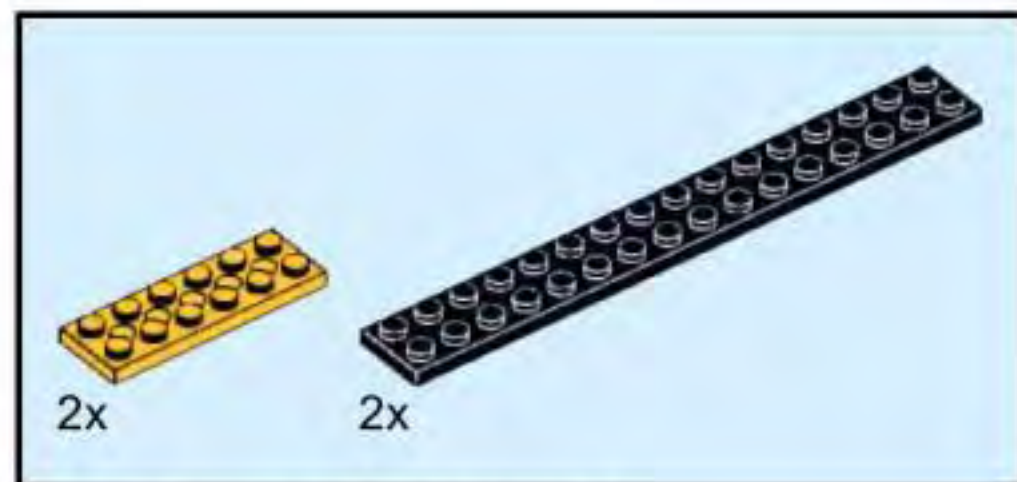


Walking Man

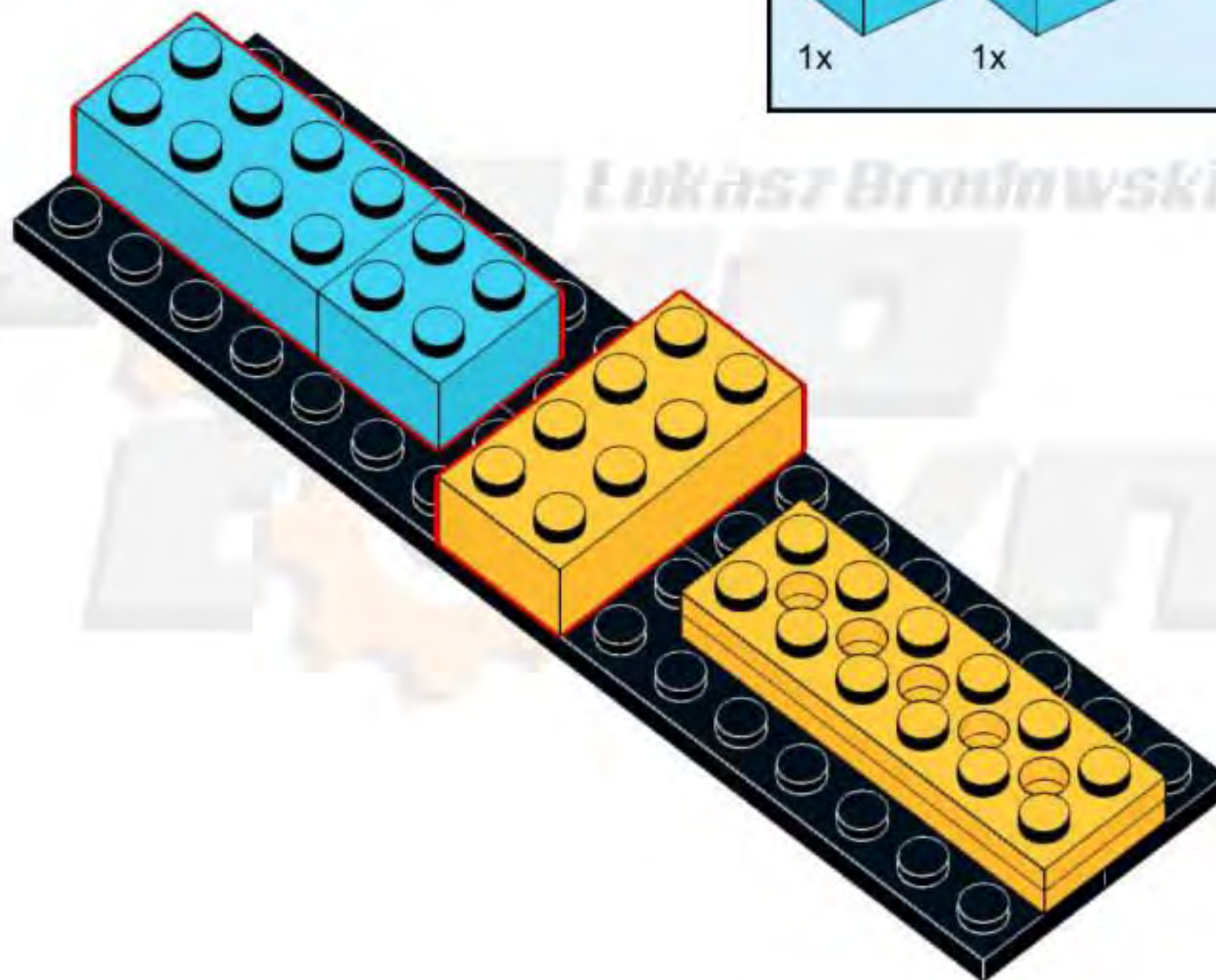
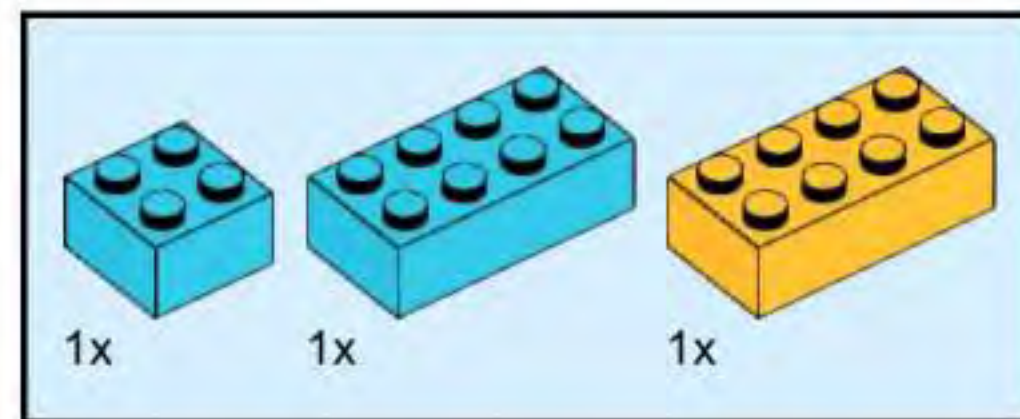


Author: Łukasz Brodowski

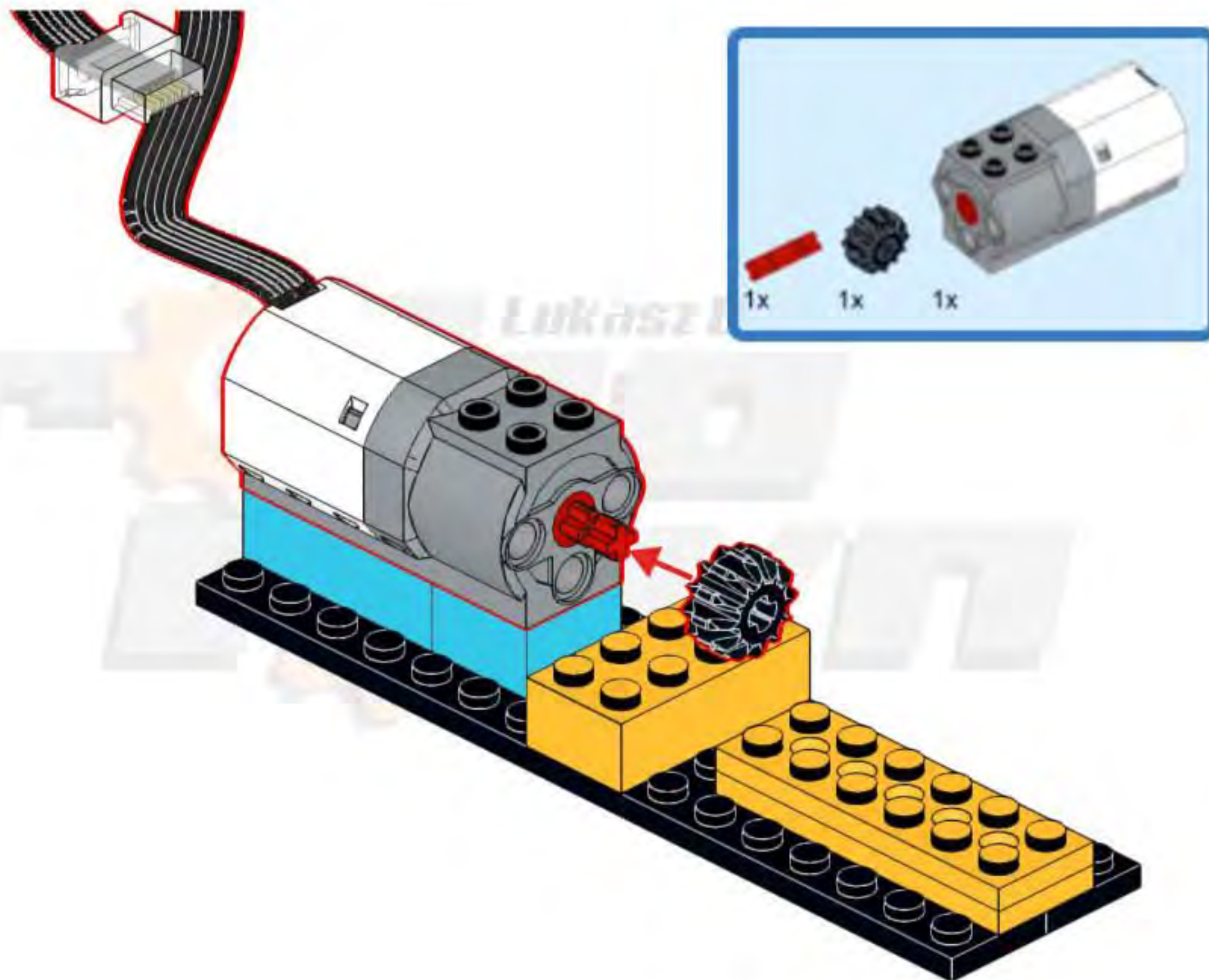
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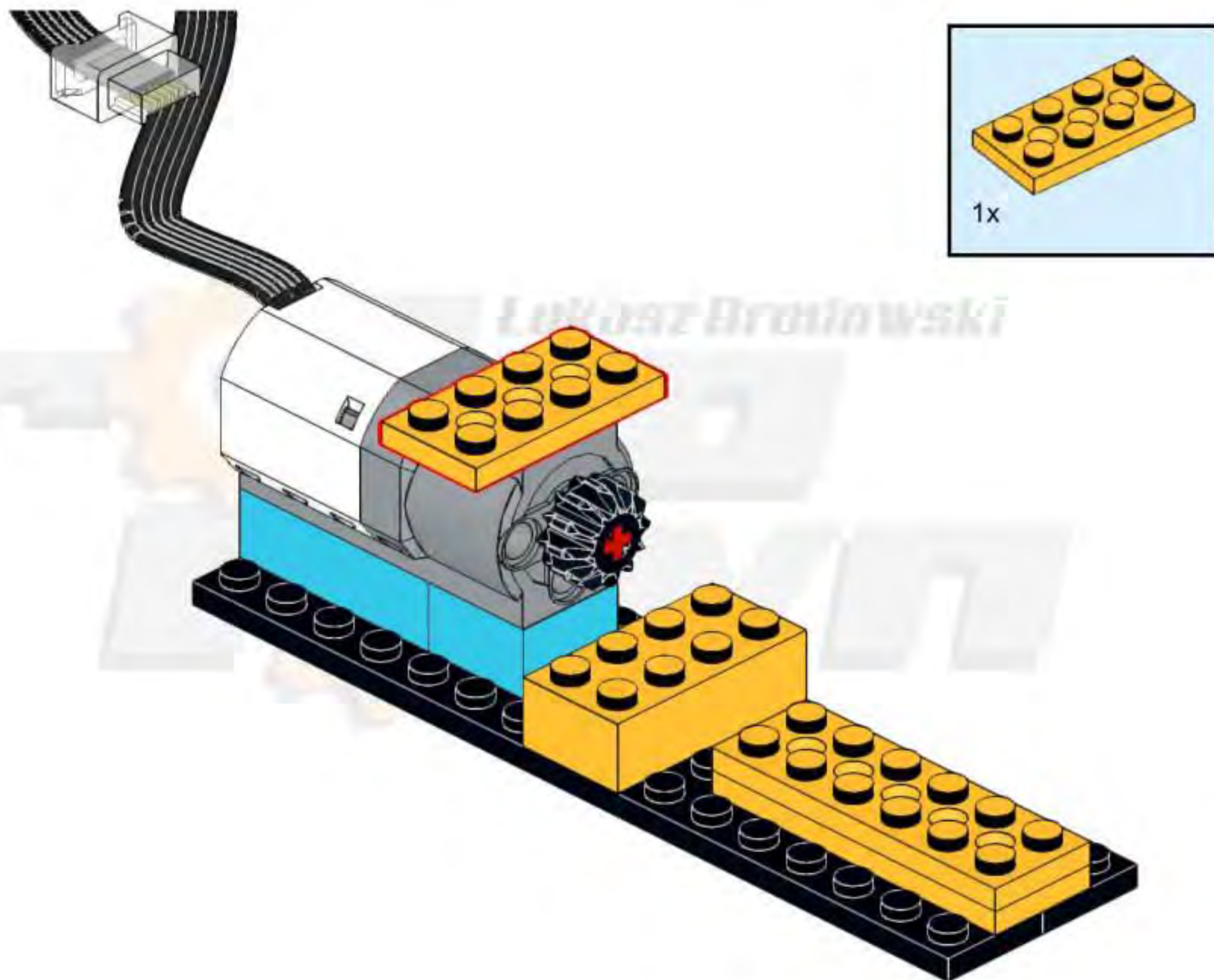
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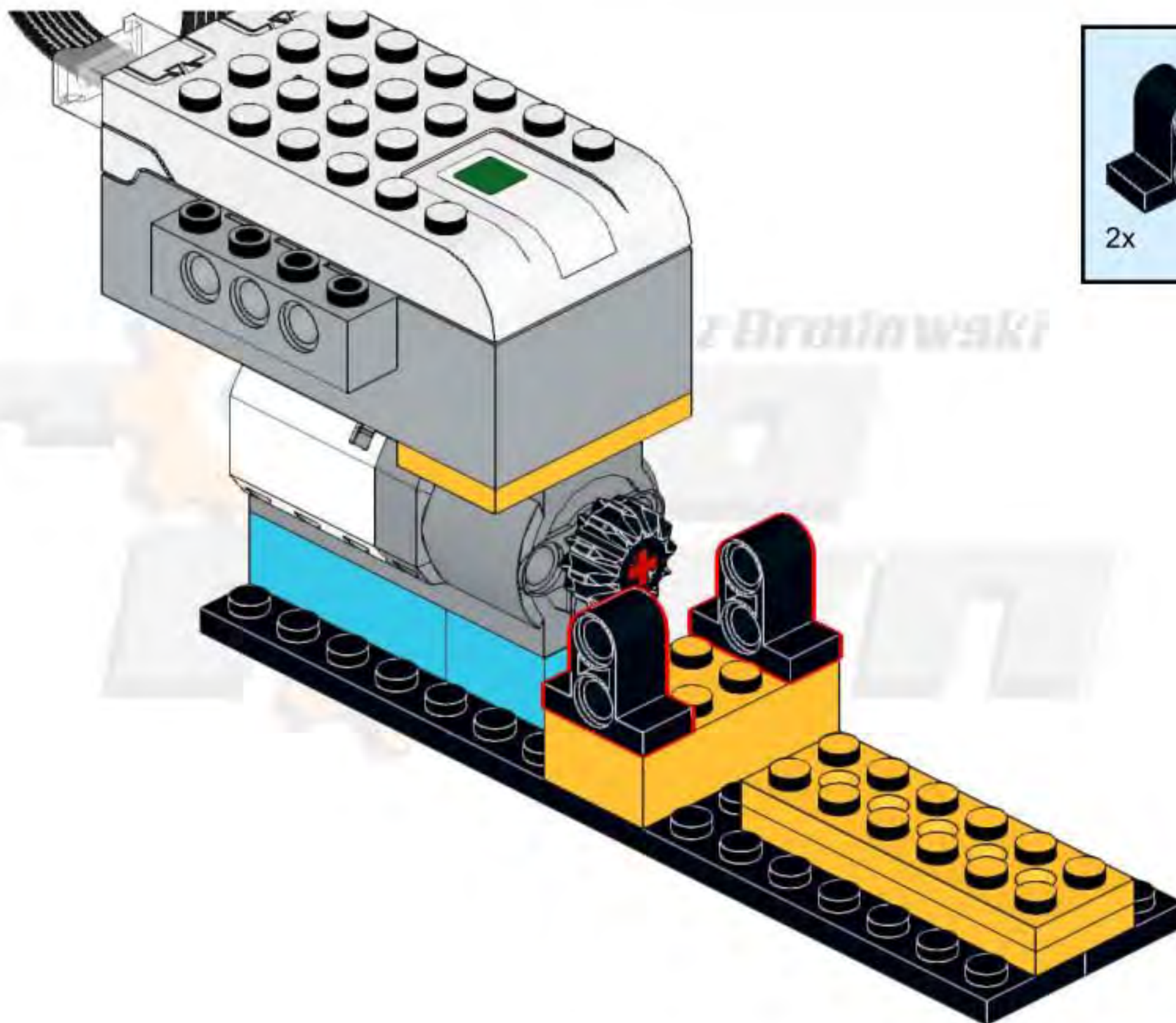


