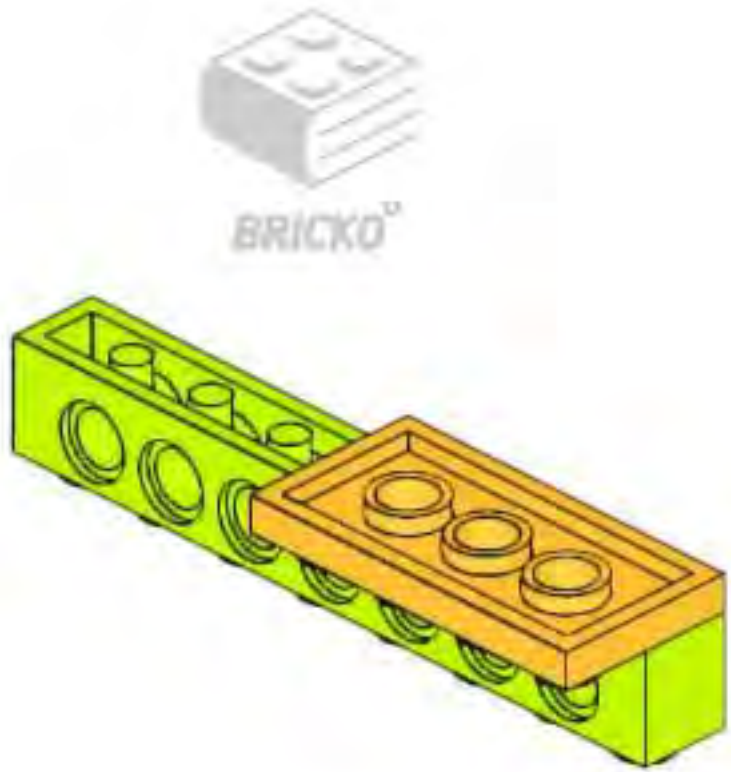
BRICKO[®]







BRICKO[®]



BRICKO[®]

BRICKO[®]



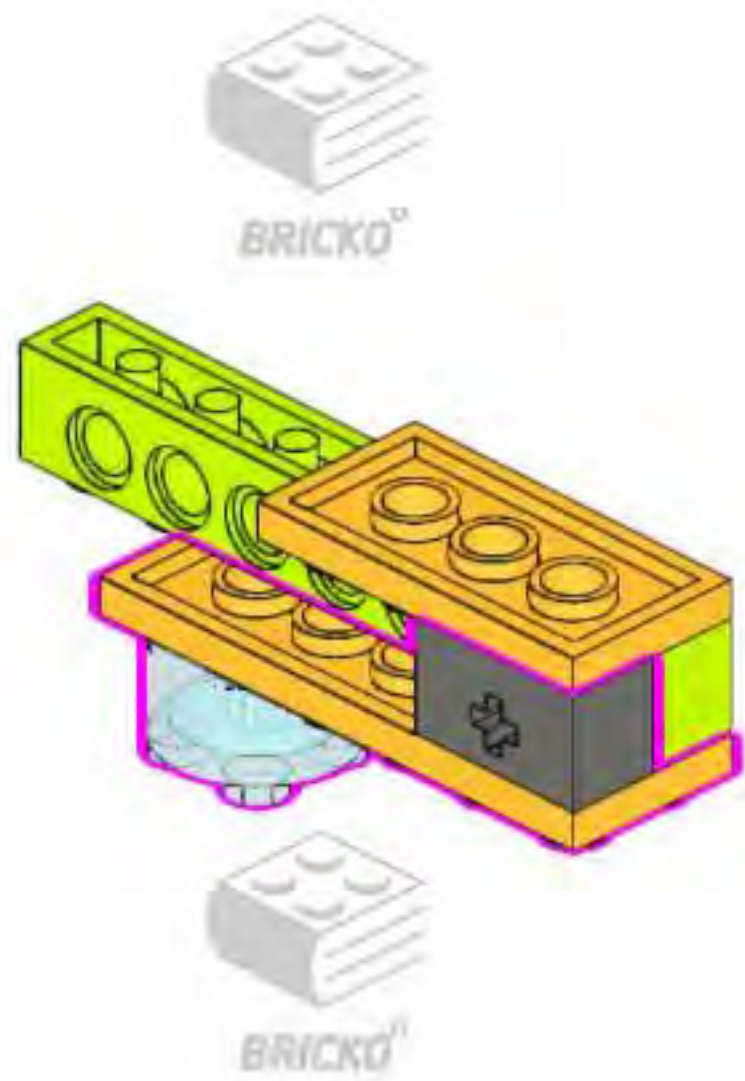
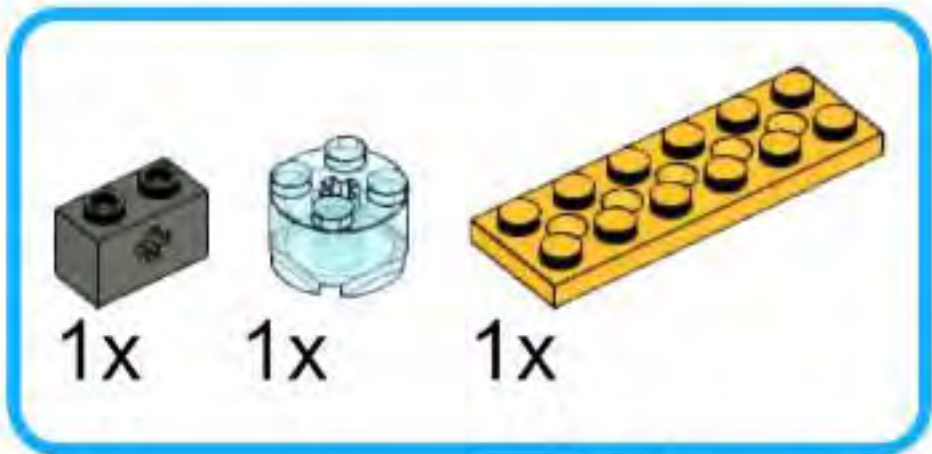
BRICKO[®]

