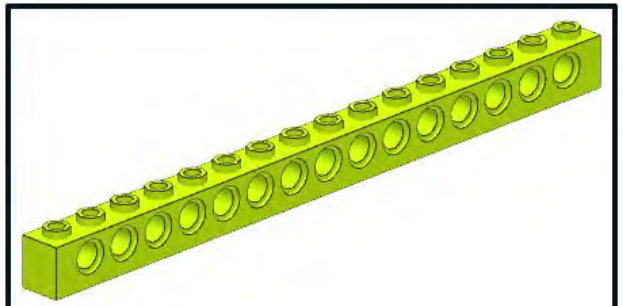
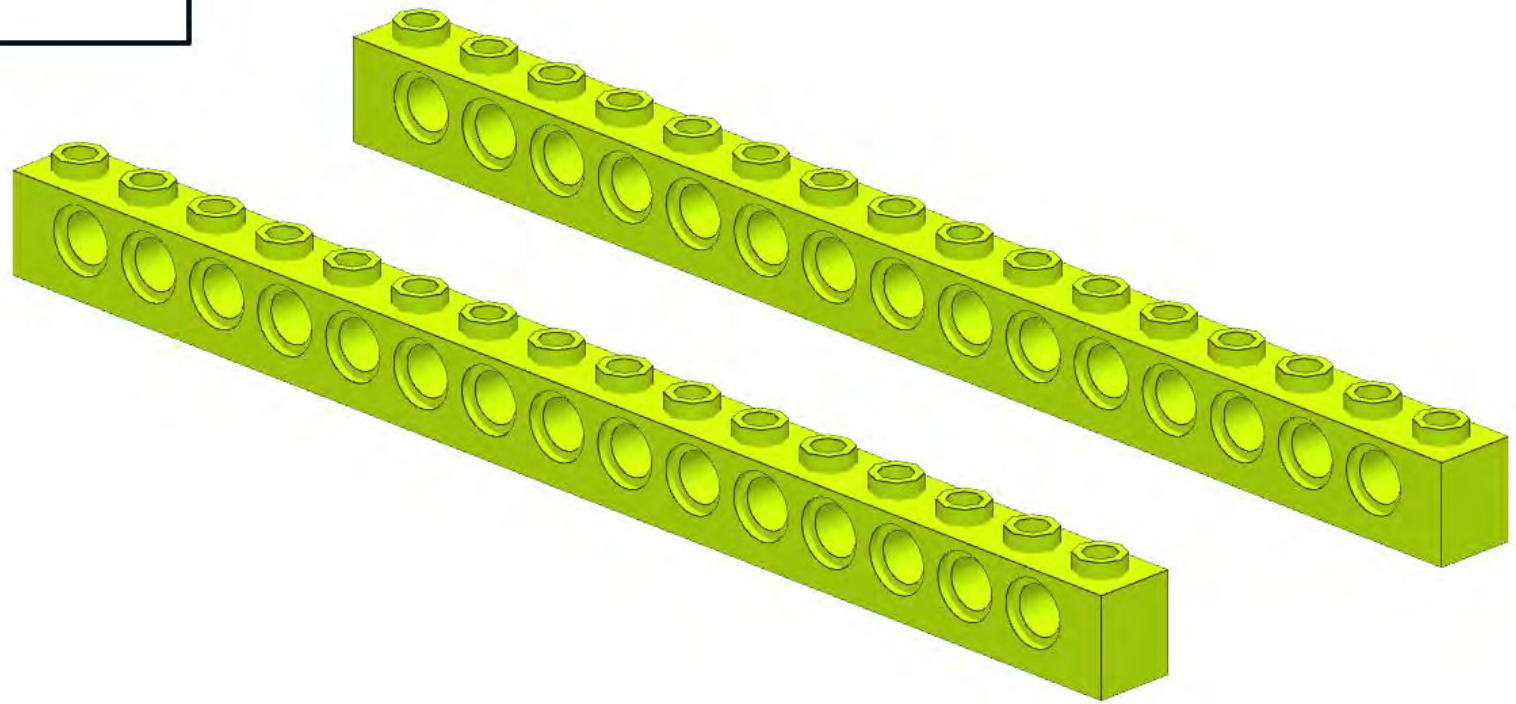
More buildings from Anger project
on https://play.google.com/store/apps/developer?id=AnGer+project