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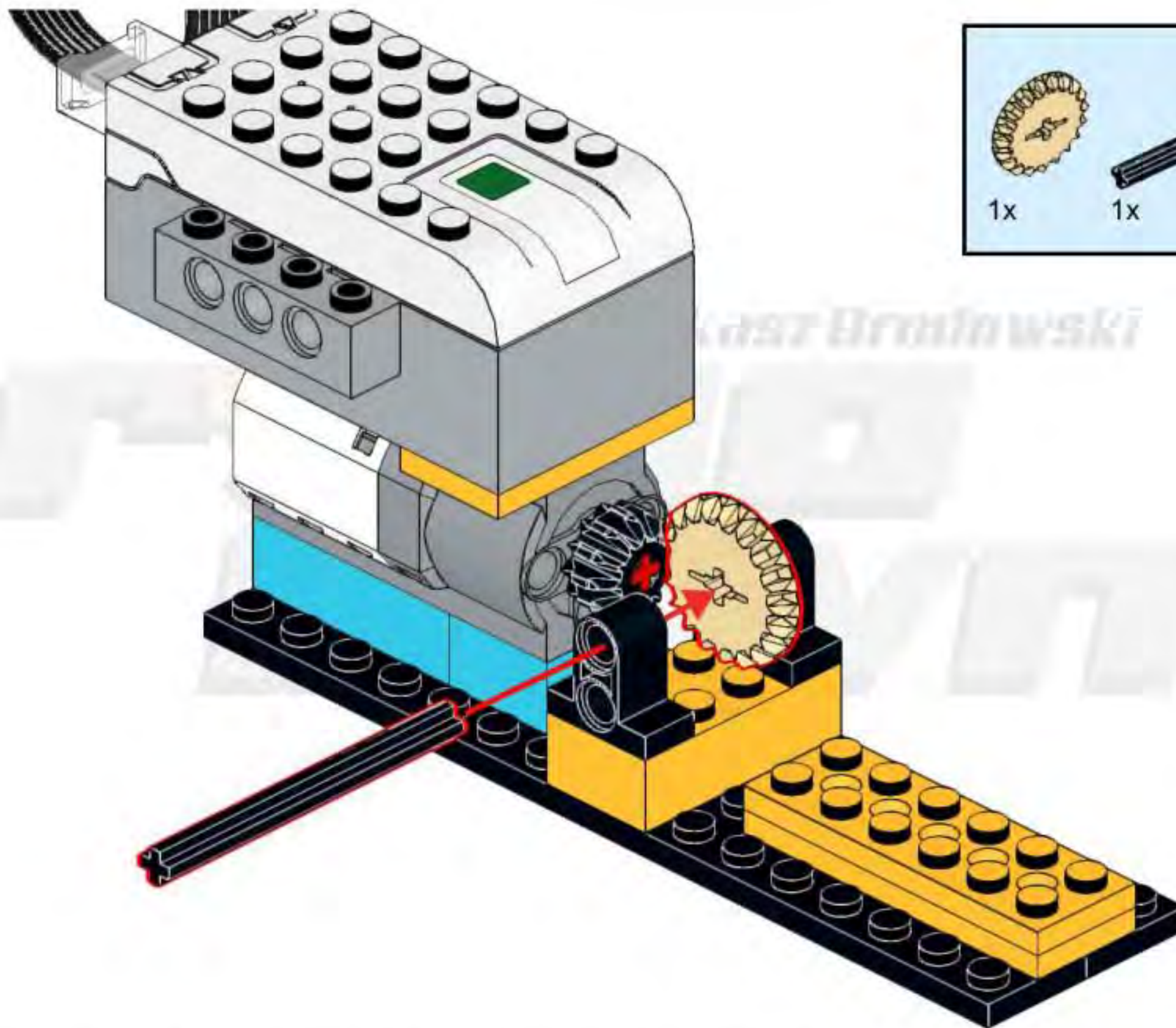