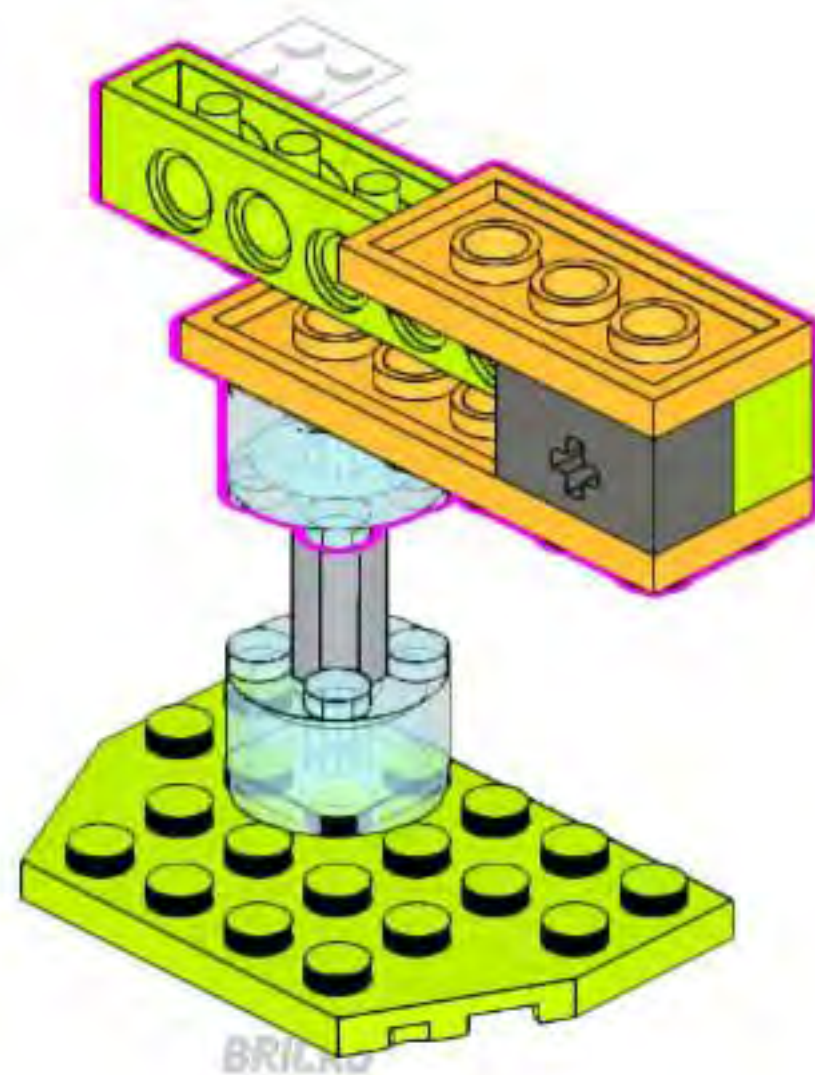


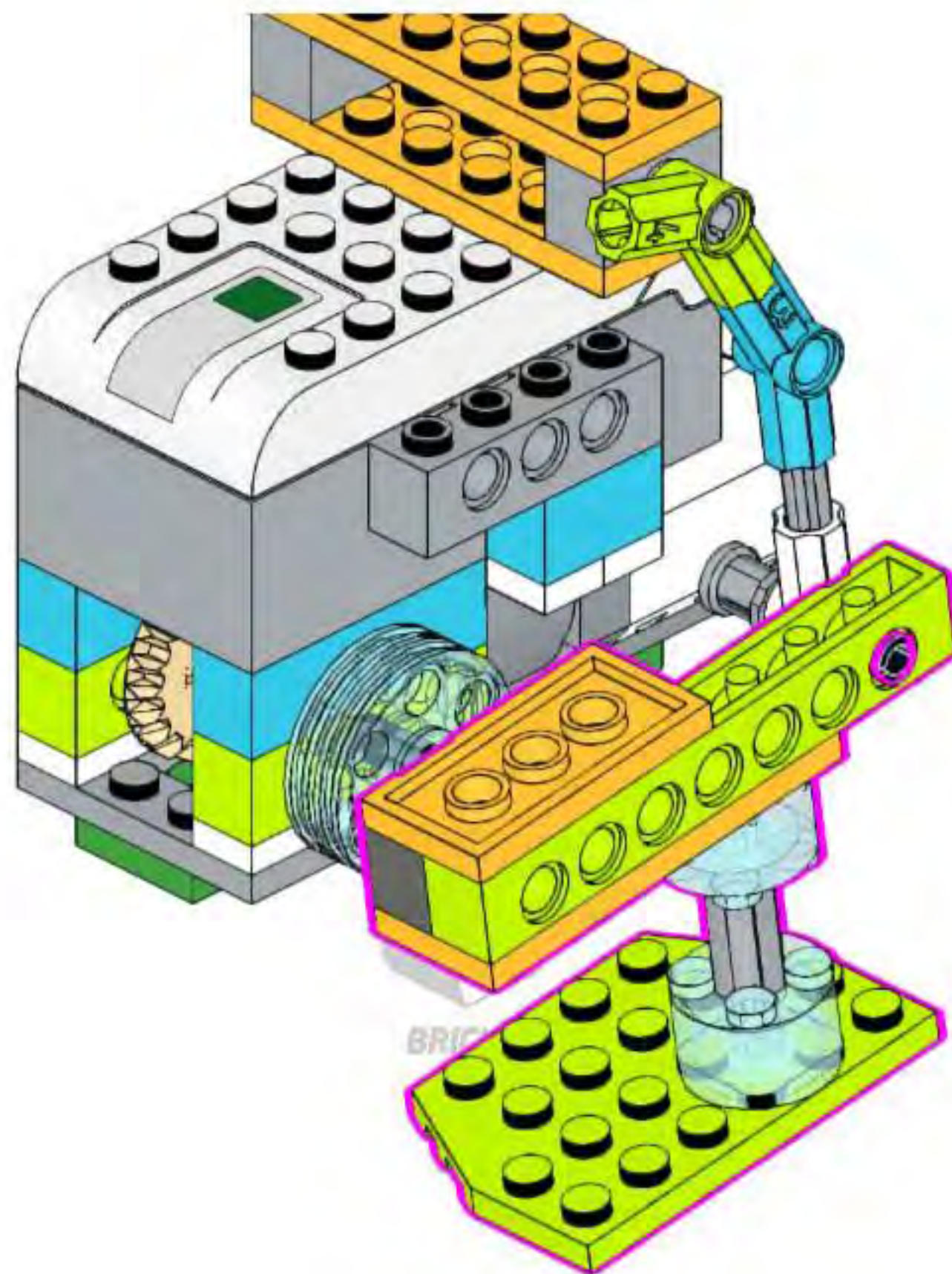
BRICKO[®]