AnGer project

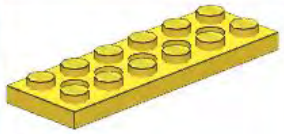
1



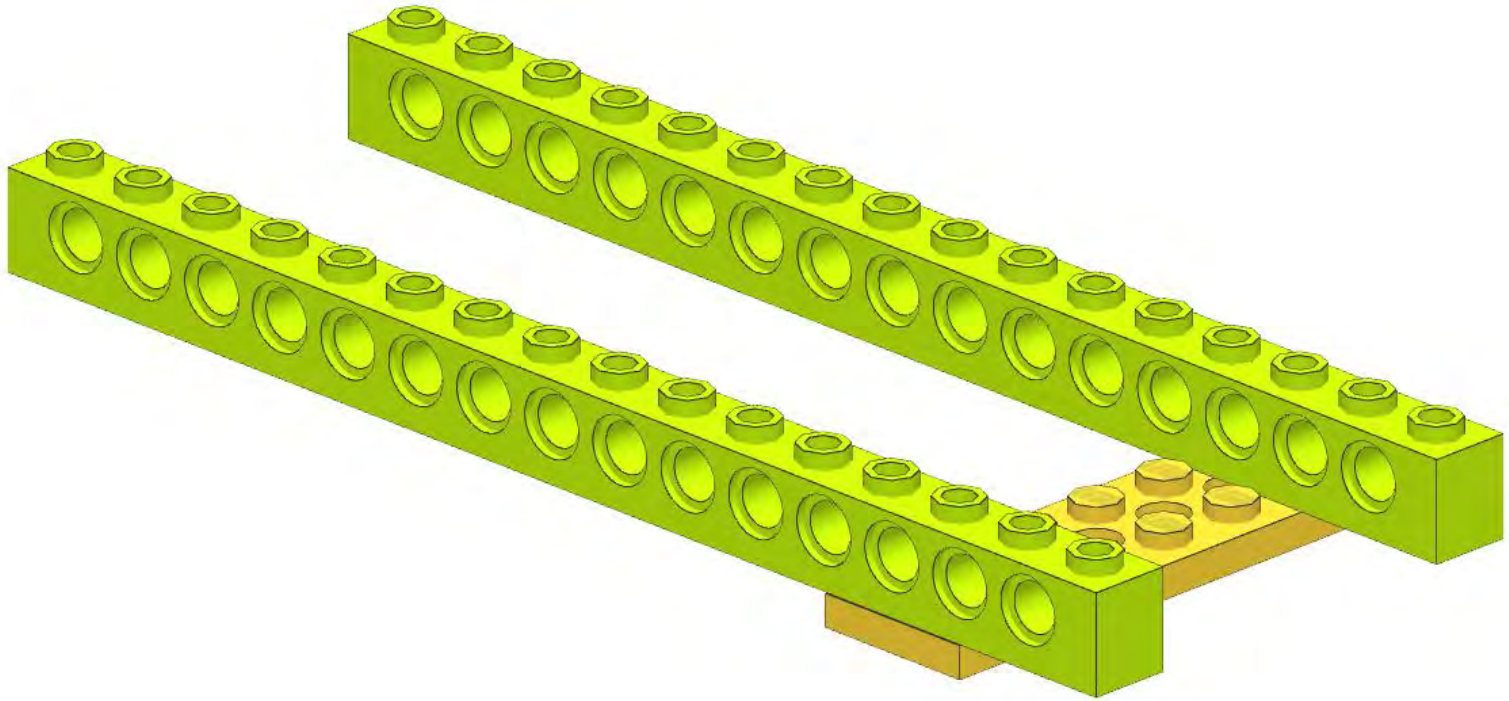
2x



2

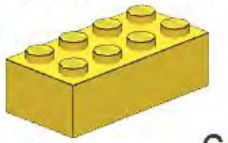


1x



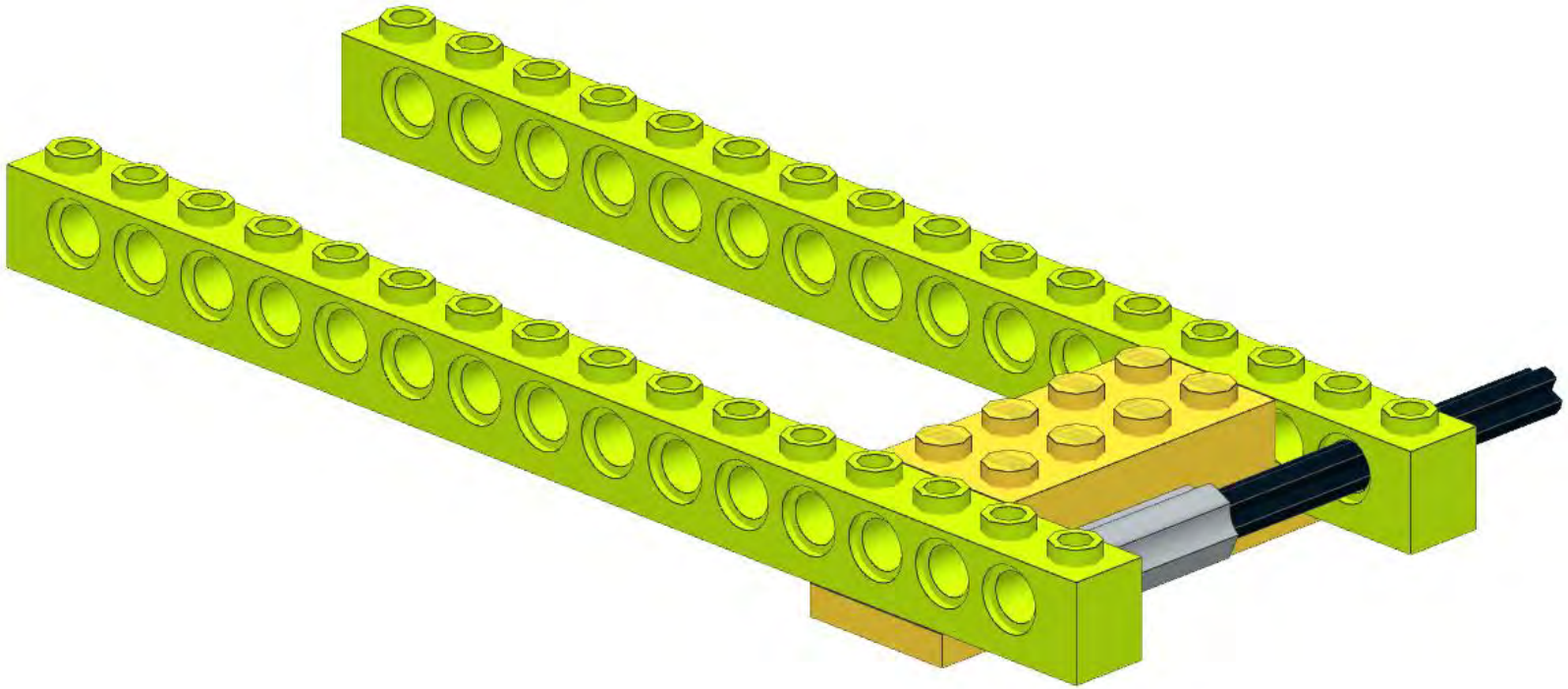
3

1x 2x4

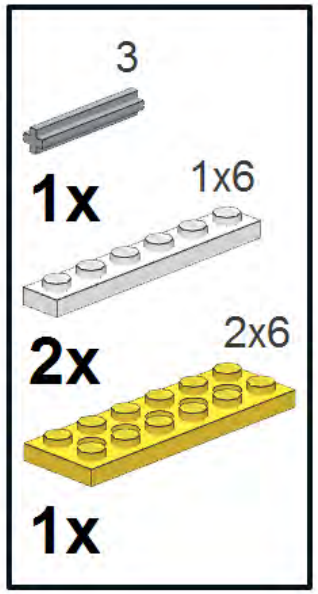