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6

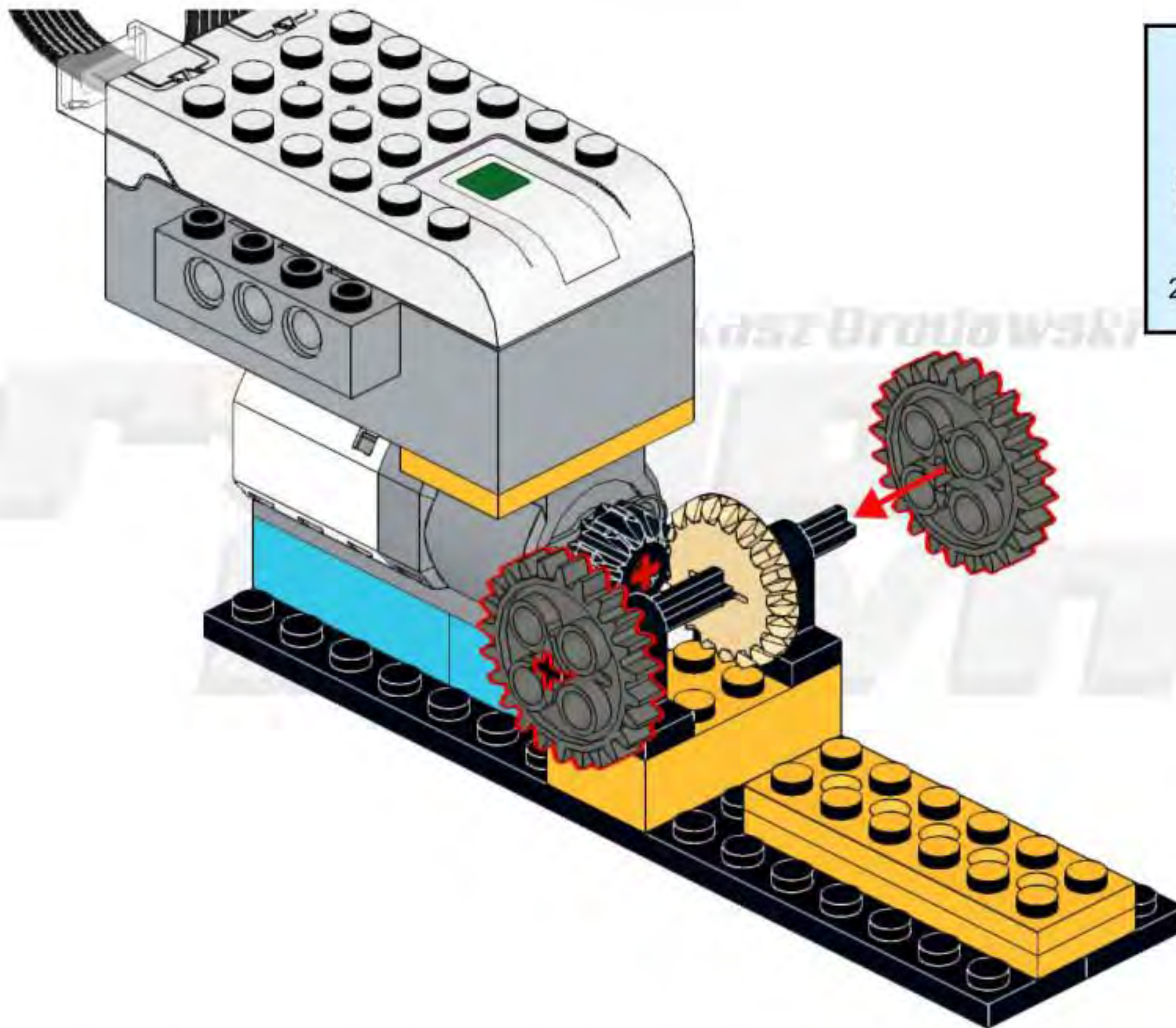


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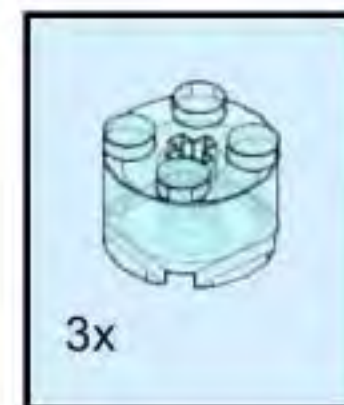
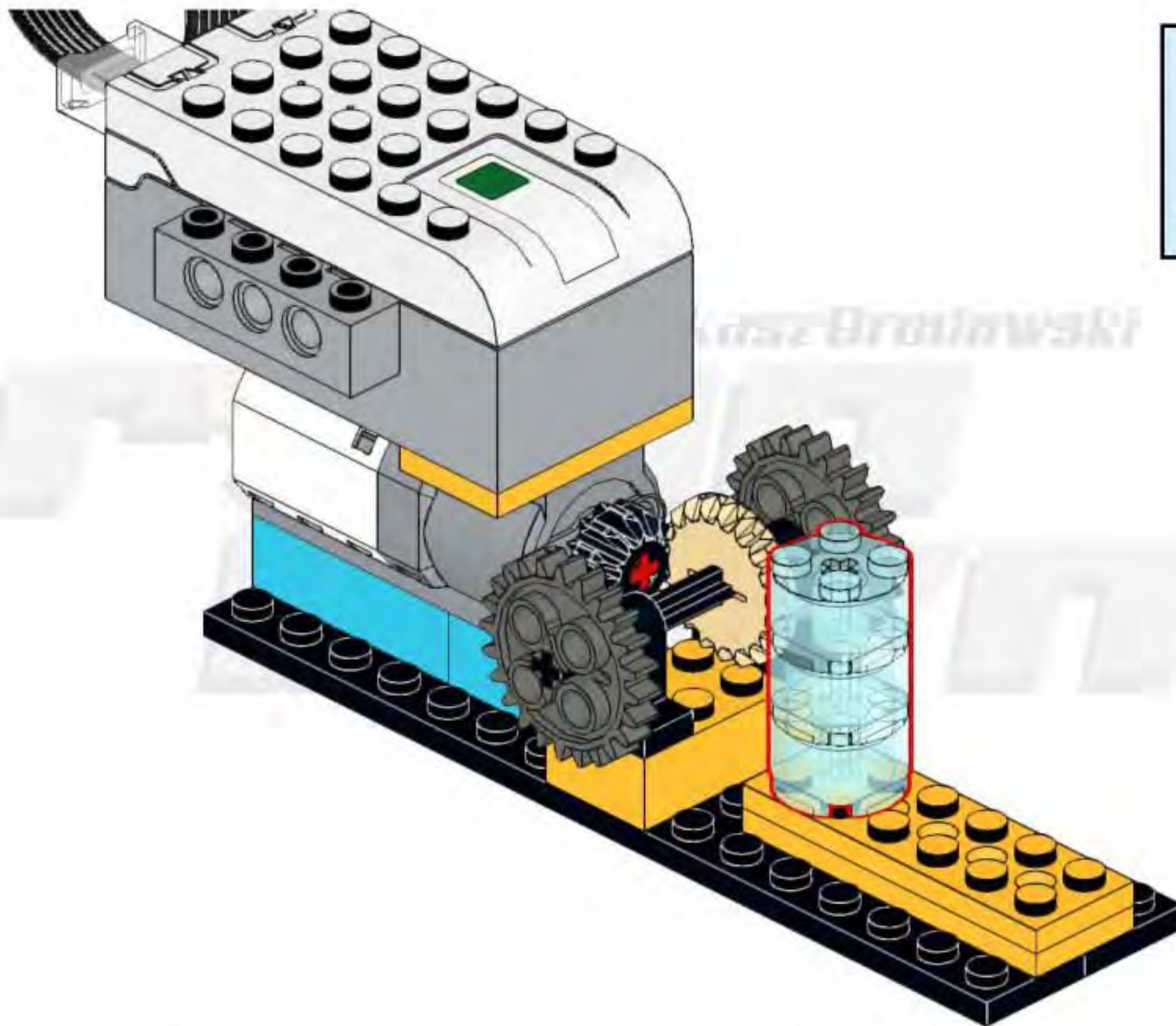


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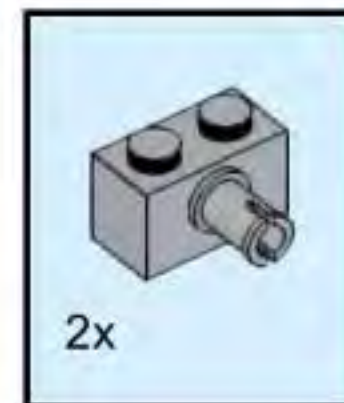
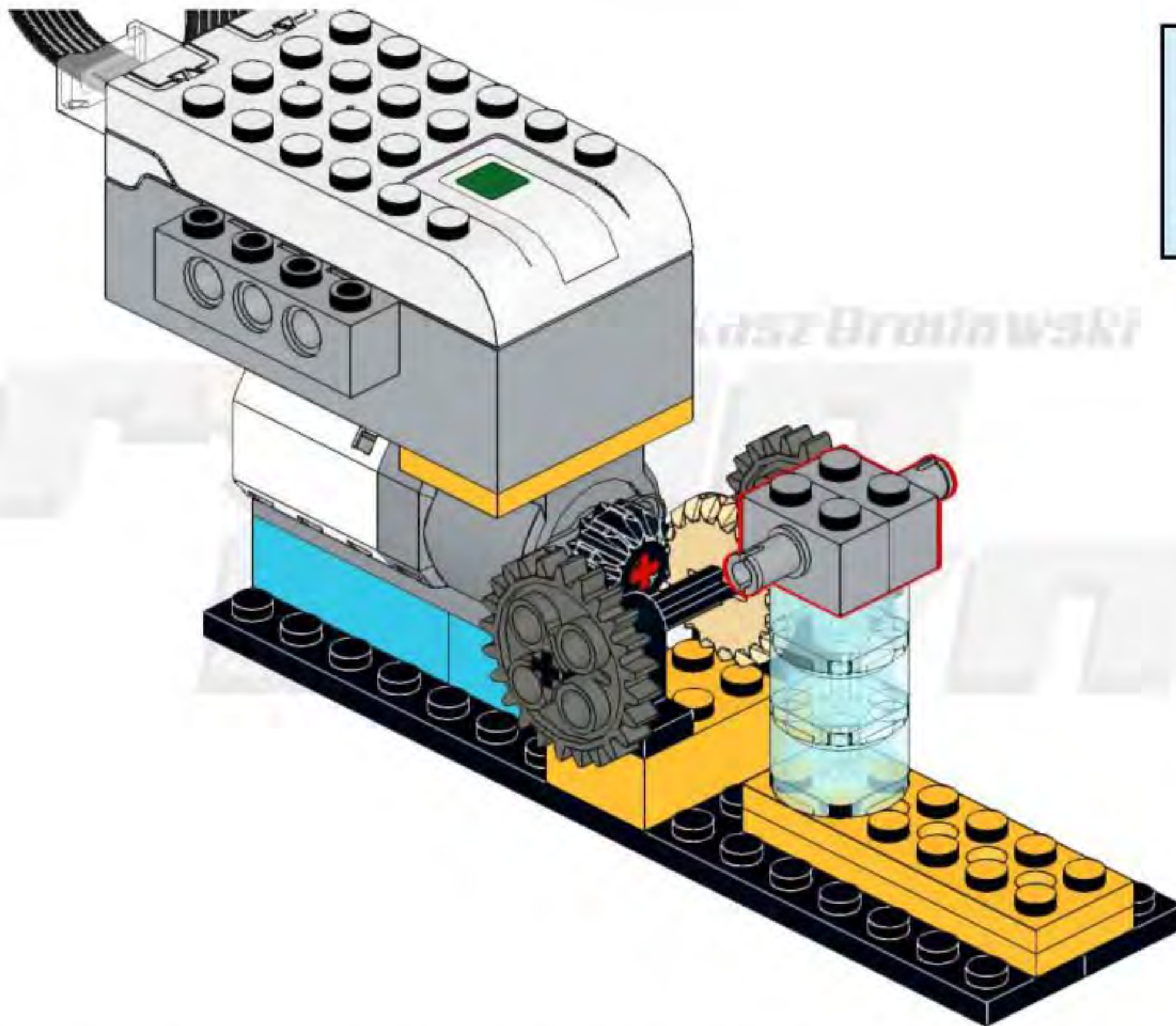
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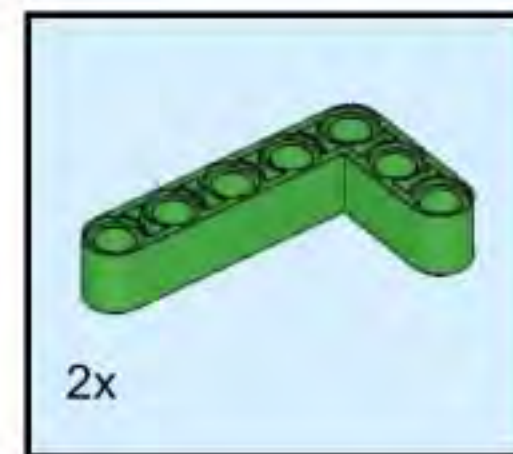
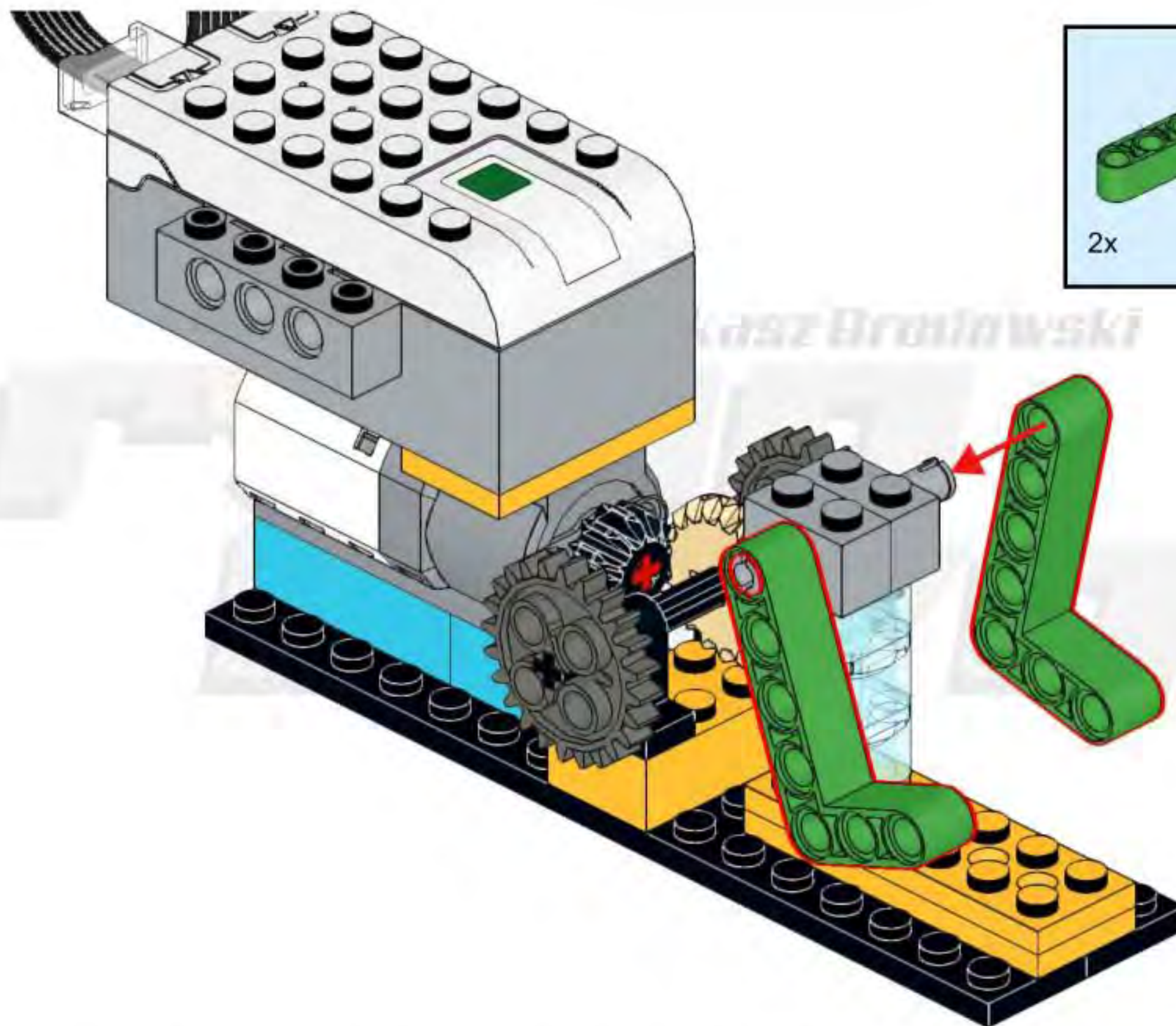
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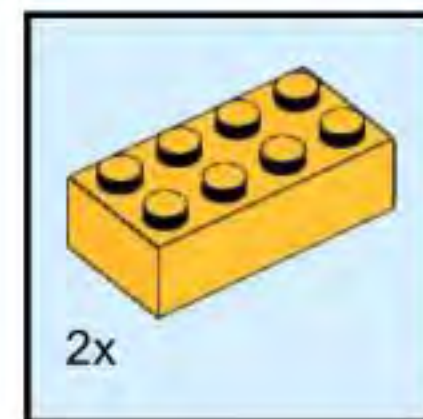
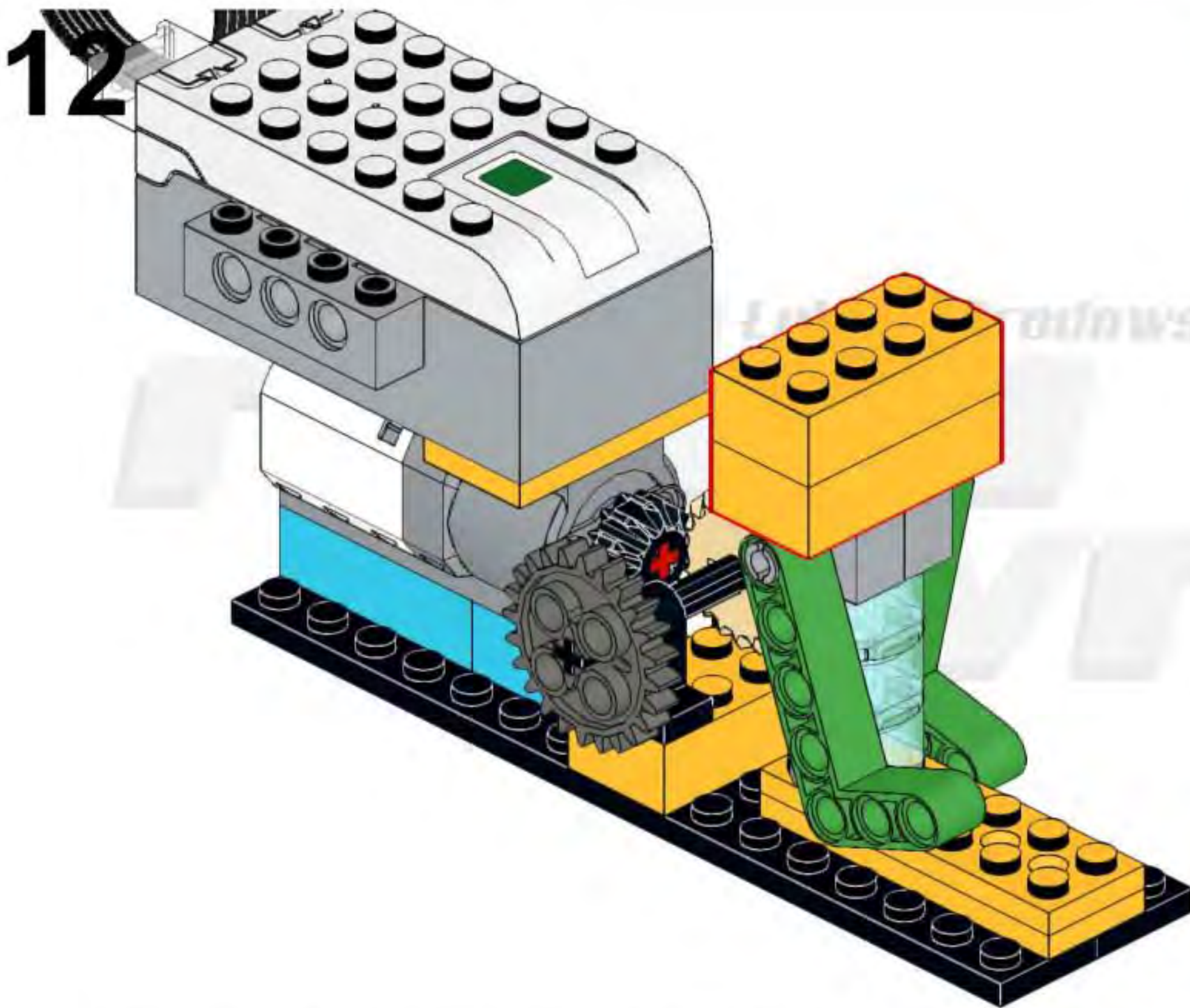