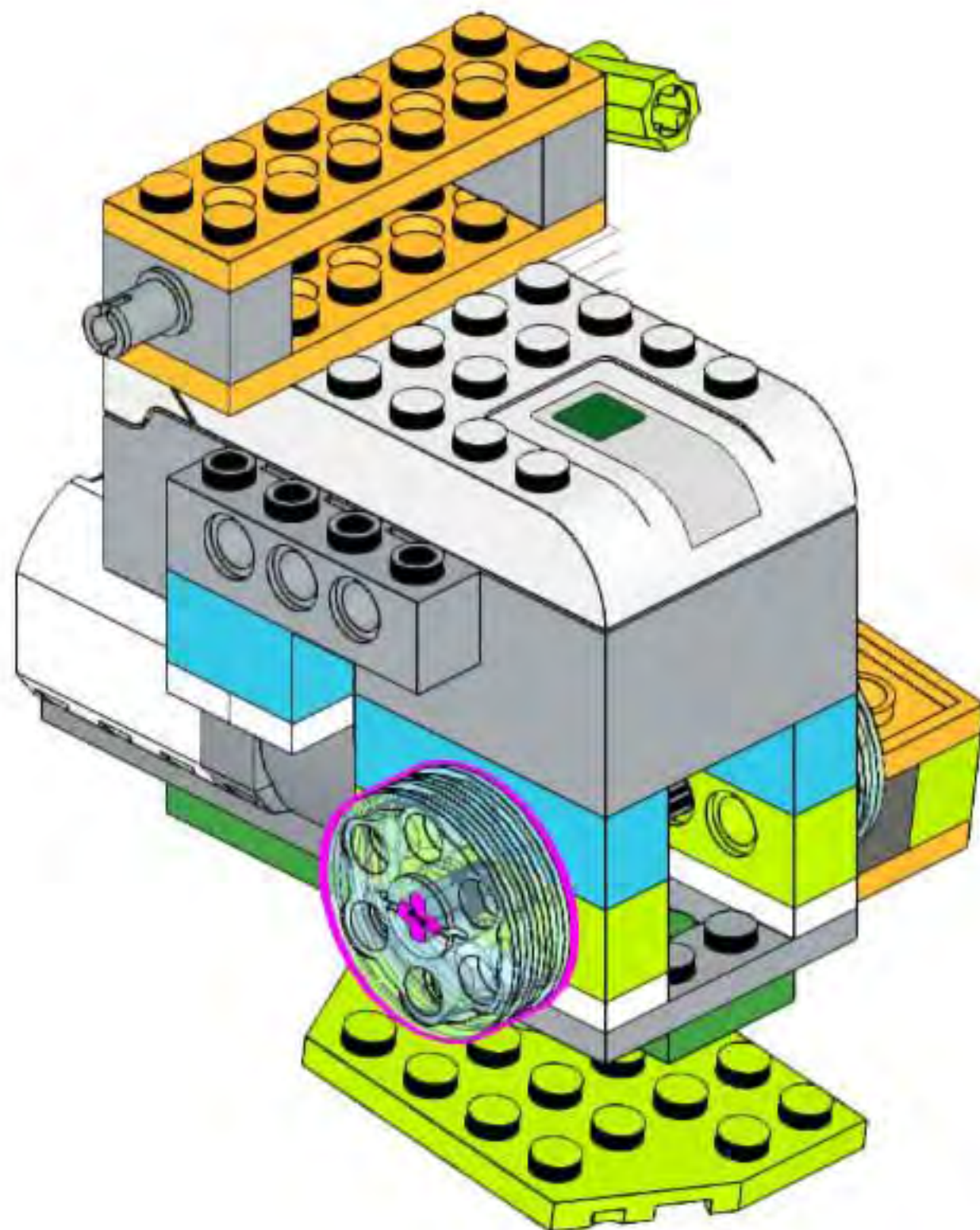


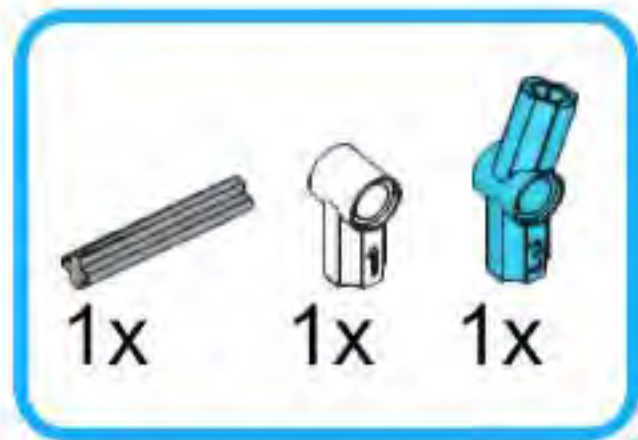
BRICKO[®]