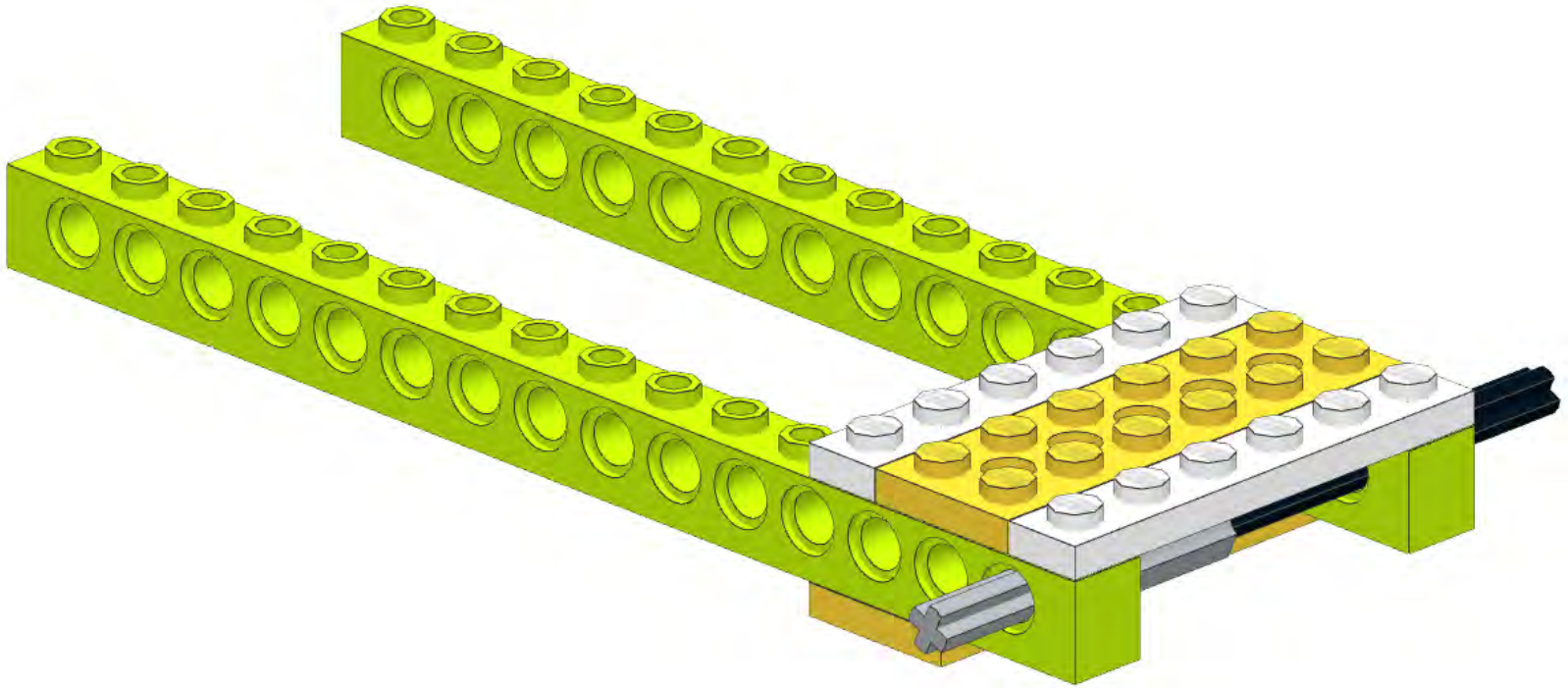
1x 6

1x

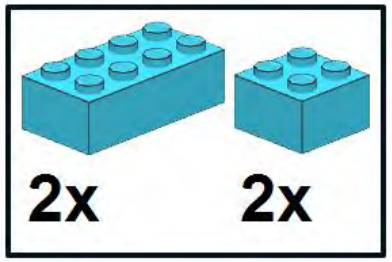


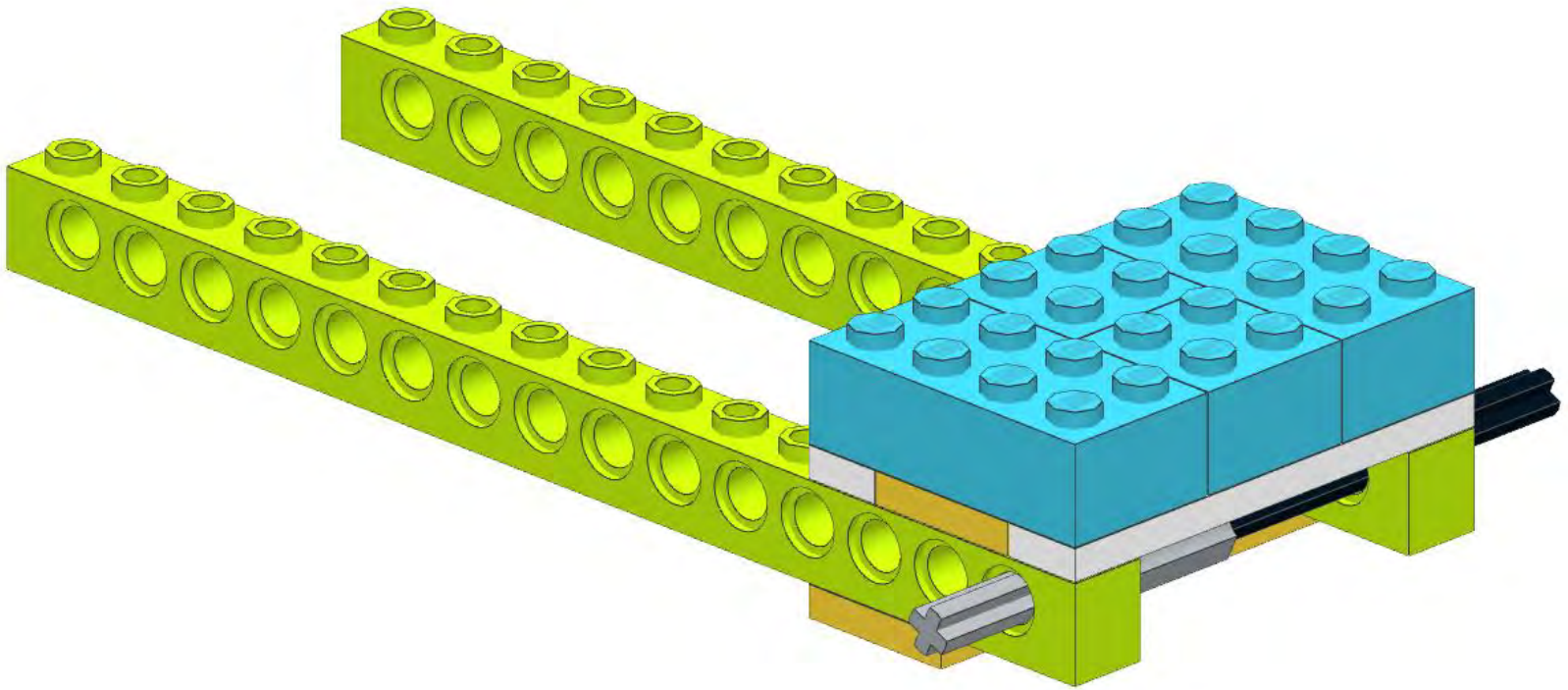
4



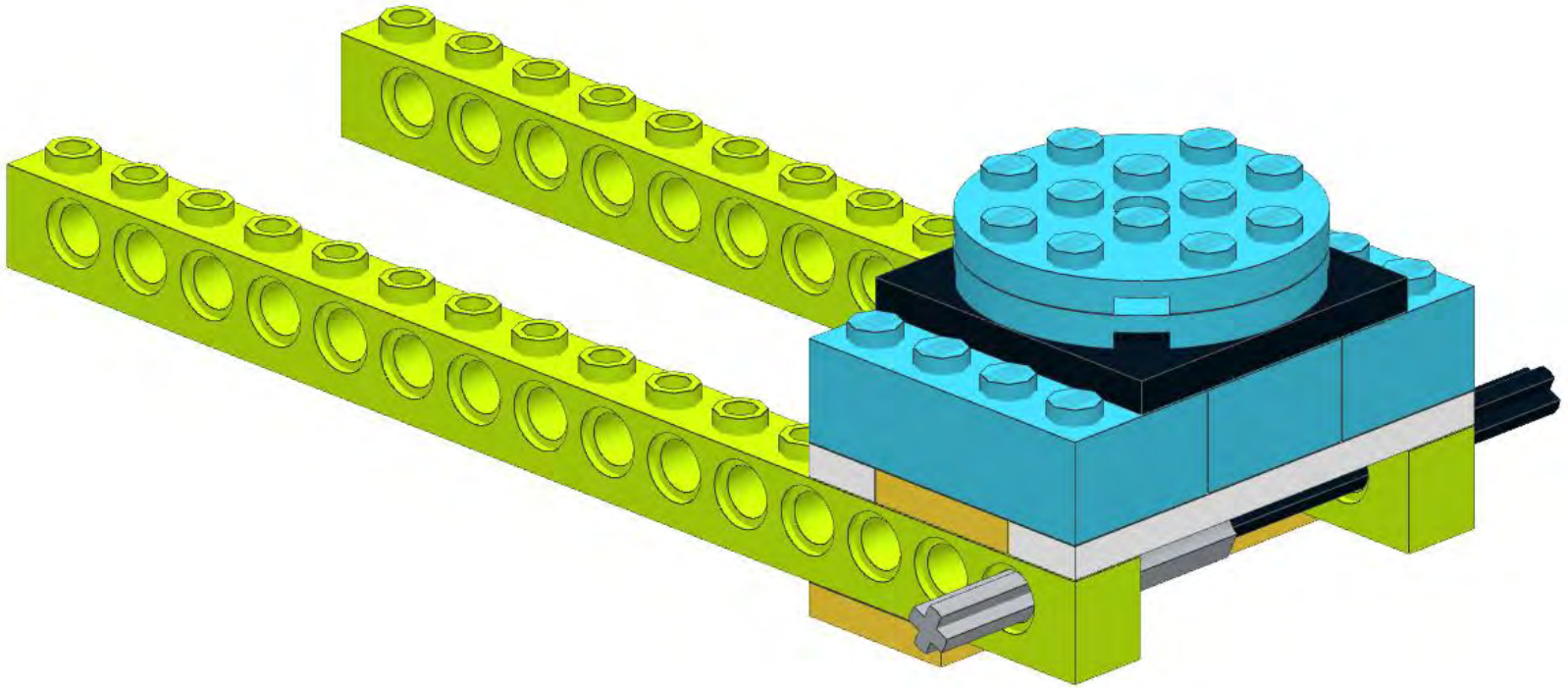


5

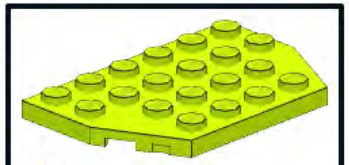