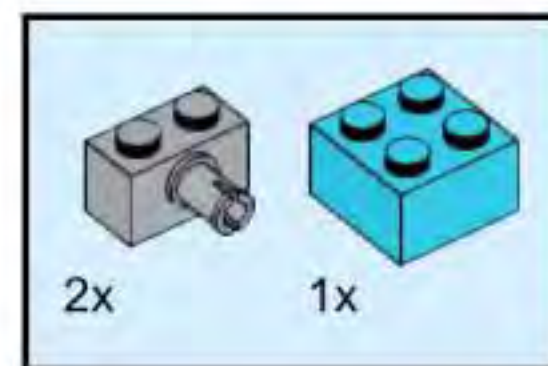
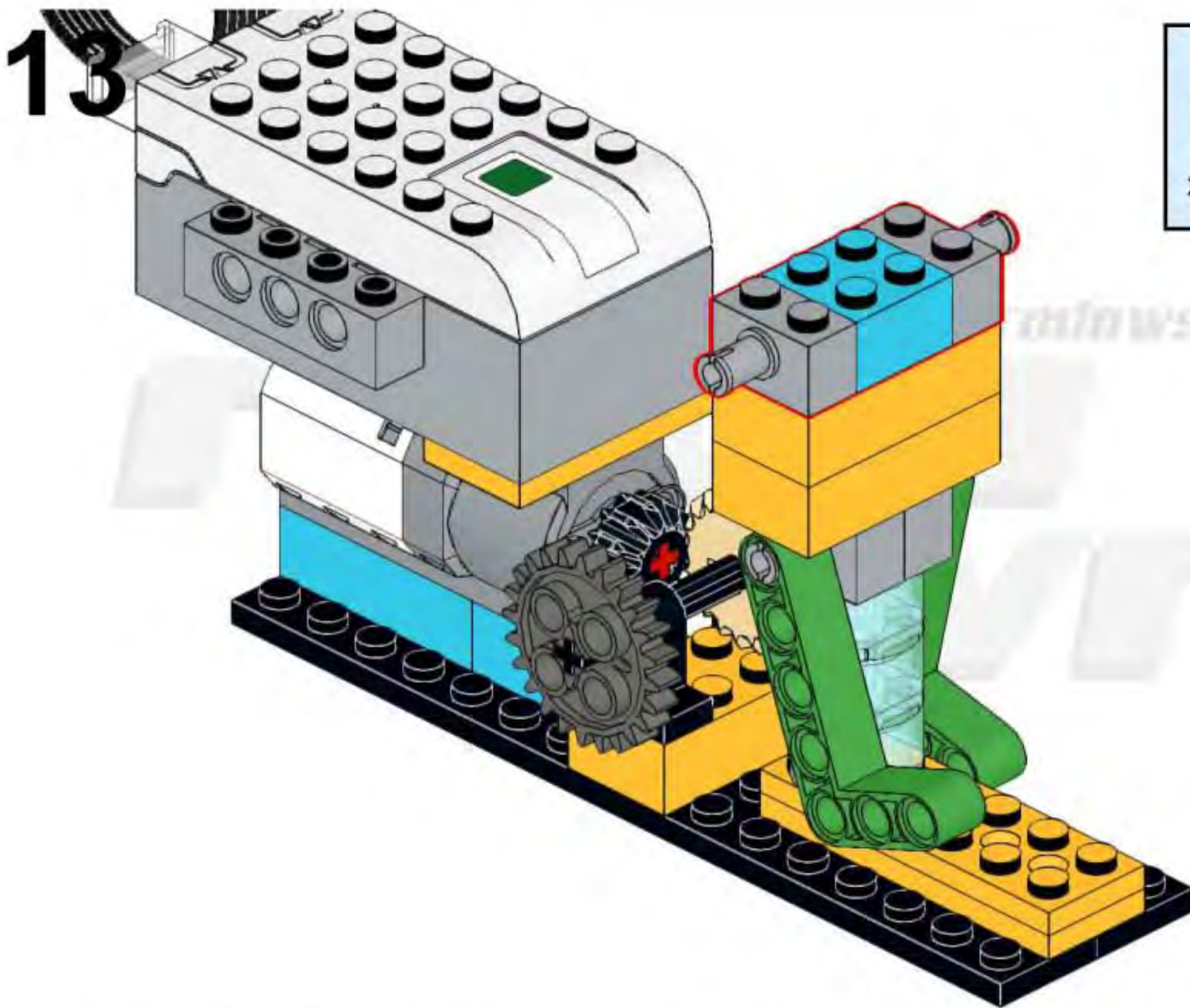
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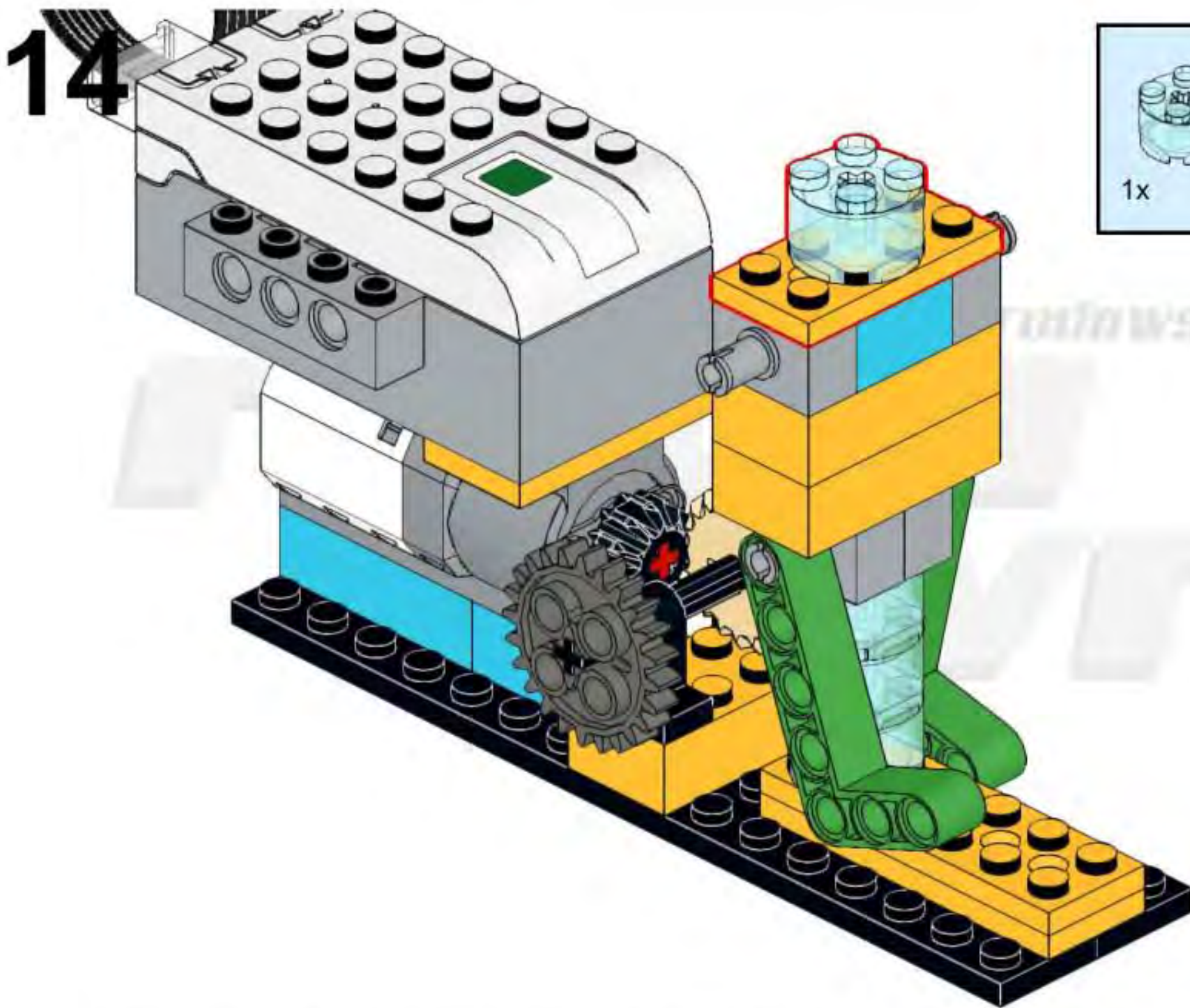