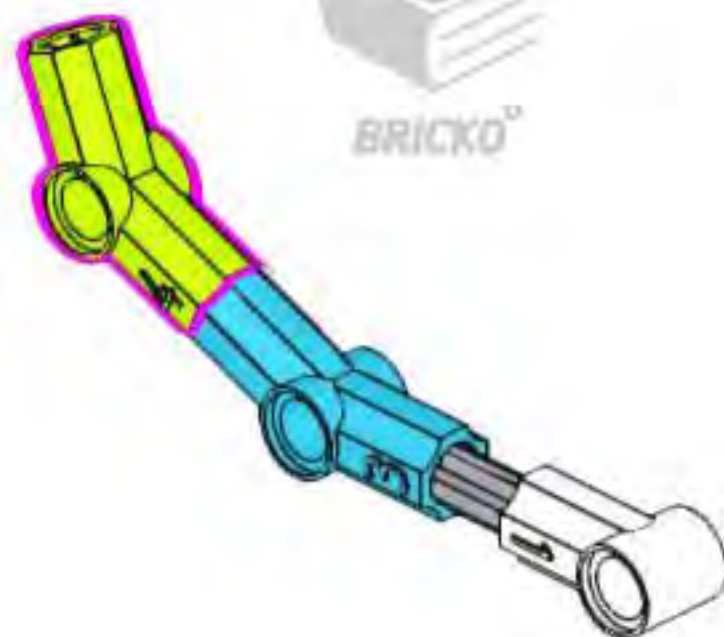


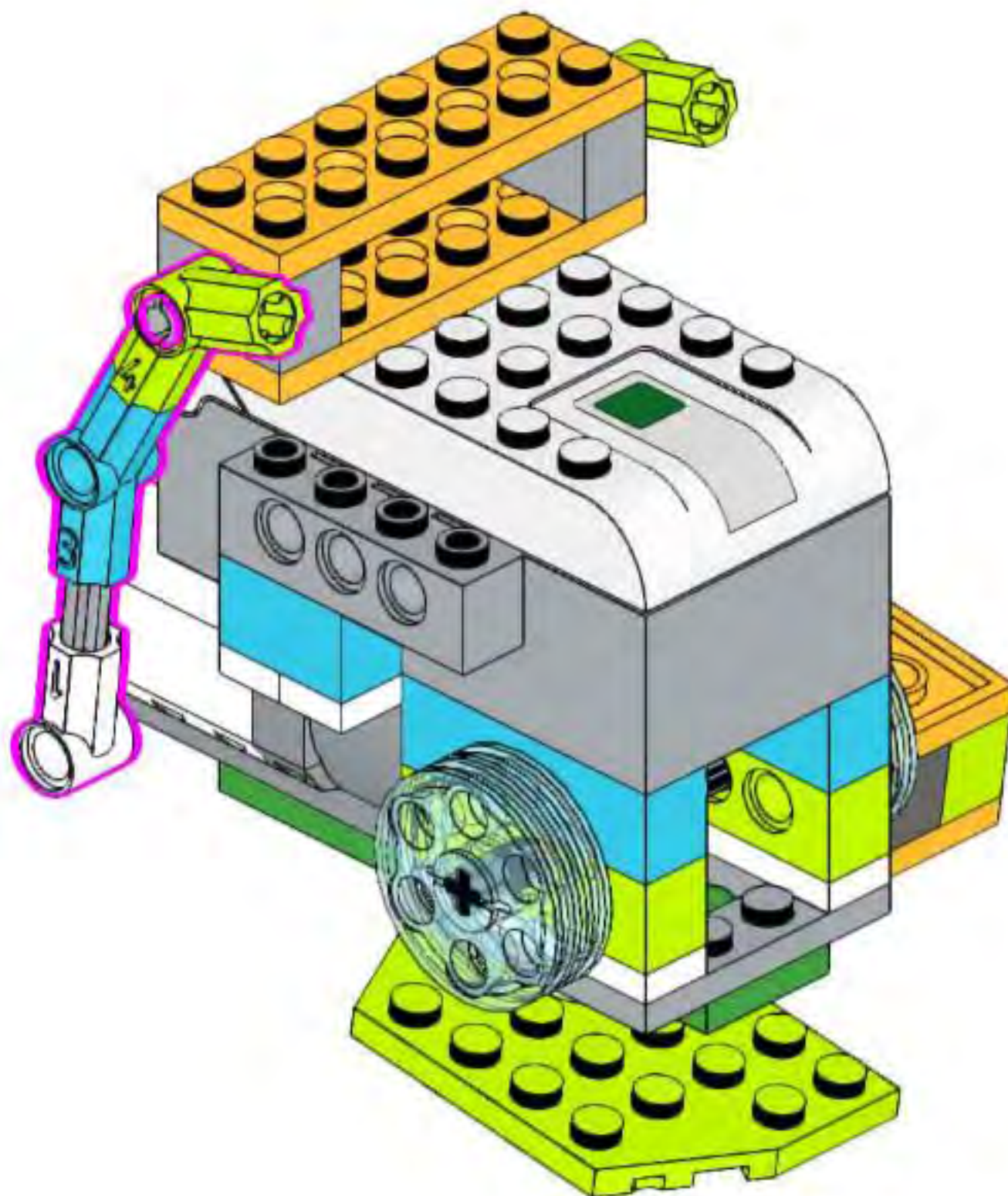


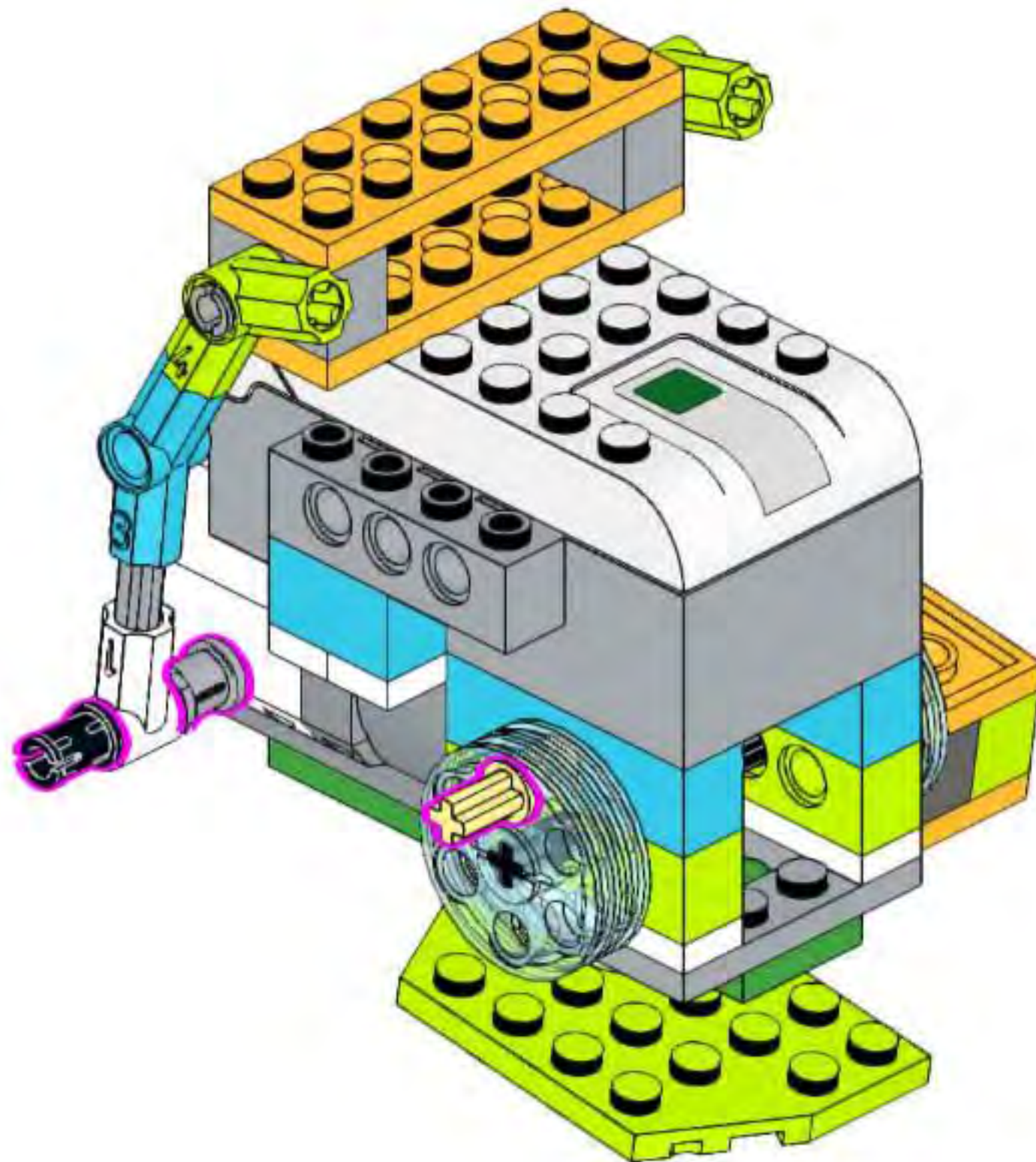
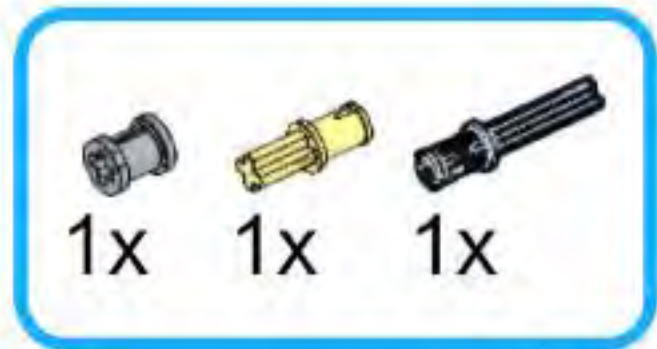