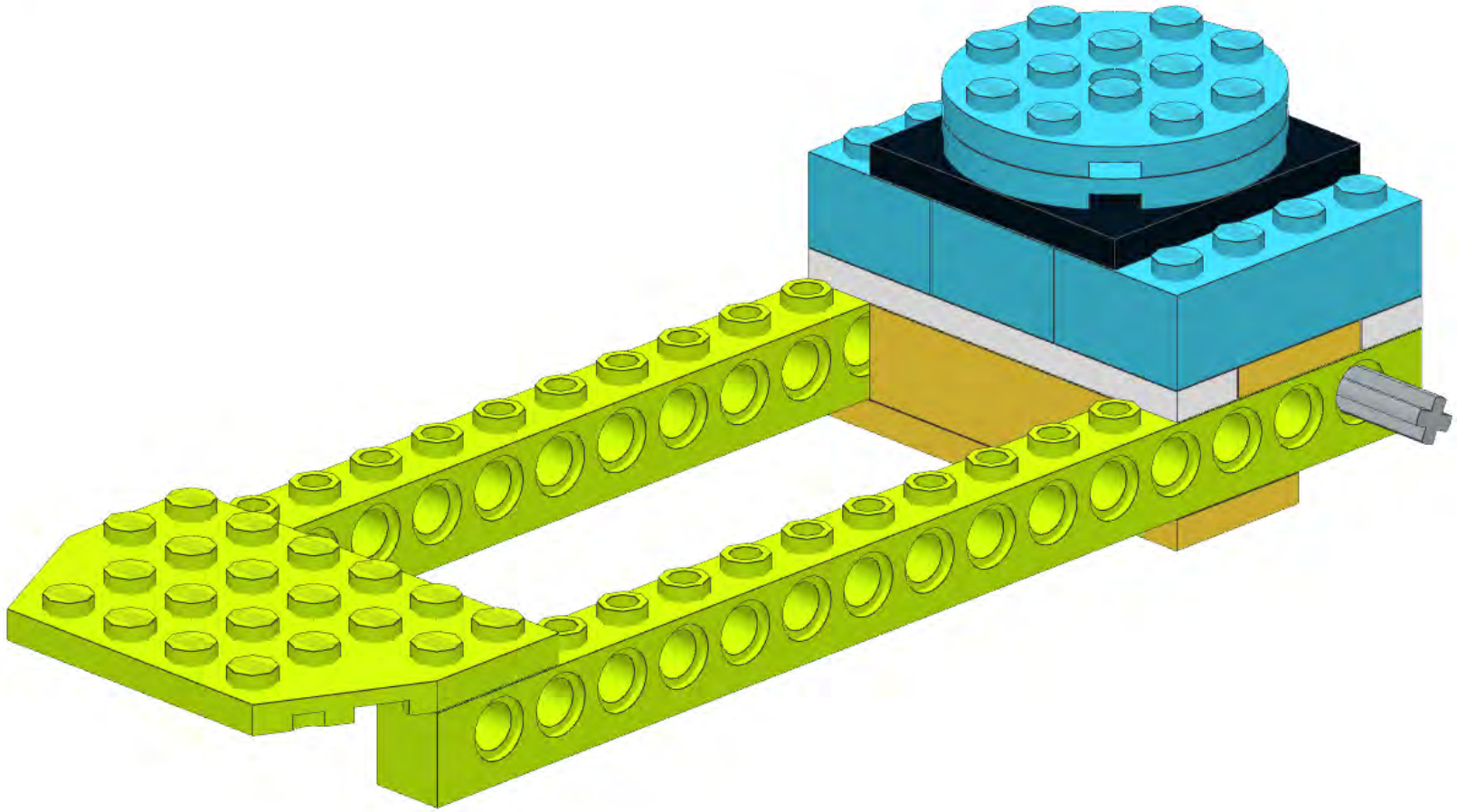
6



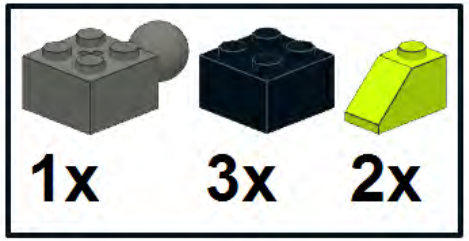
7

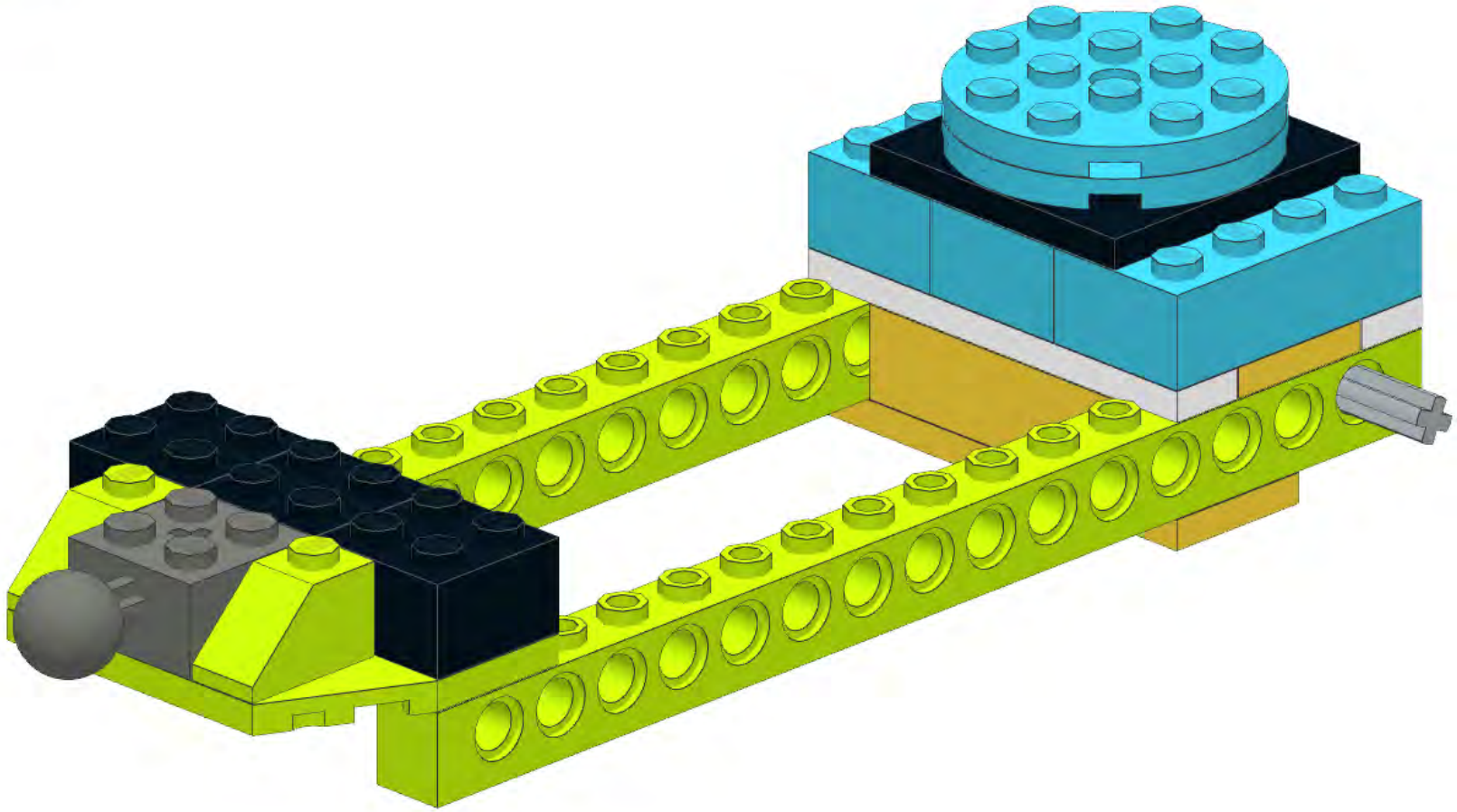


1x



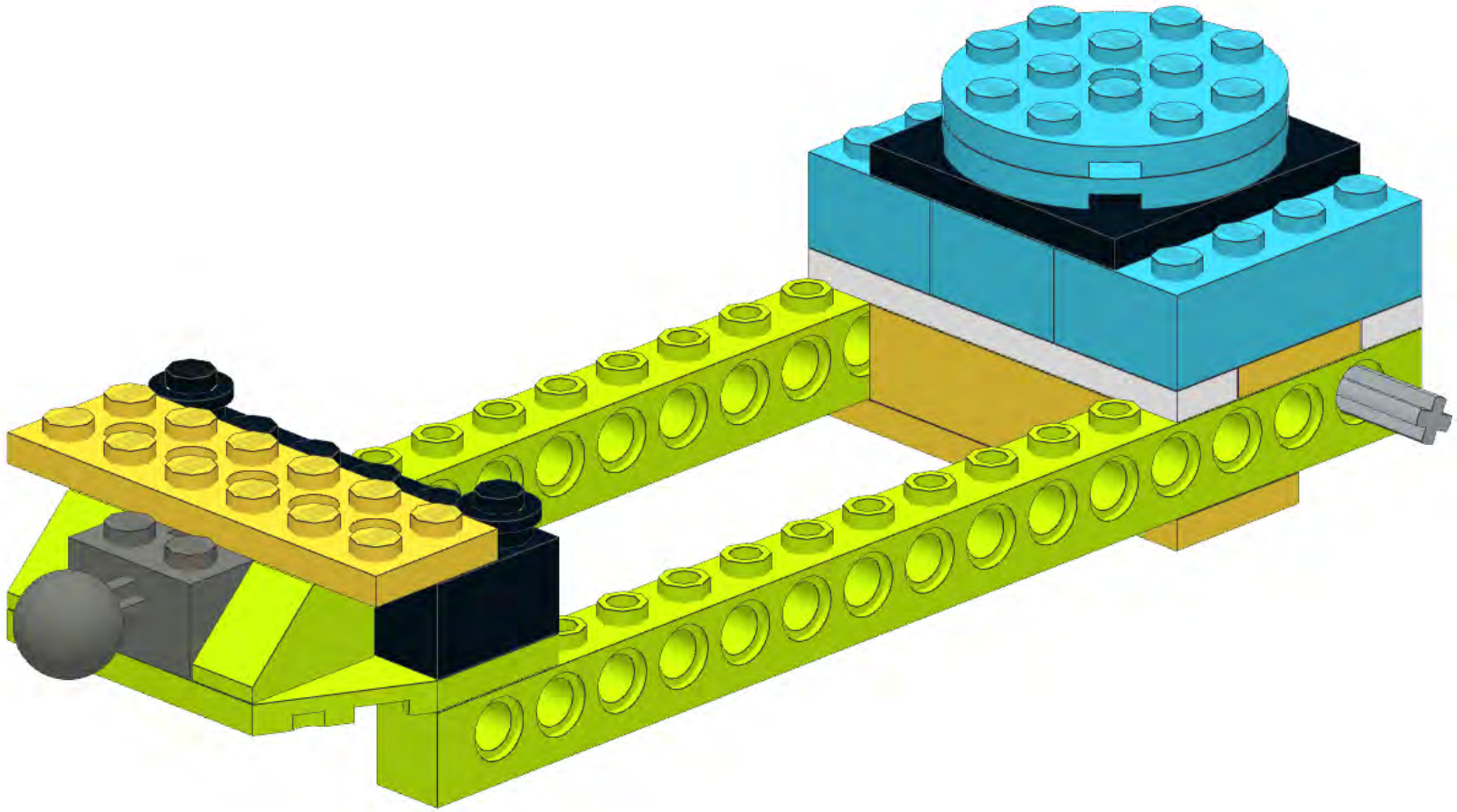
8



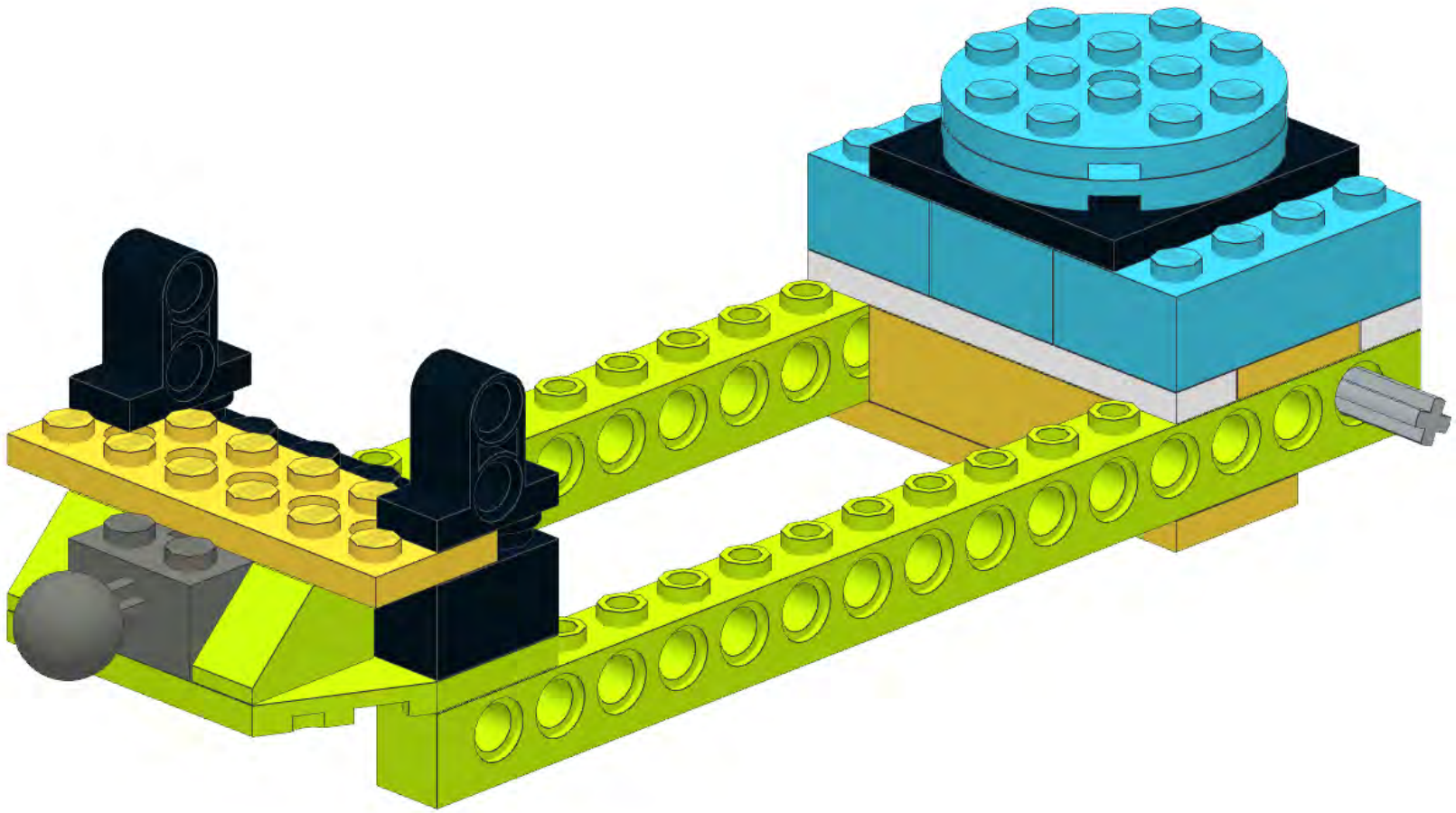


9