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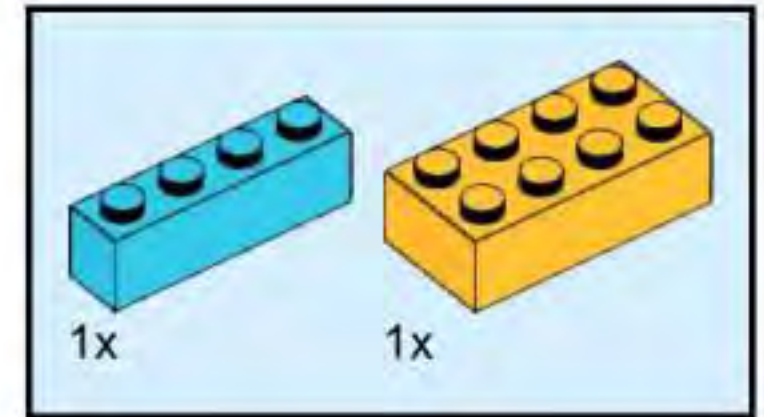
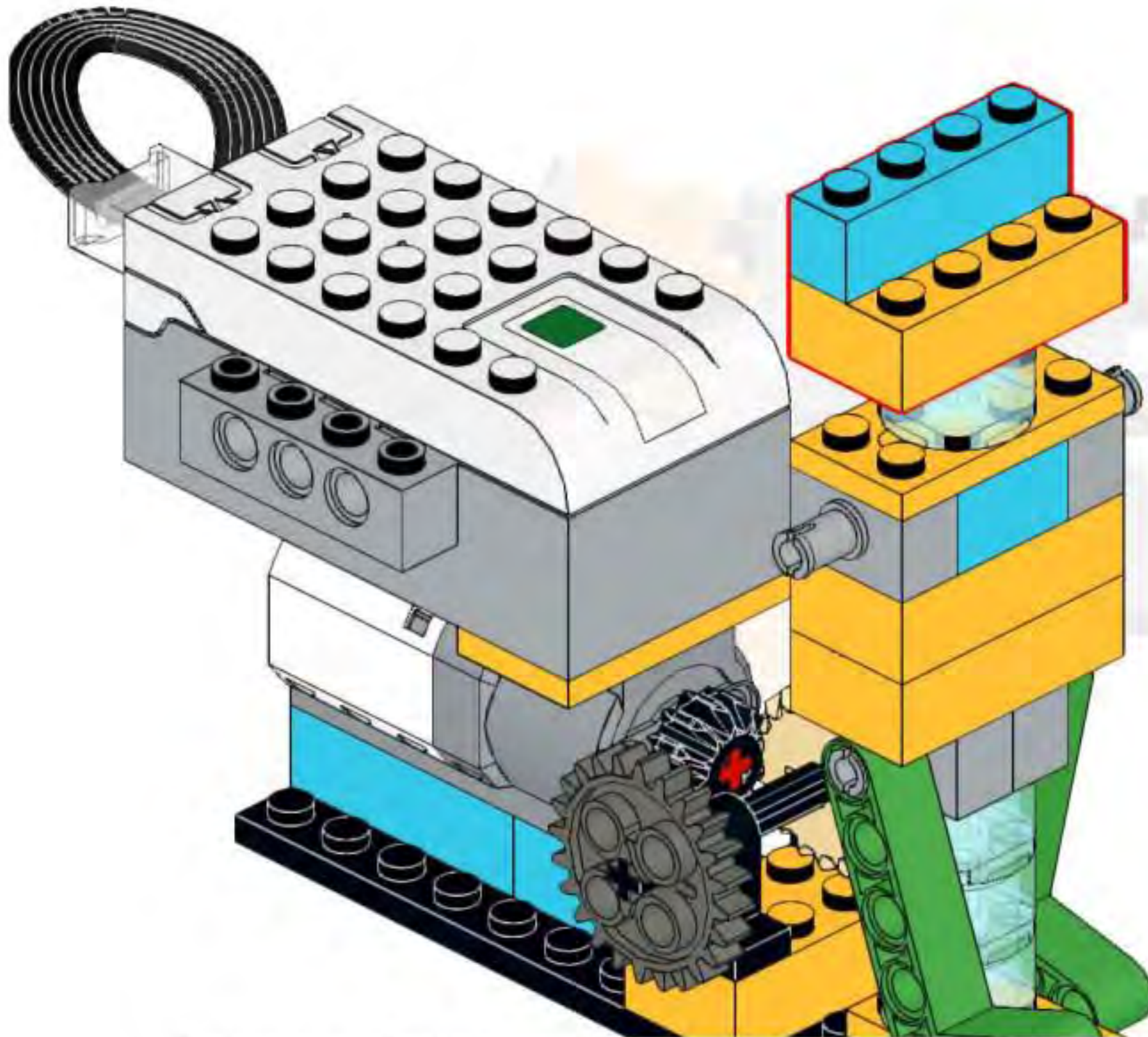




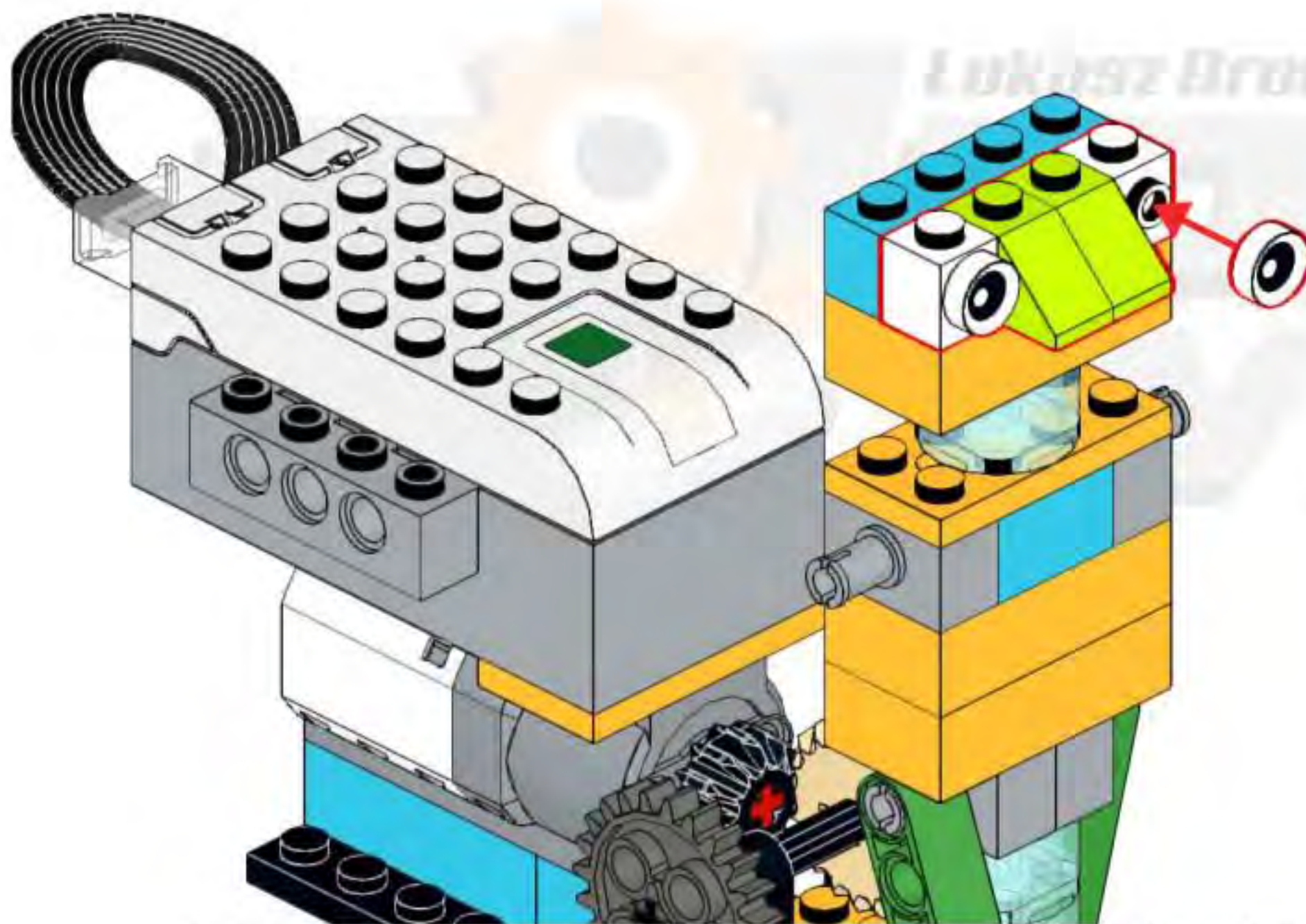
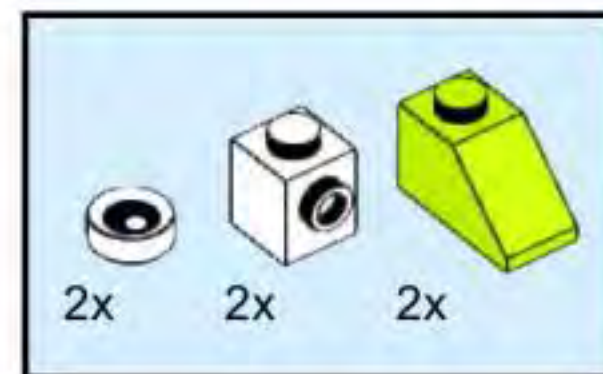




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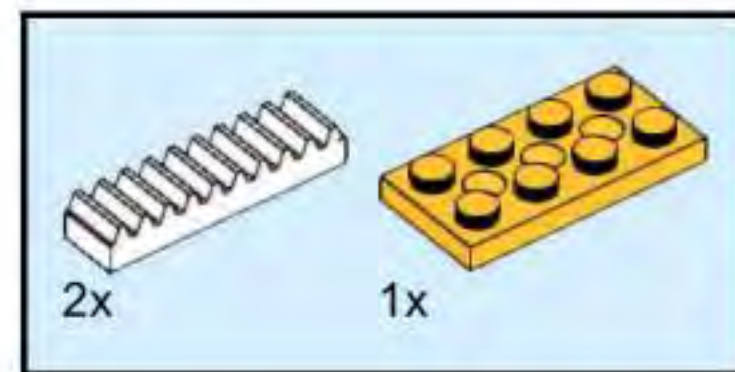
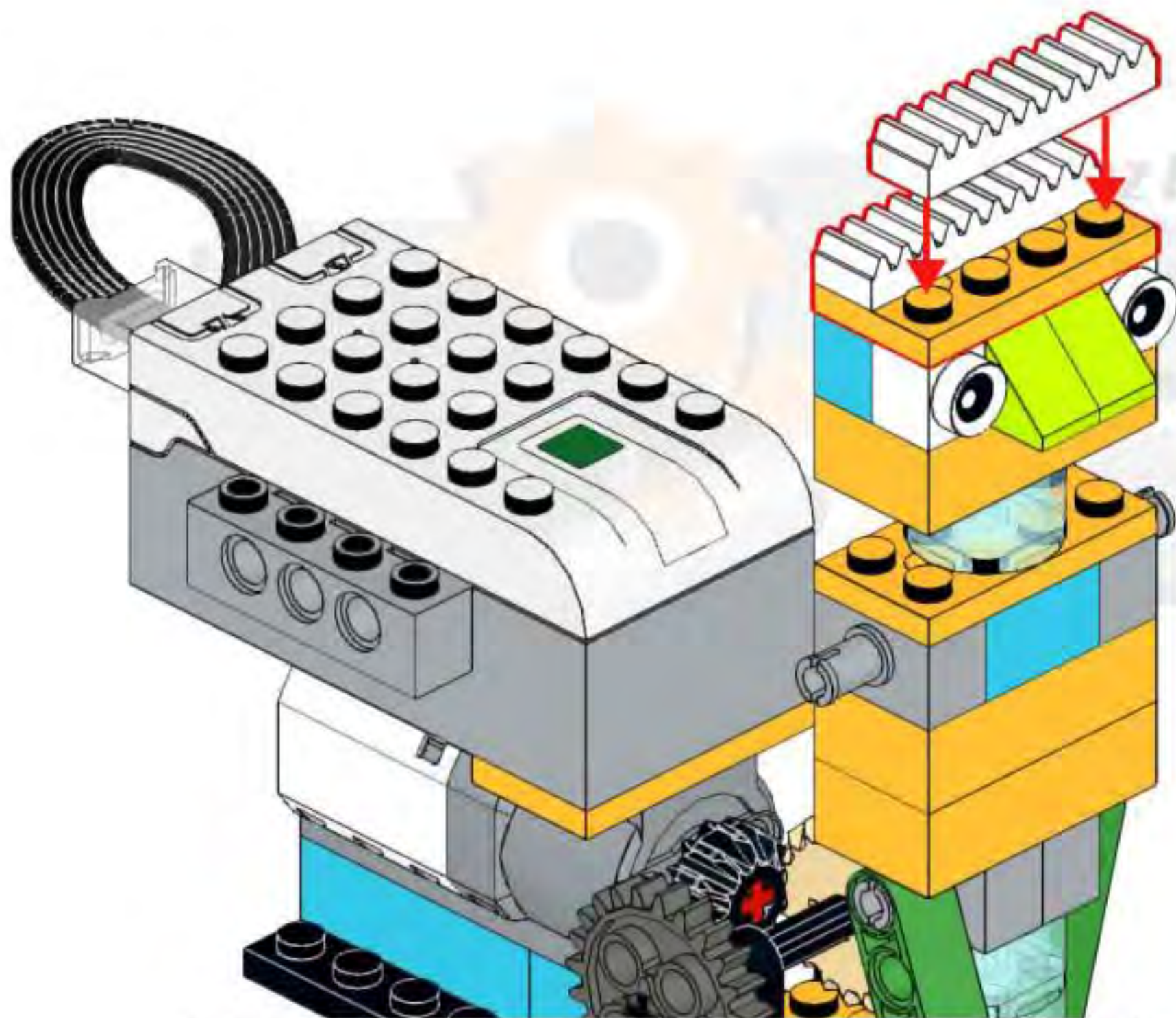