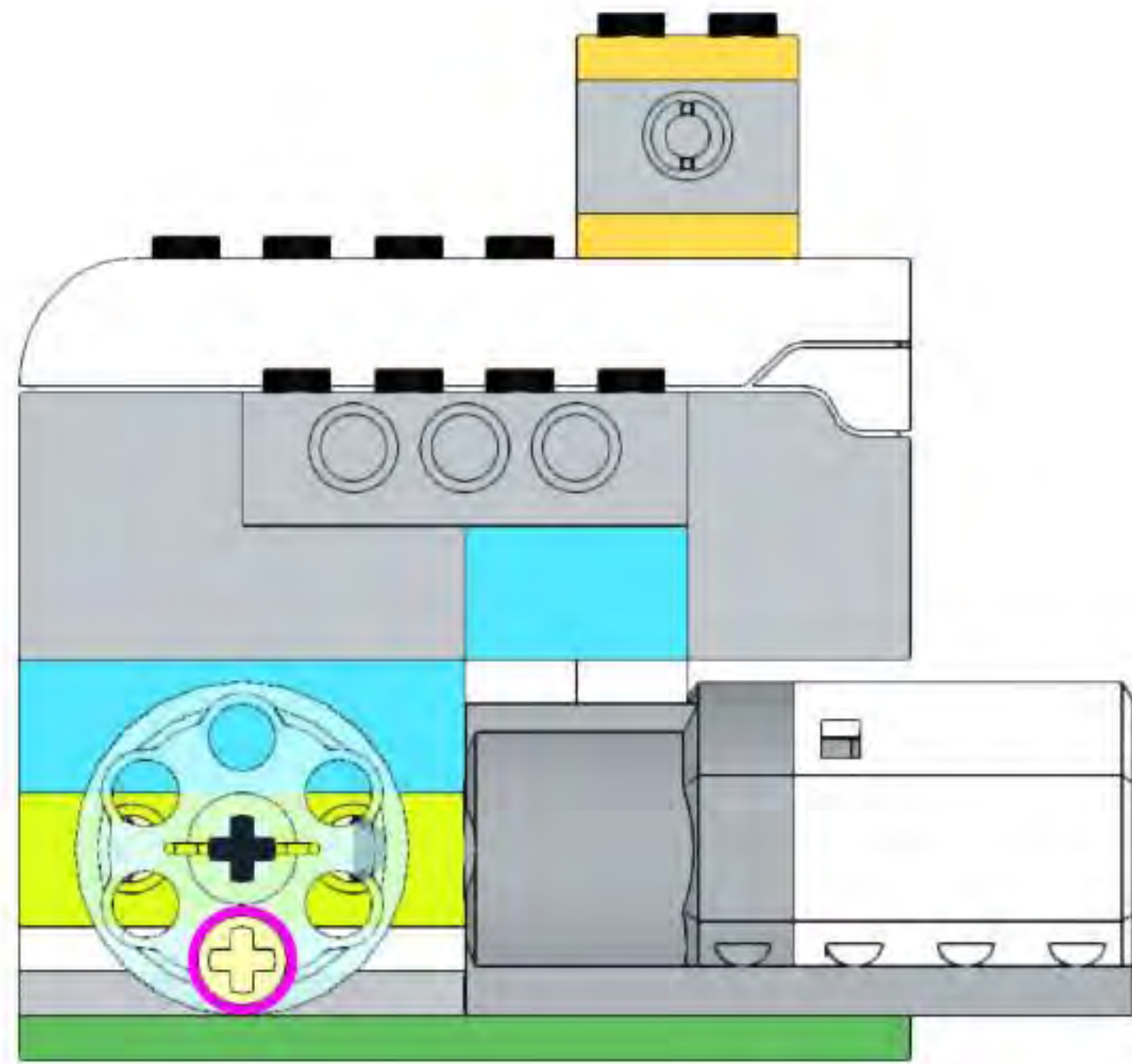
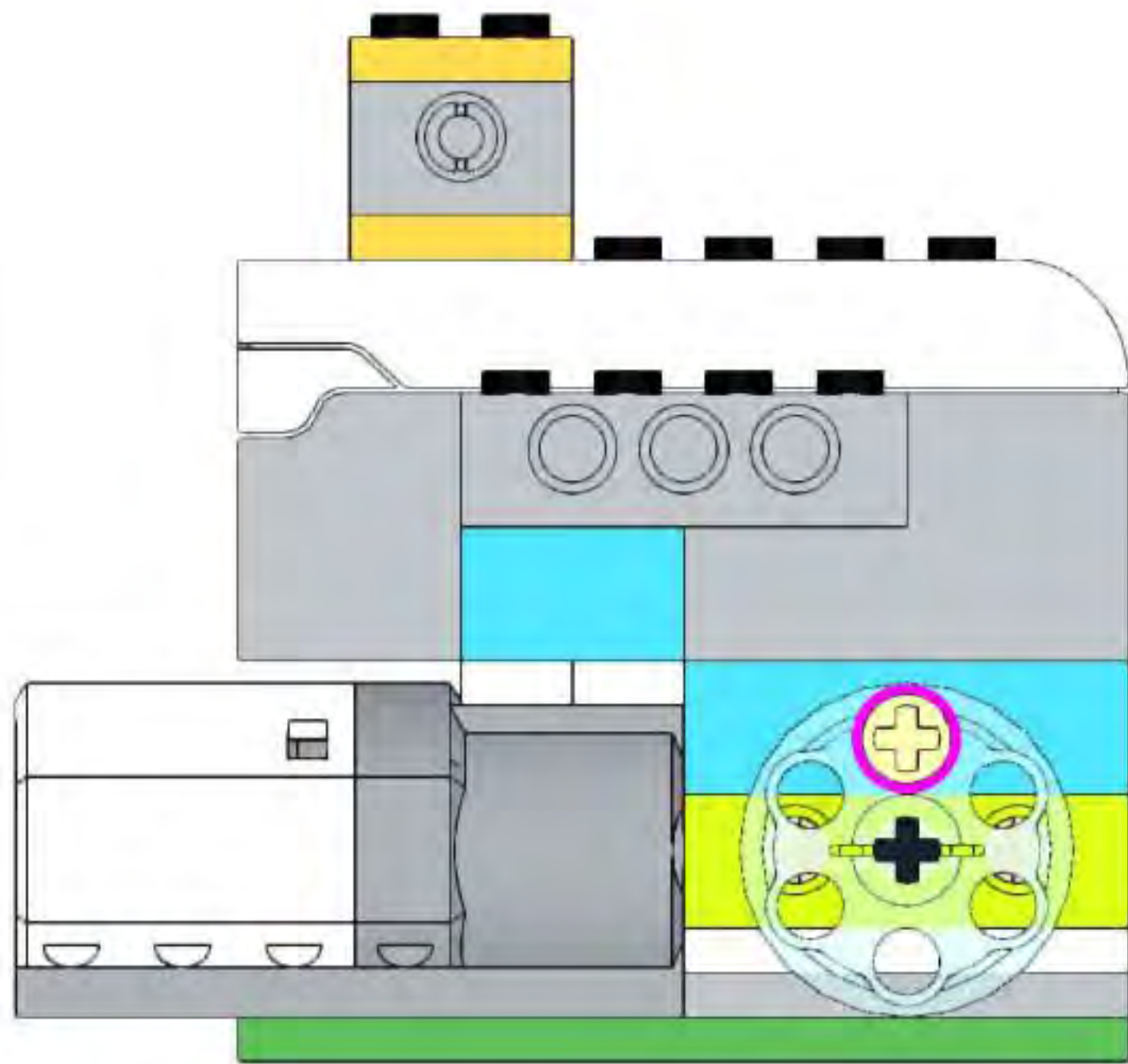