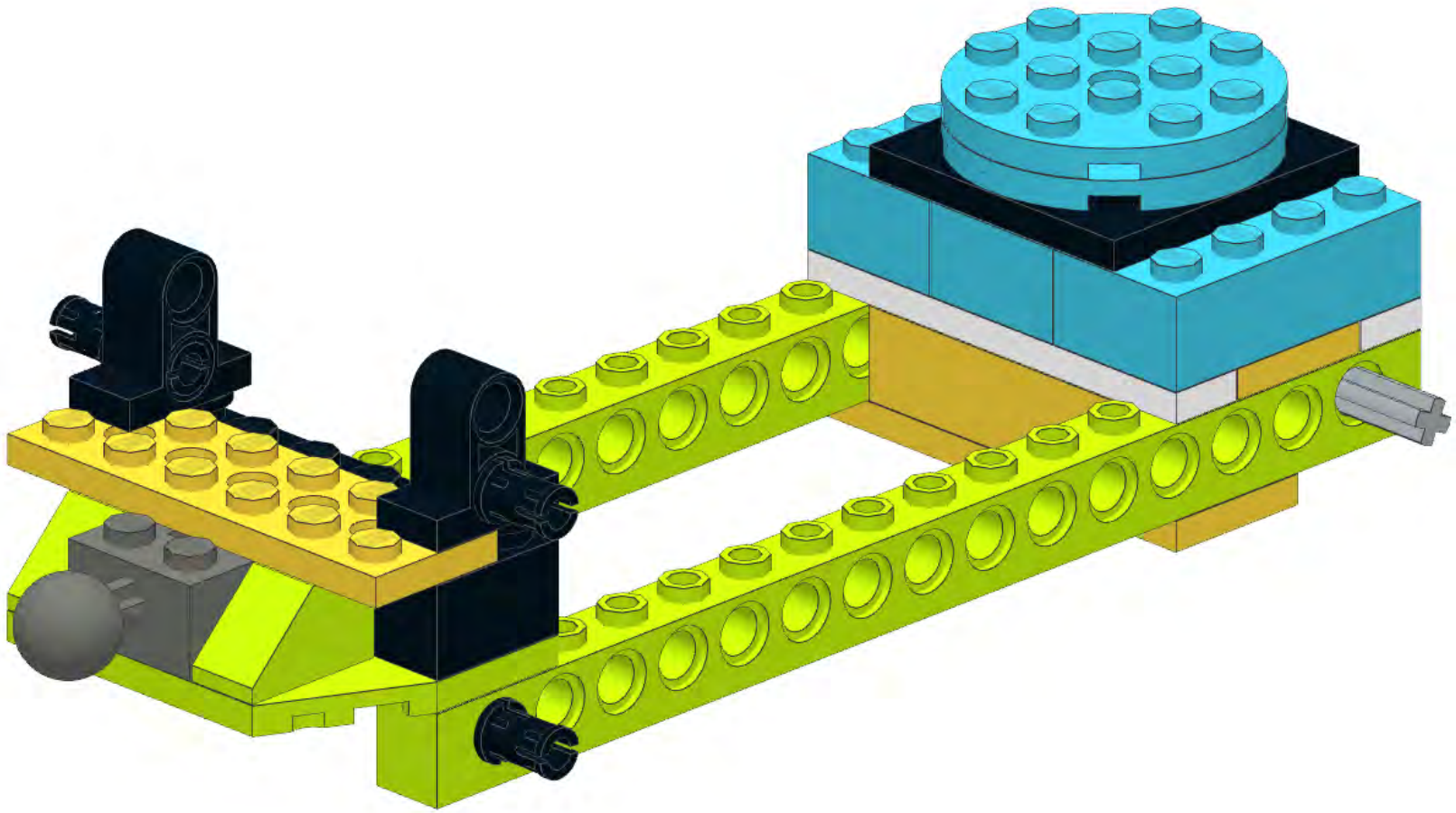
1x 2x



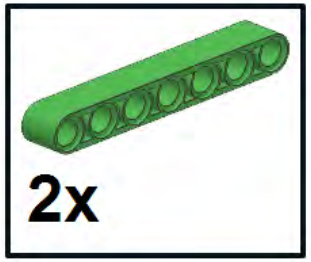
10

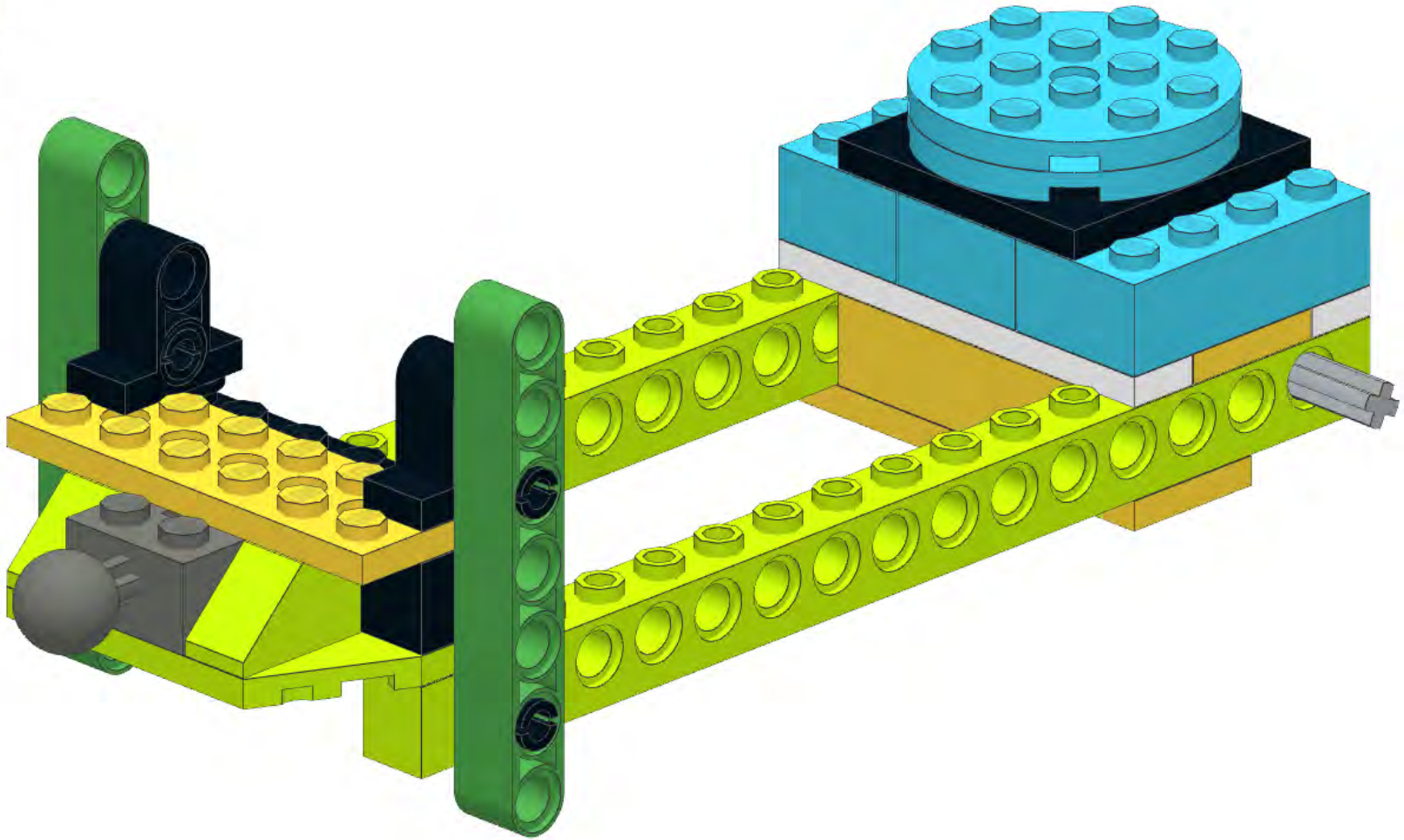


11

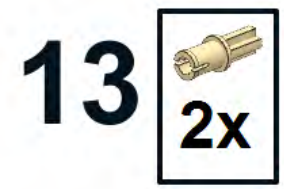


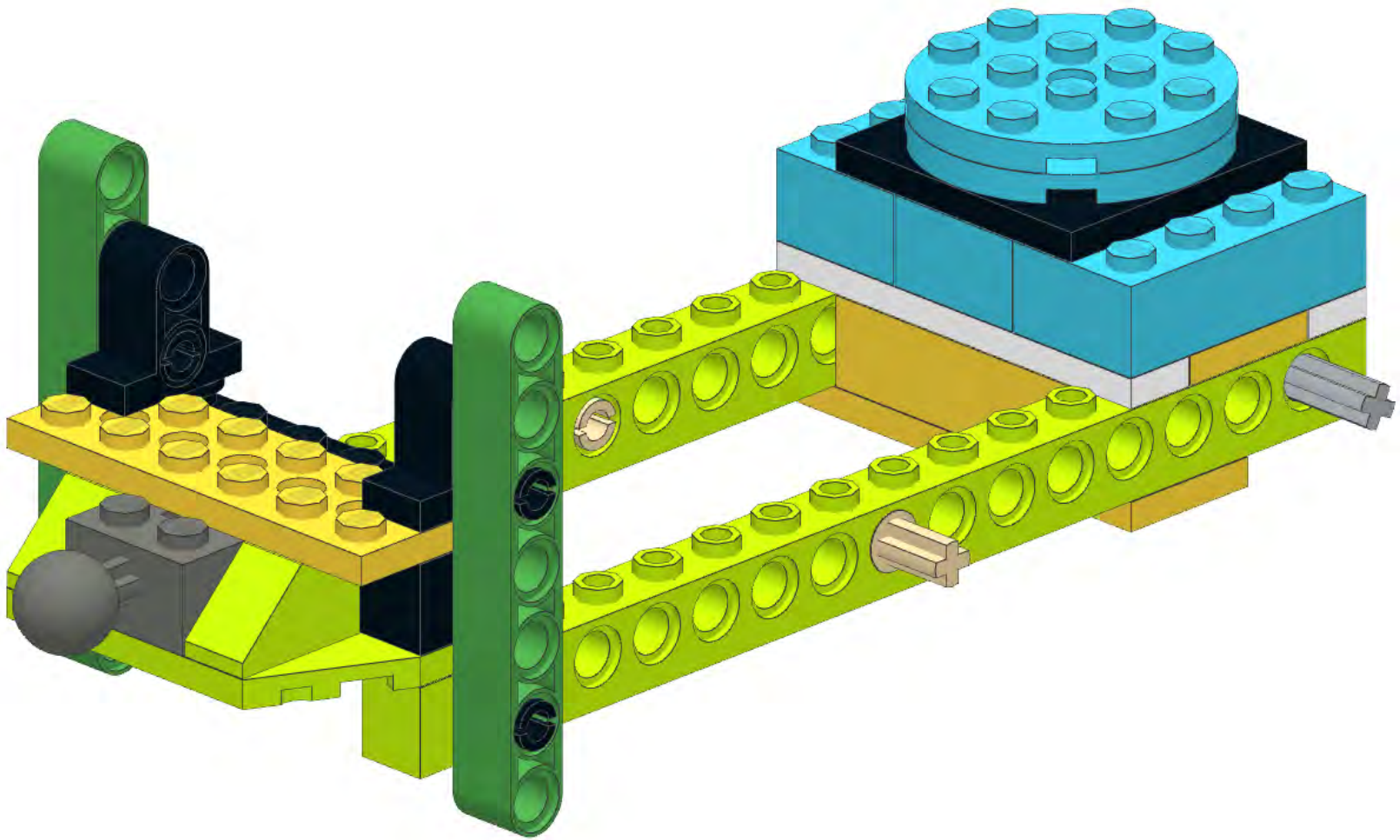
12