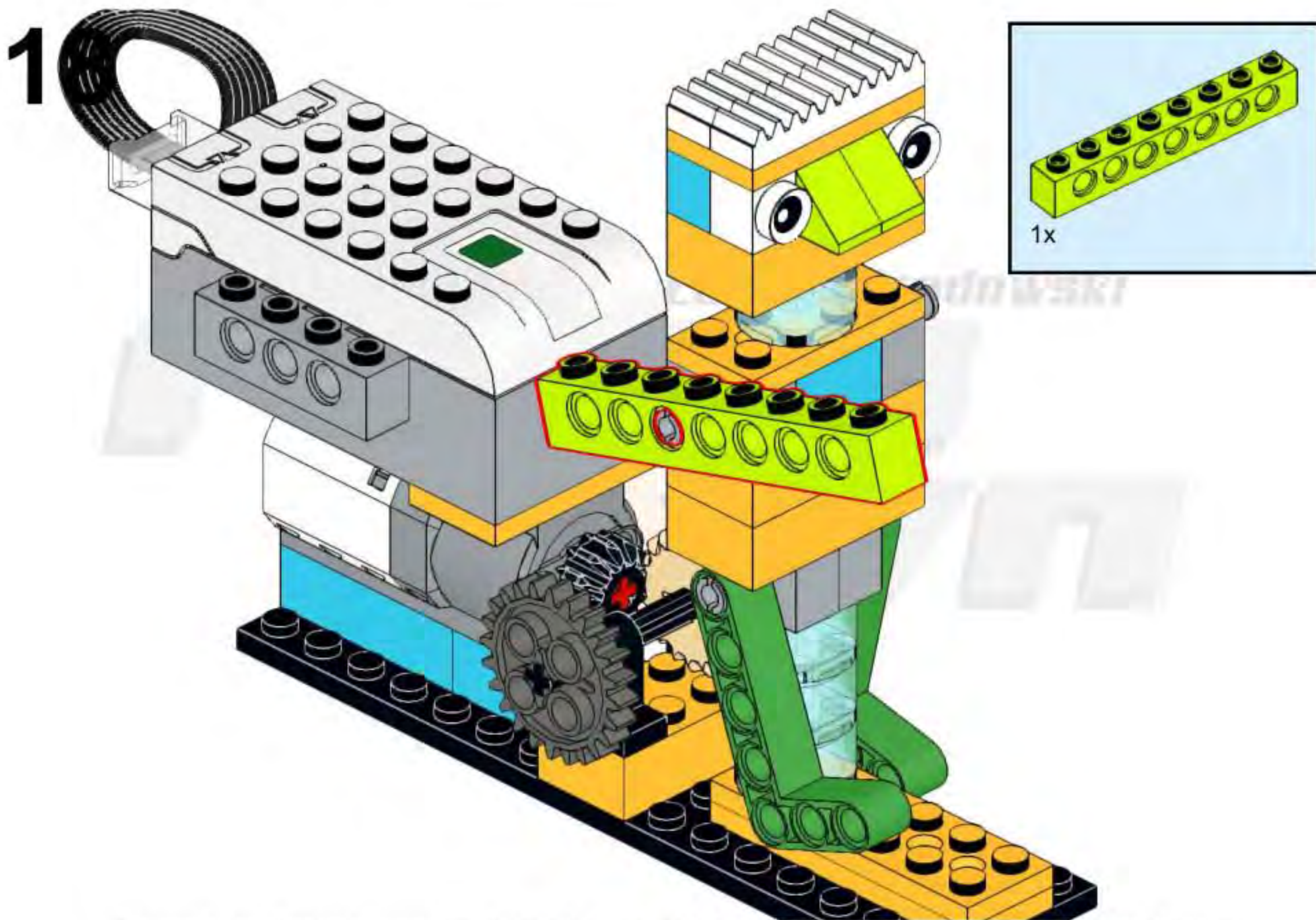
16



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17

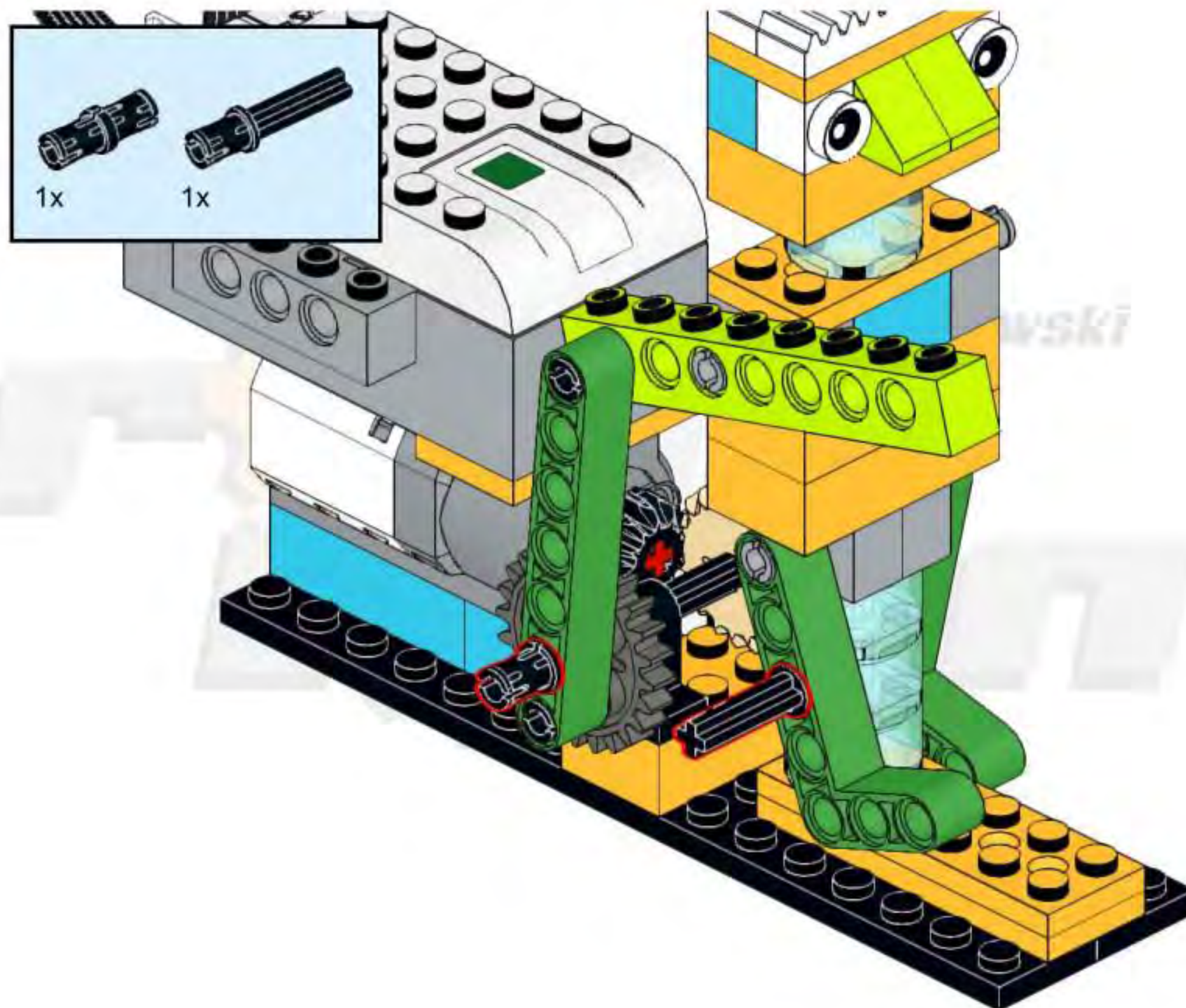


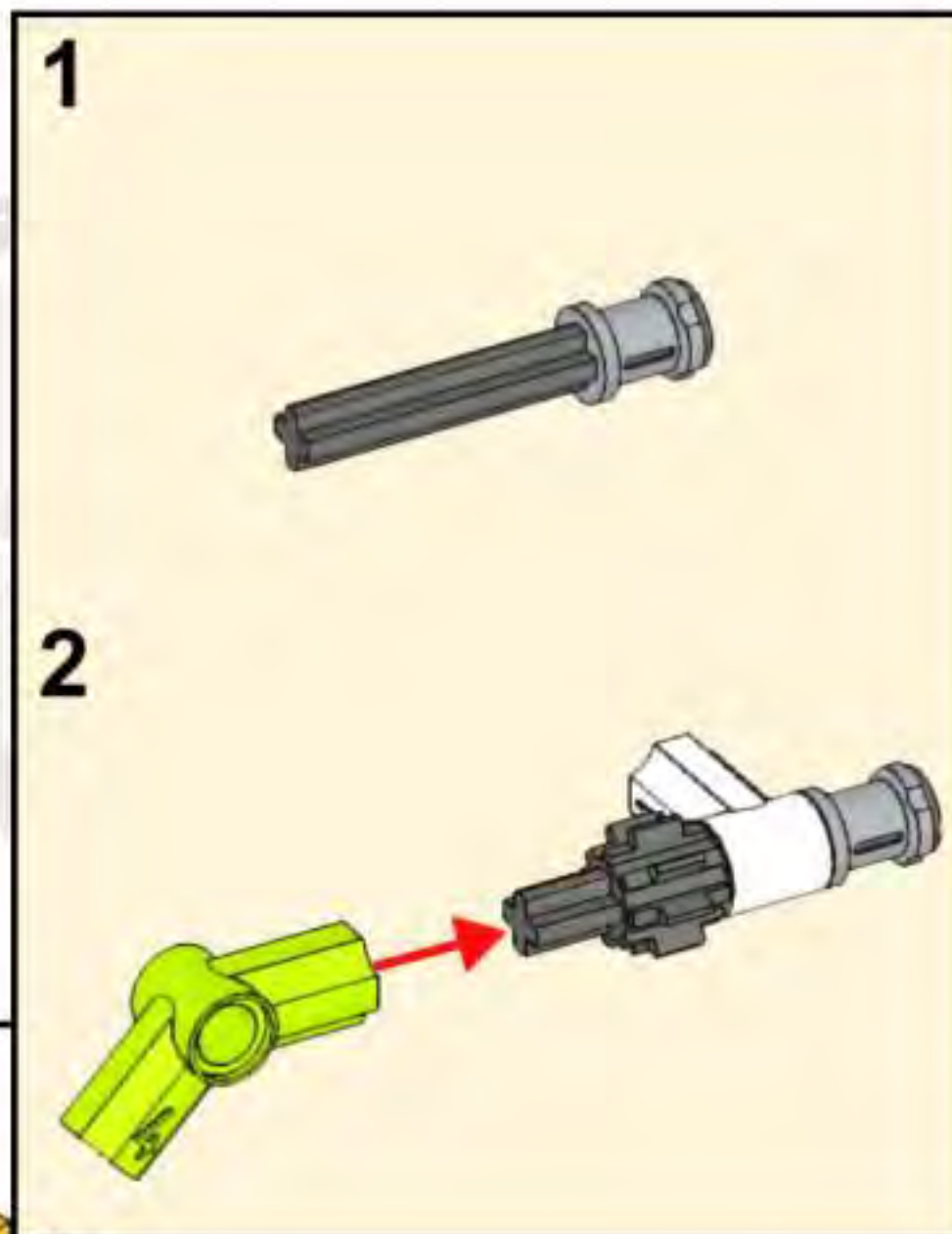
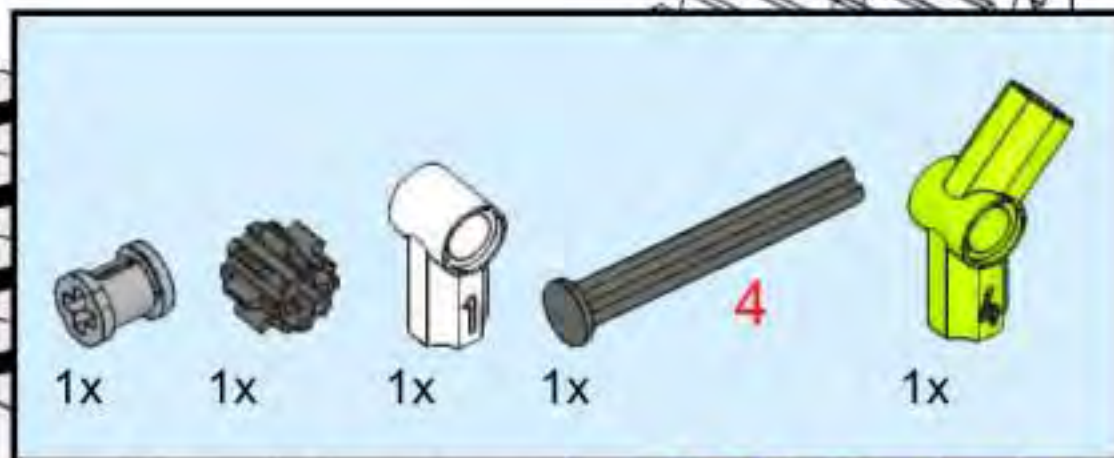
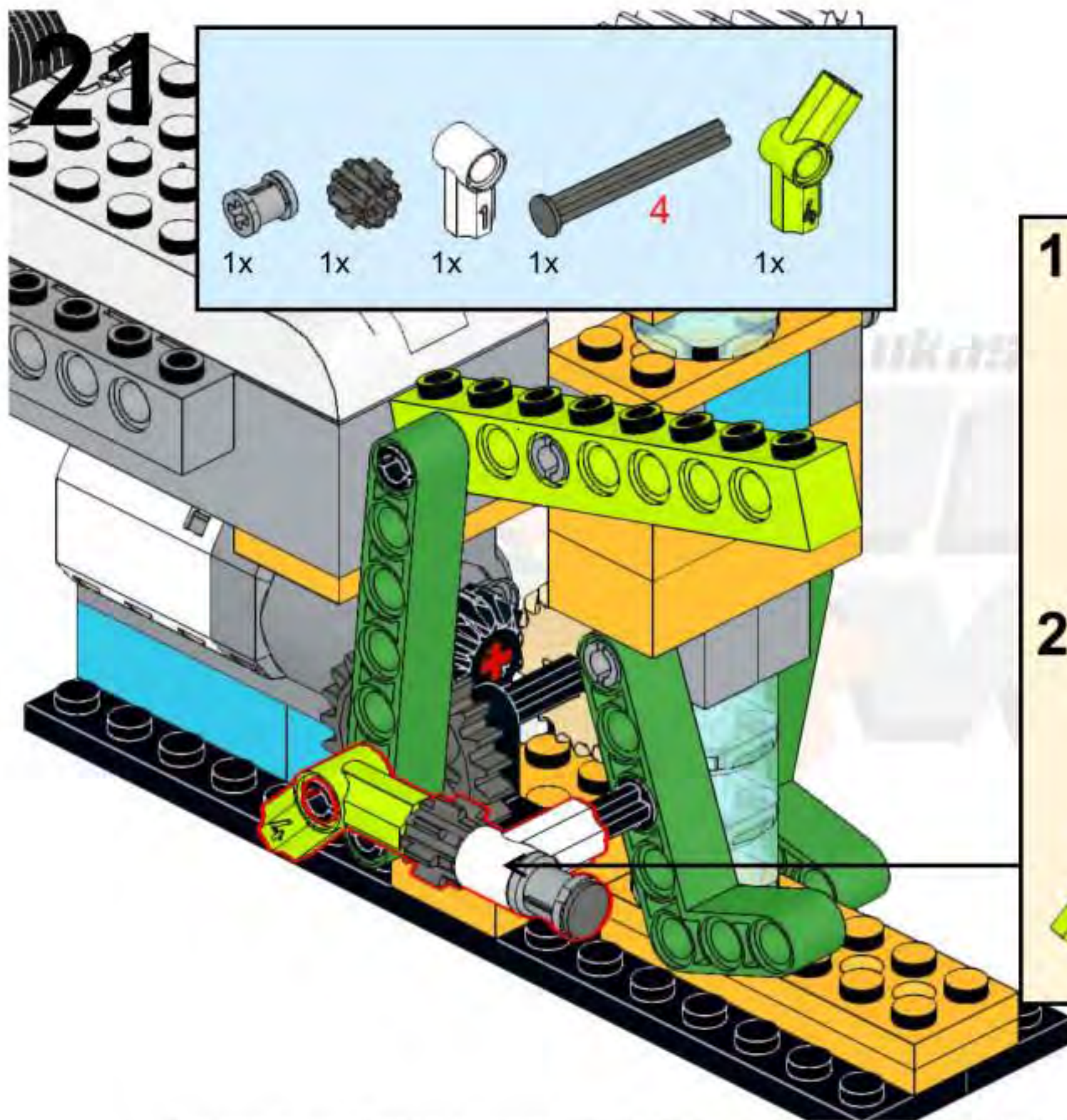


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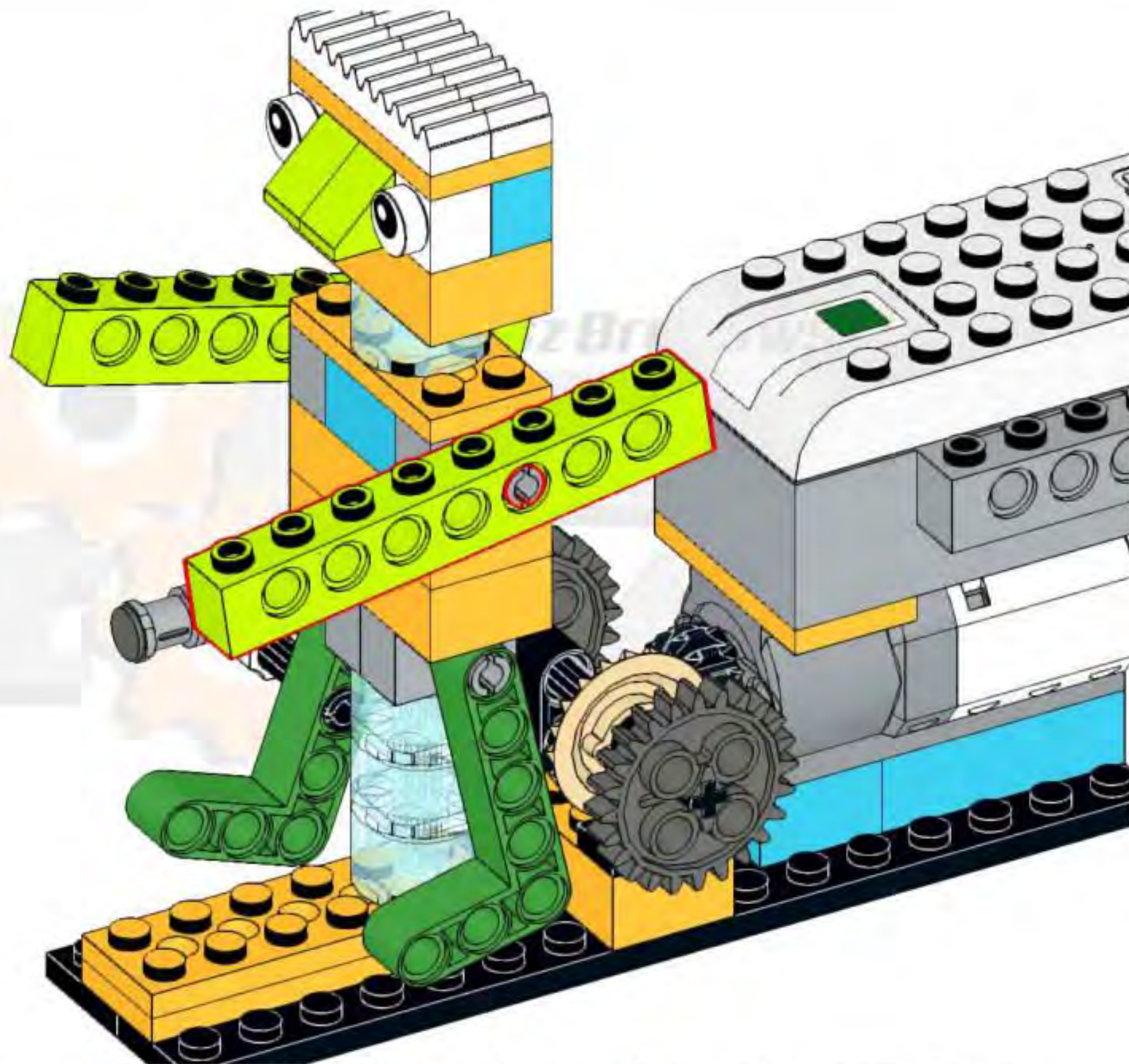
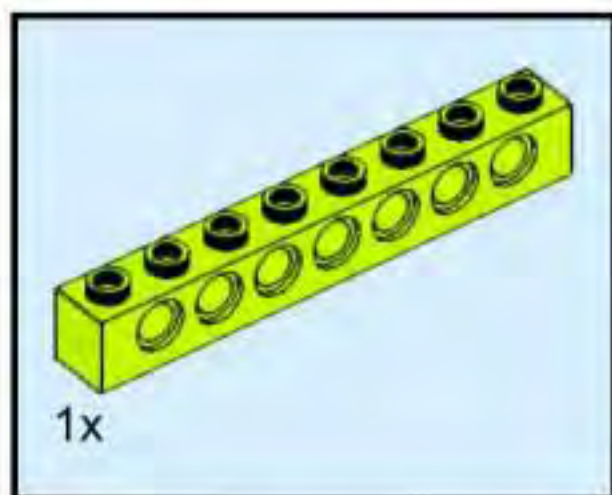
This diagram illustrates the assembly of a LEGO robot's lower body. A green Technic beam (1x7) is being attached to a grey motor housing. The beam is connected to a black axle that runs through a large gear. The entire assembly is mounted on a yellow base plate. An inset shows the required parts: two black pins (labeled '2x') and one green beam (labeled '1x'). Red arrows indicate the placement of the pins to secure the beam.