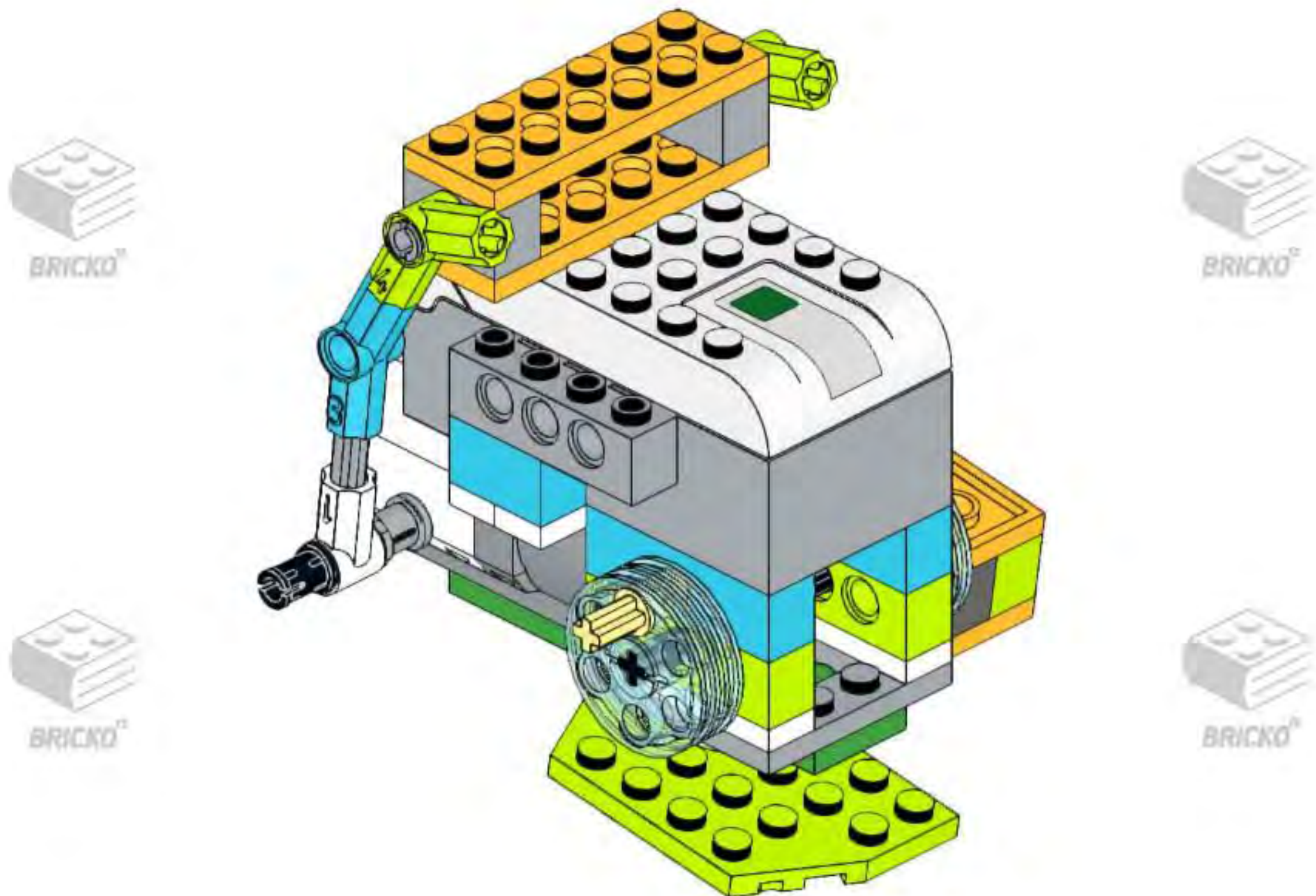


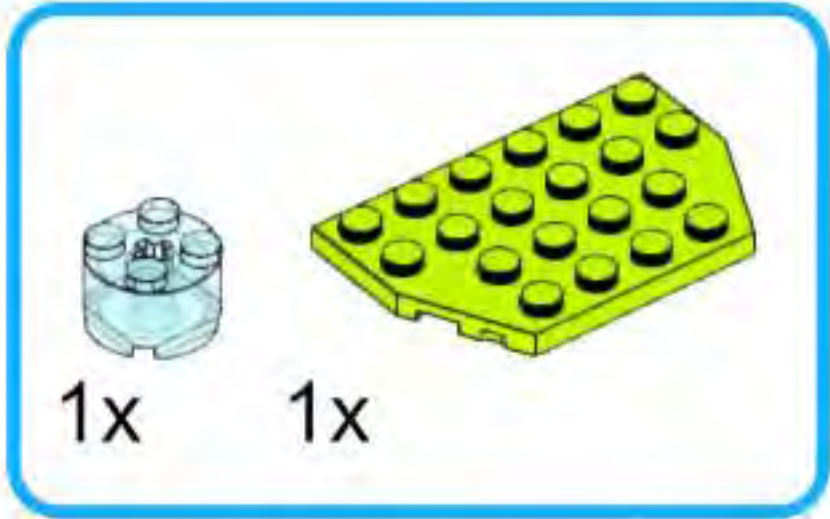












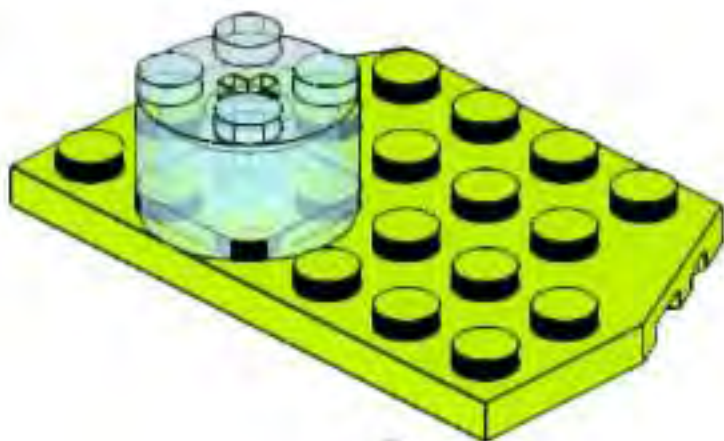
BRICKO[®]



BRICKO[®]



BRICKO[®]