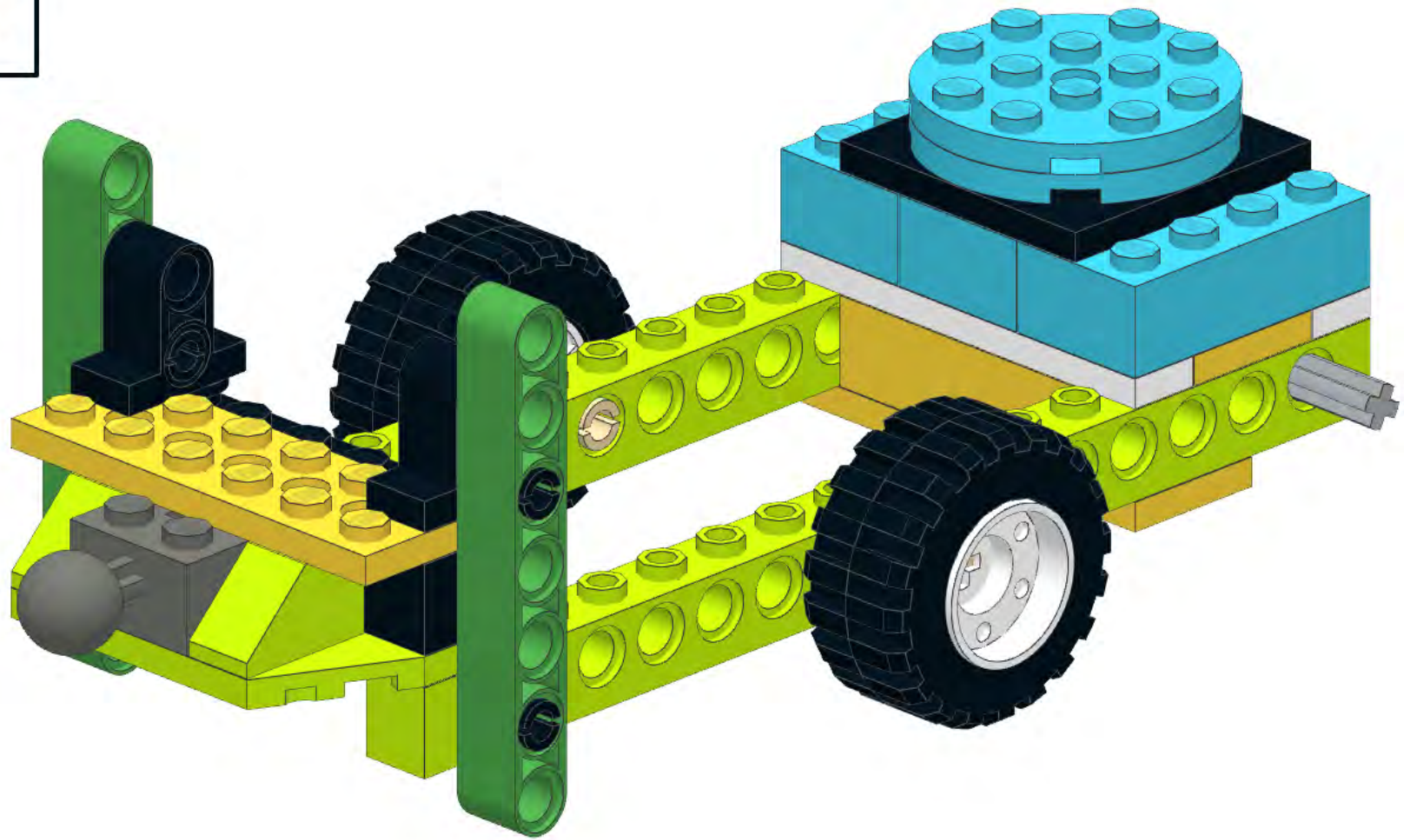


13

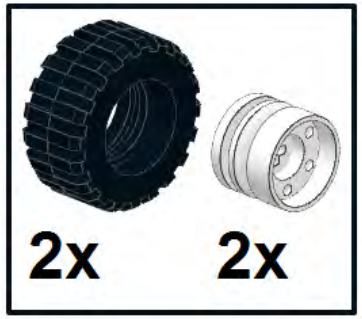


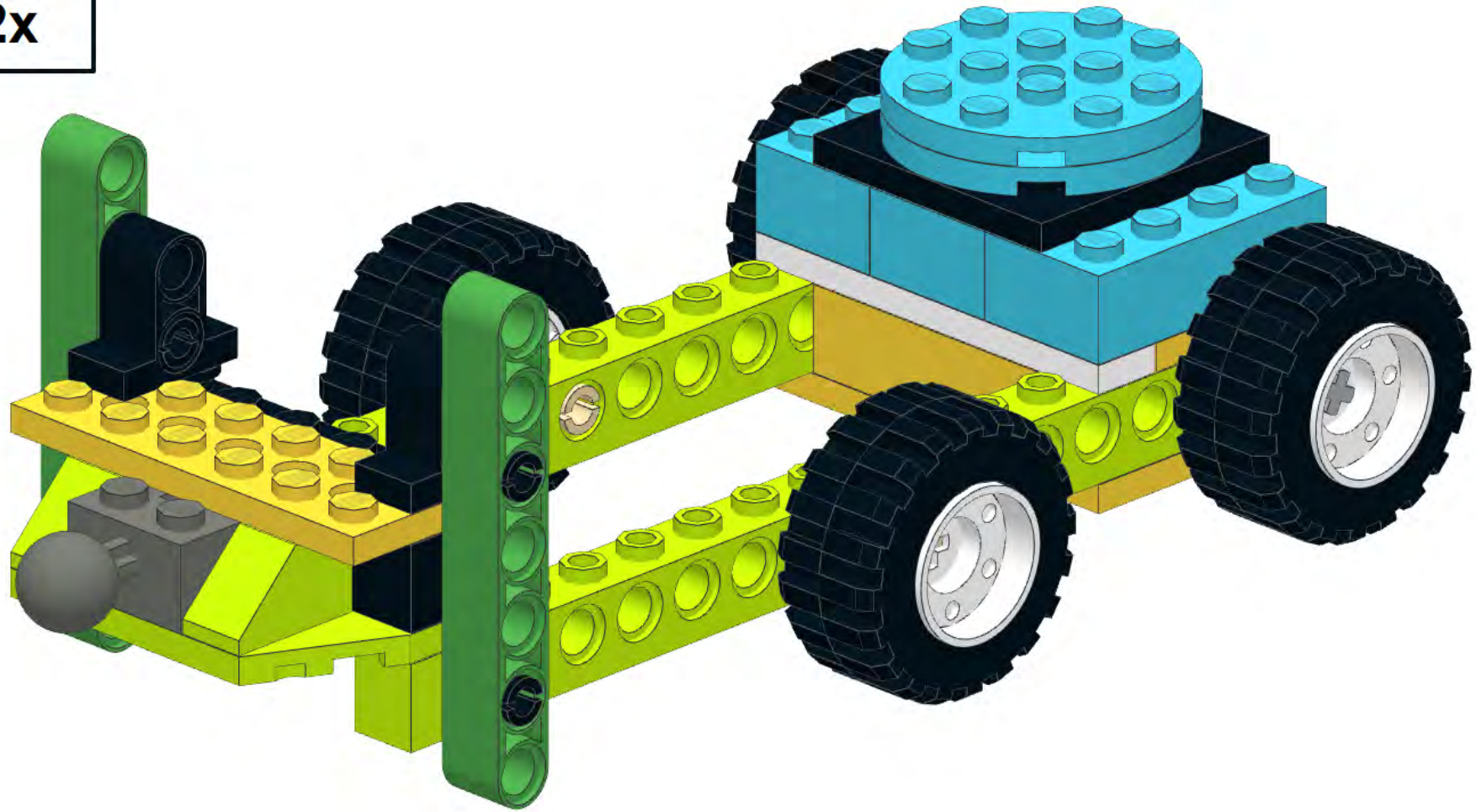


14

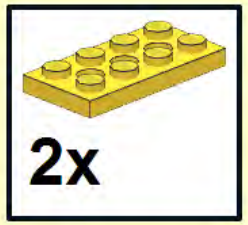


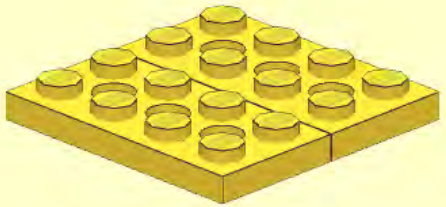
15



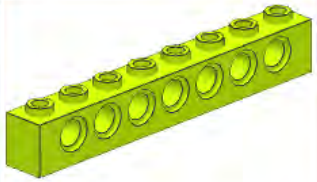