20

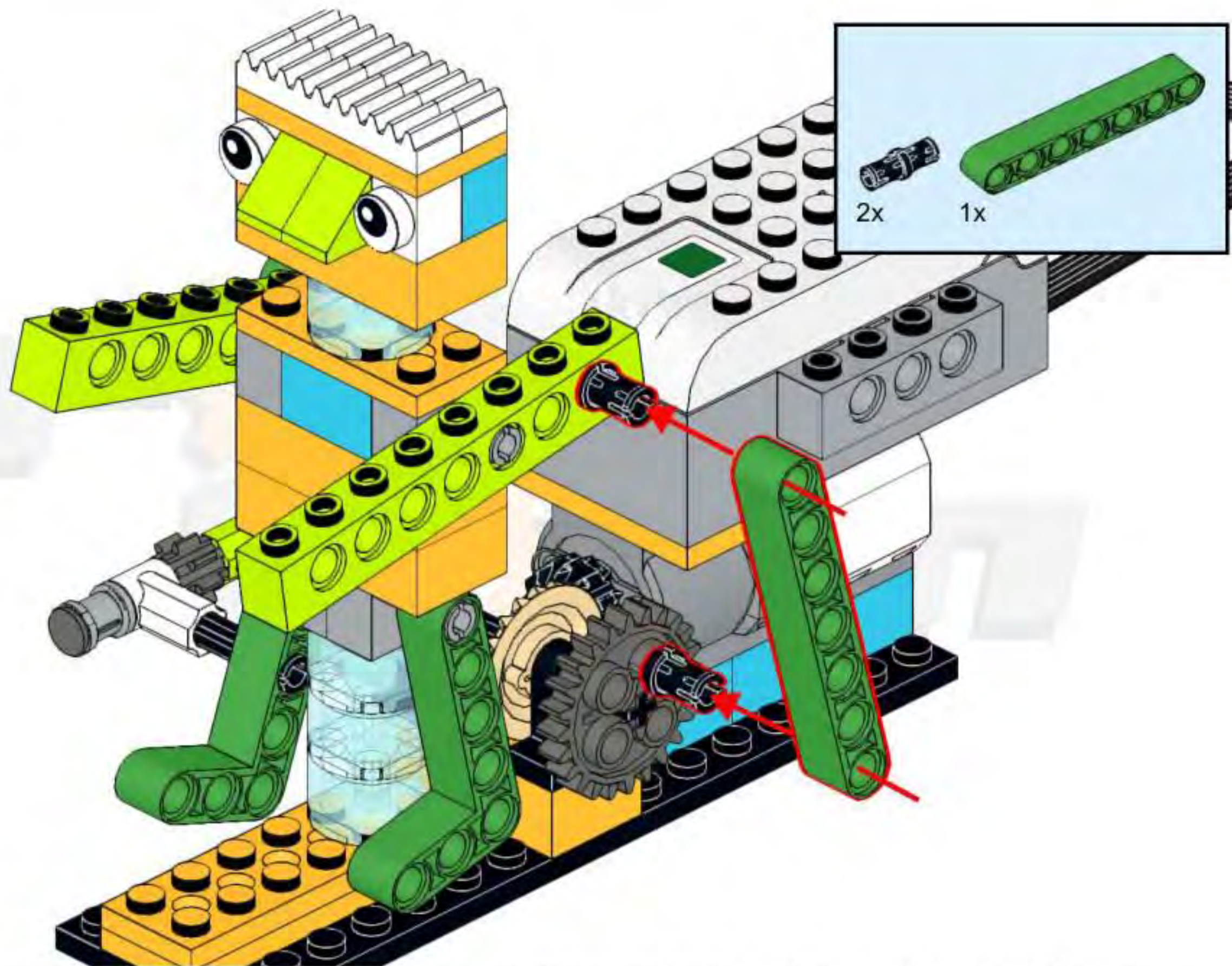




22

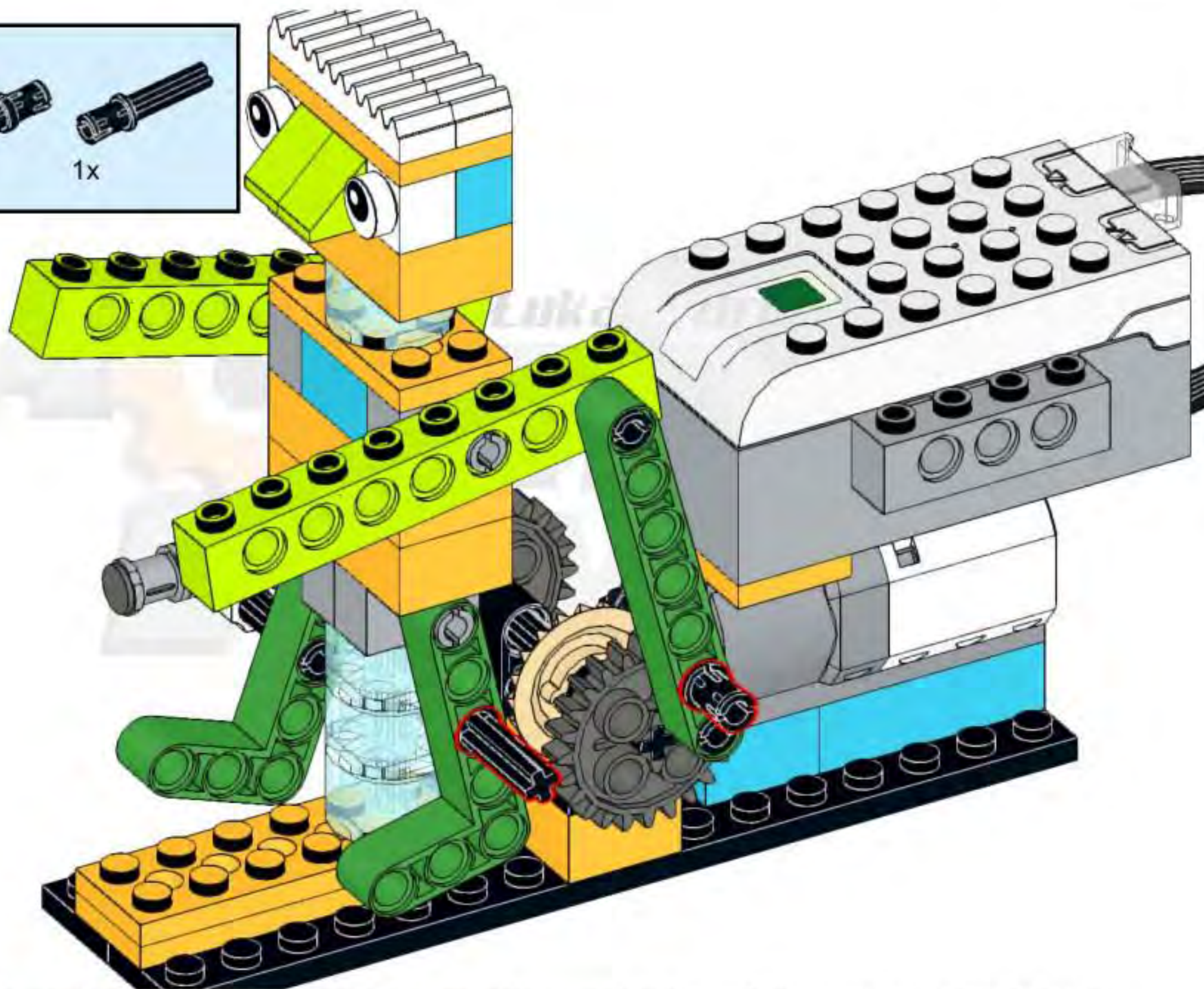
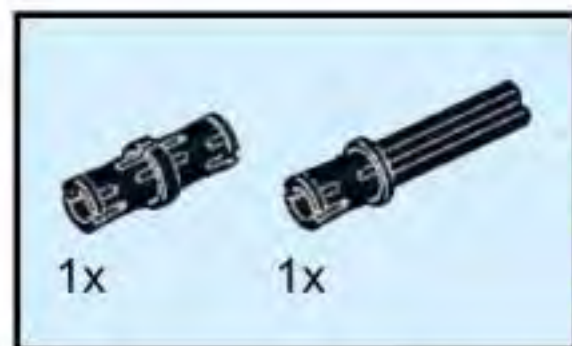


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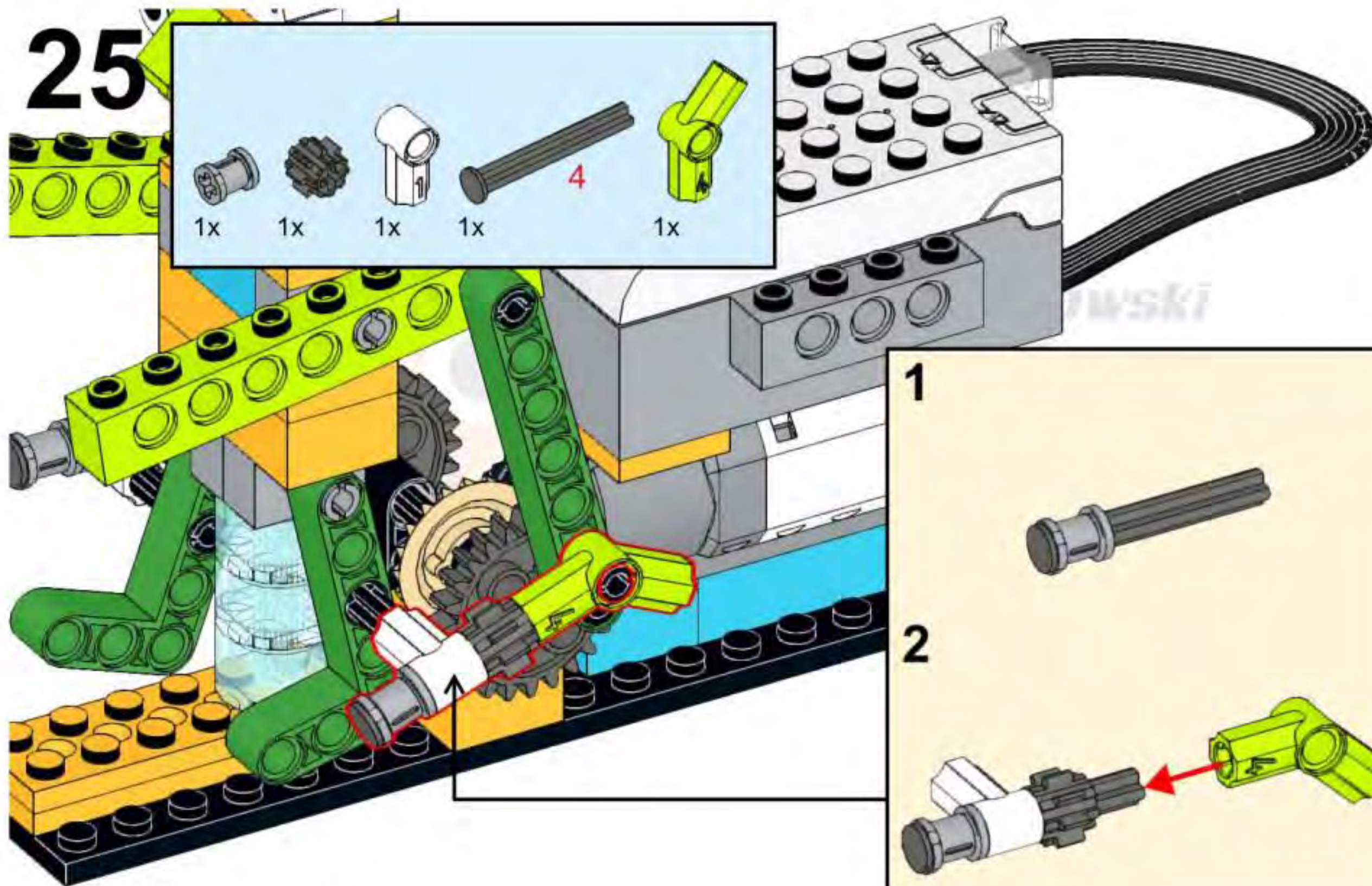
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24

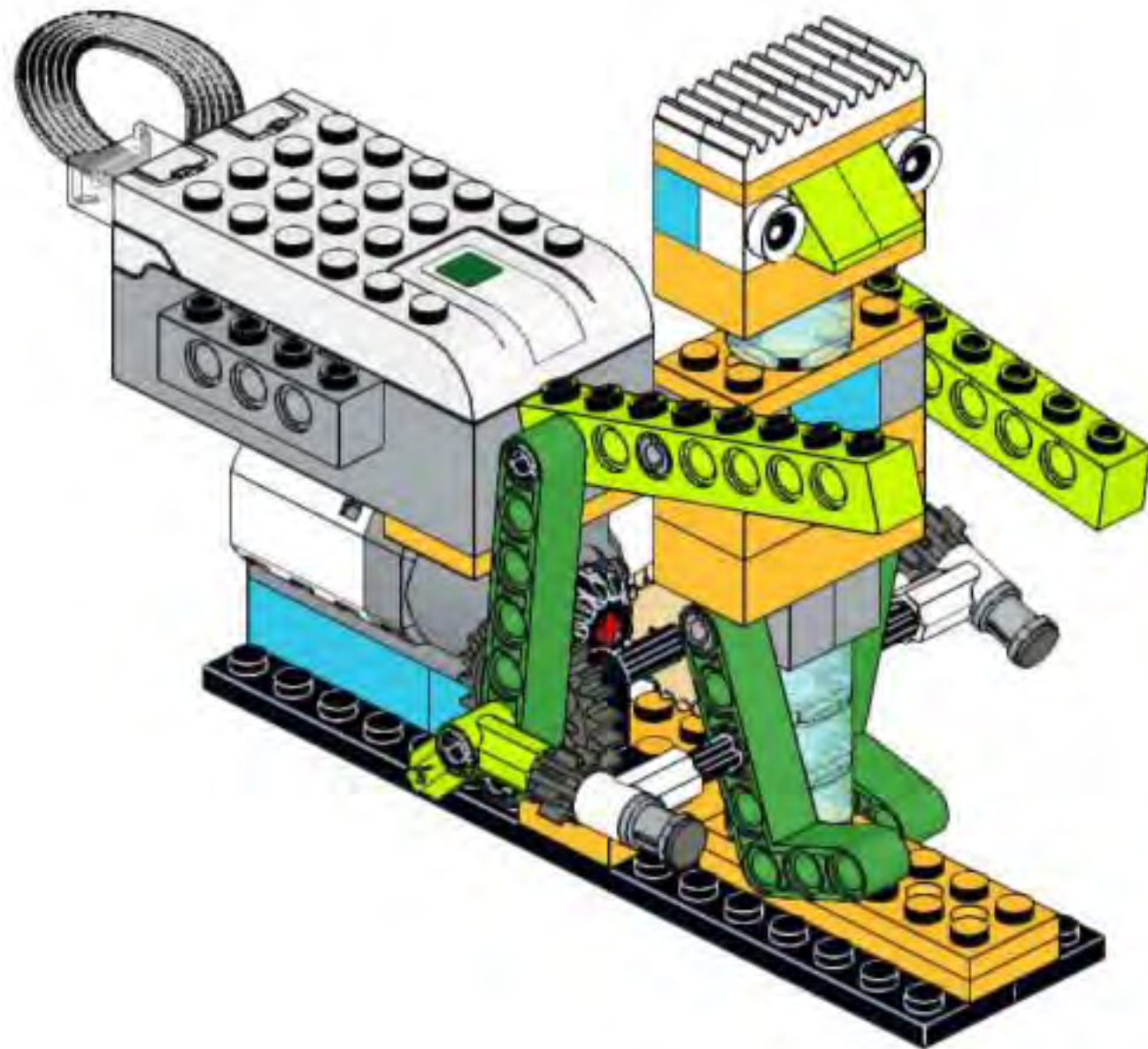


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25



26



Program