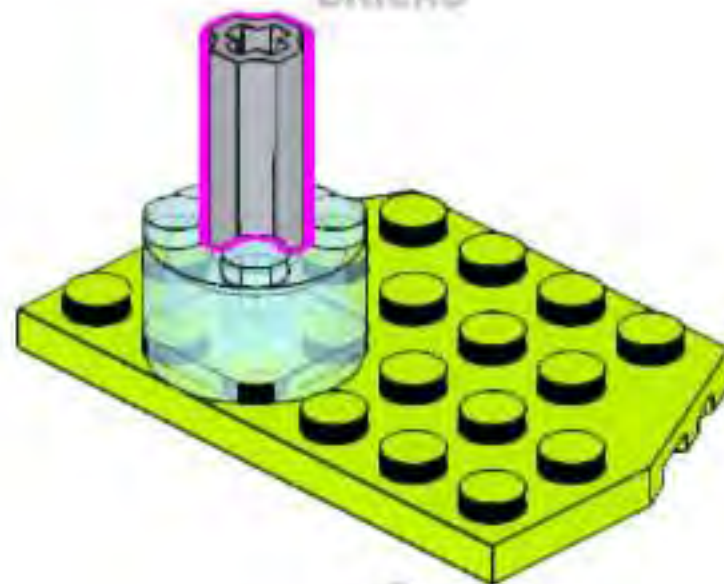
BRICKO[®]

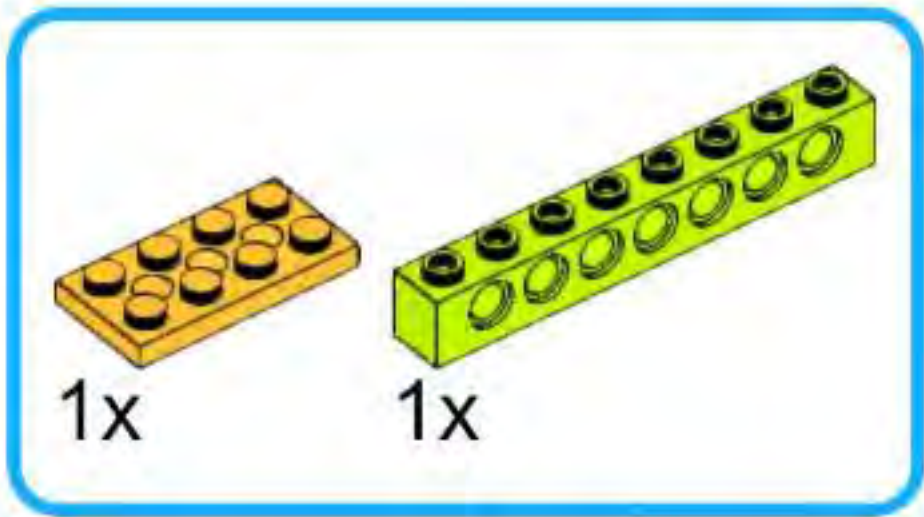


BRICKO[®]

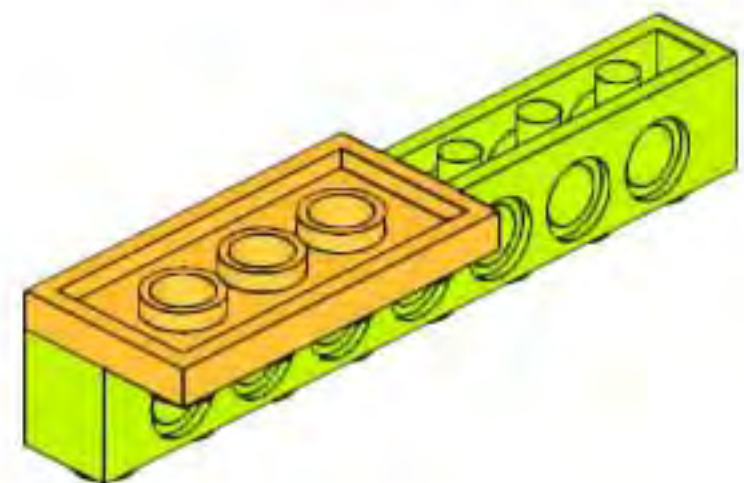


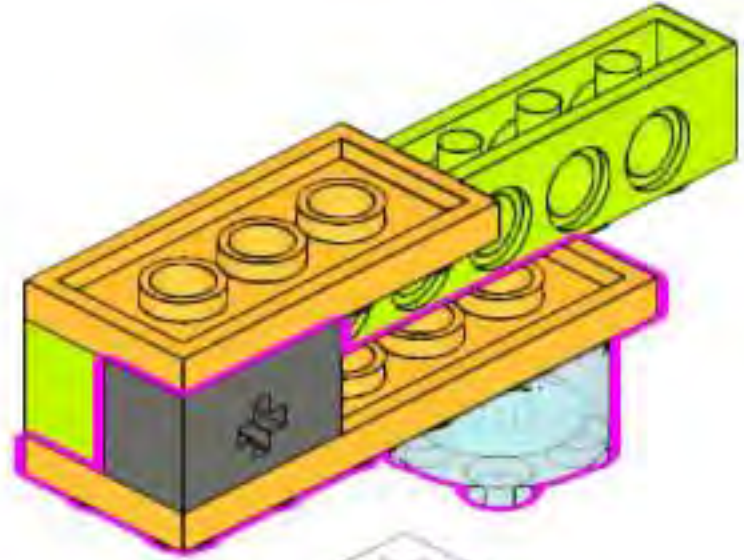
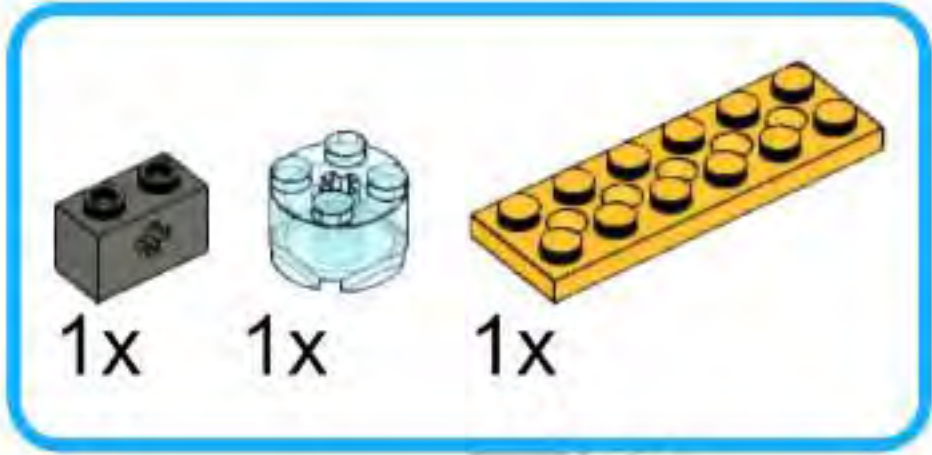
BRICKO[®]