1

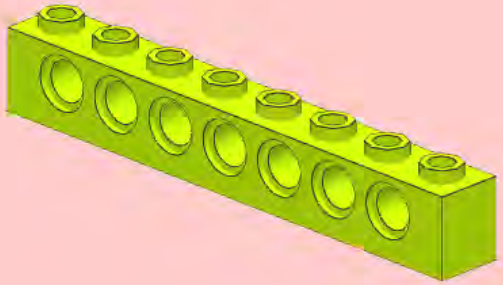




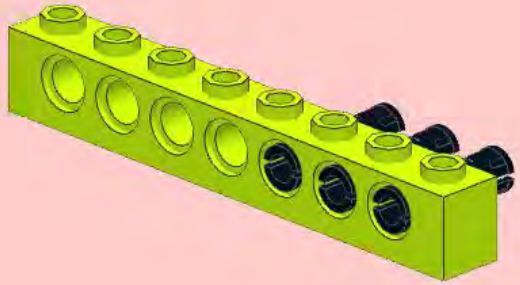
1



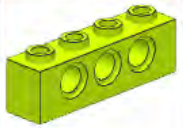
1x



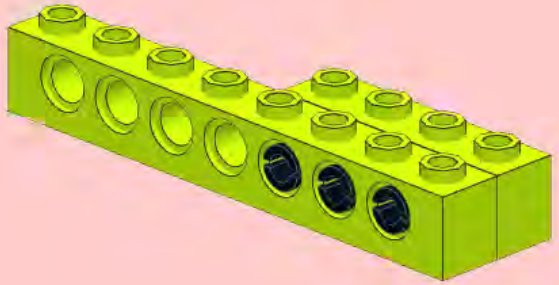
2



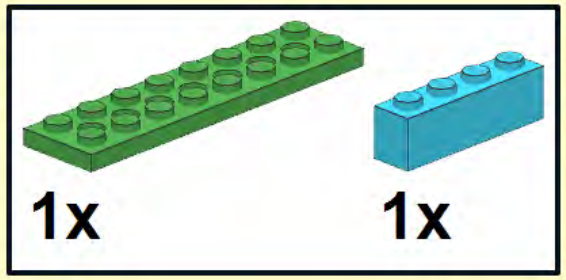