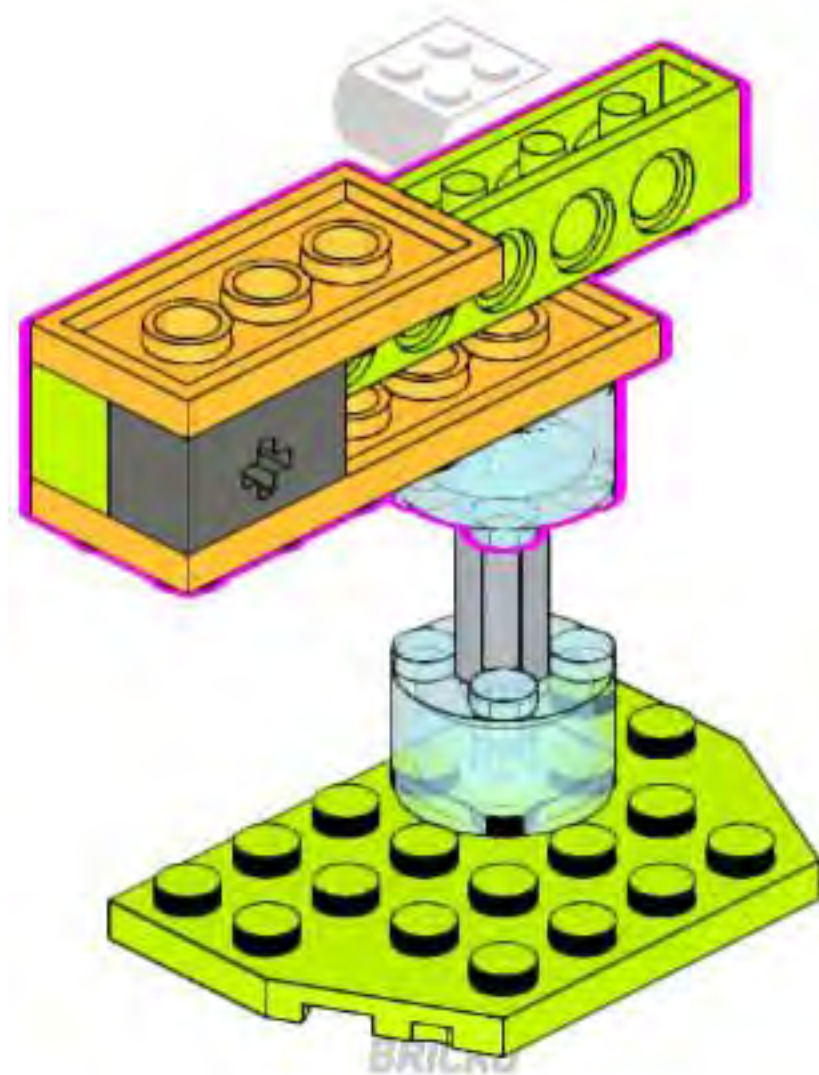




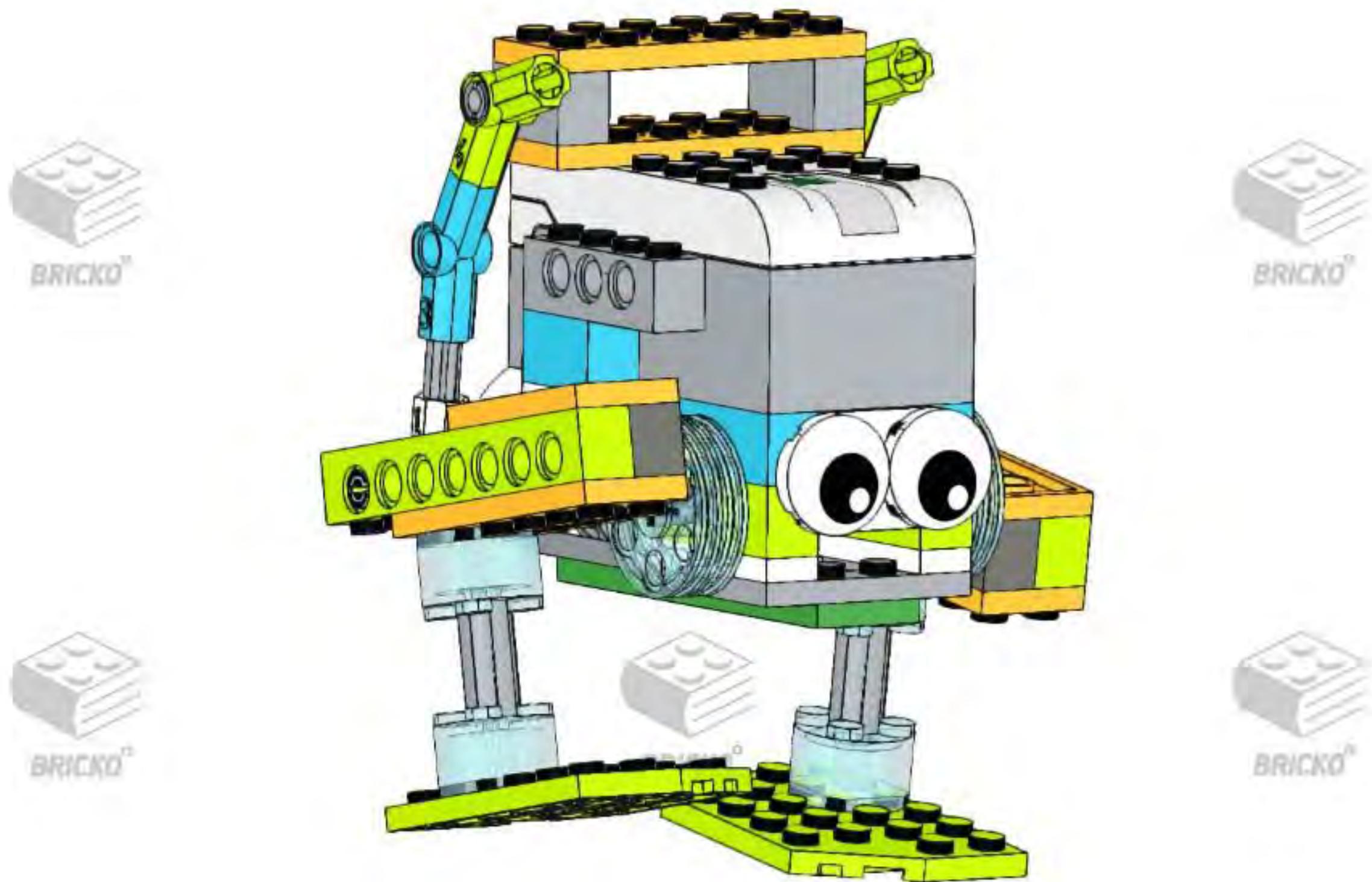
BRICKO[®]











Task 1

Make a program of the robot's movement with the lowest speed.

Is the robot moving?



Task 2

Make a program of the robot's movement with the highest speed.

The robot doesn't break down?



Task 3



Create a program for the robot's movement at the optimal speed. As quickly as possible, but so that it does not break.

What is the speed of your robot?



Task *4

Make a program that moves the robot at a speed of 3 forward for 5 seconds, after which it stops.



Task *5

Make a program that moves the robot at a speed of 3 forward for 5 seconds, then 5 seconds back, after which everything repeats endlessly.