3

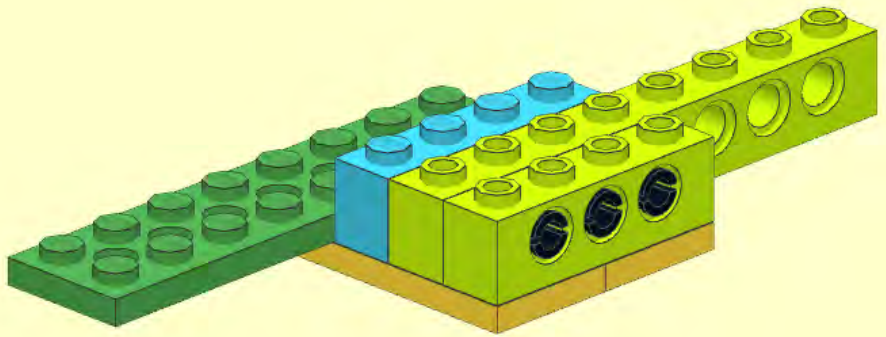


1x

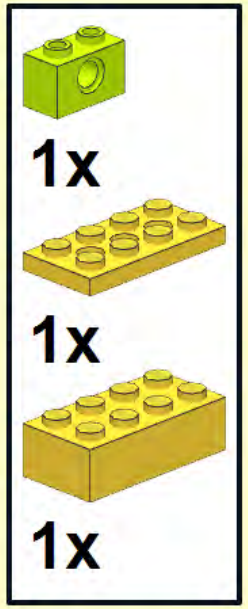


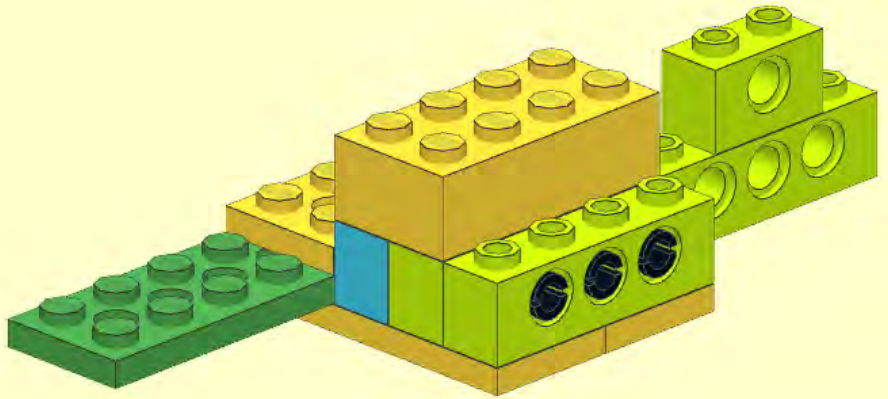
2





3



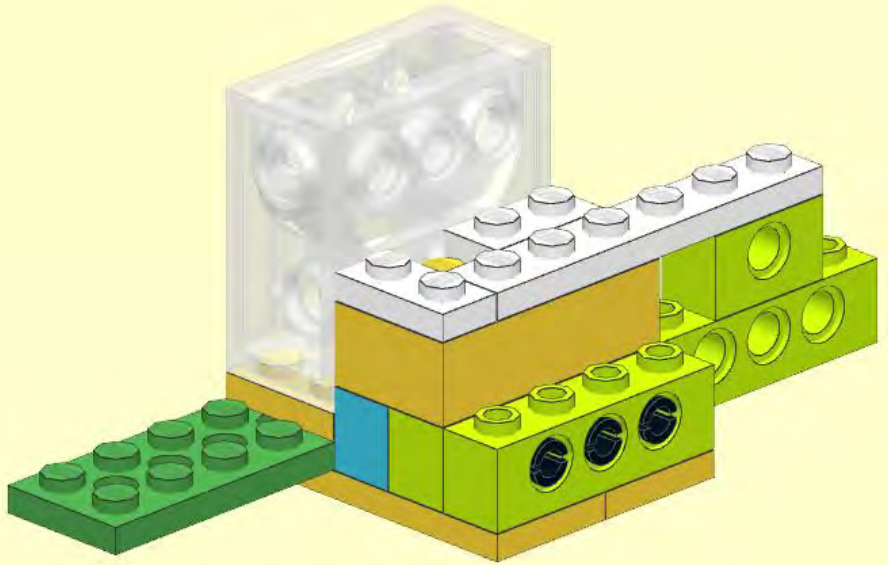


4

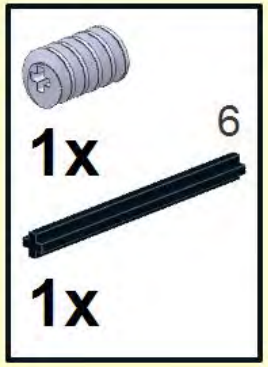
2x

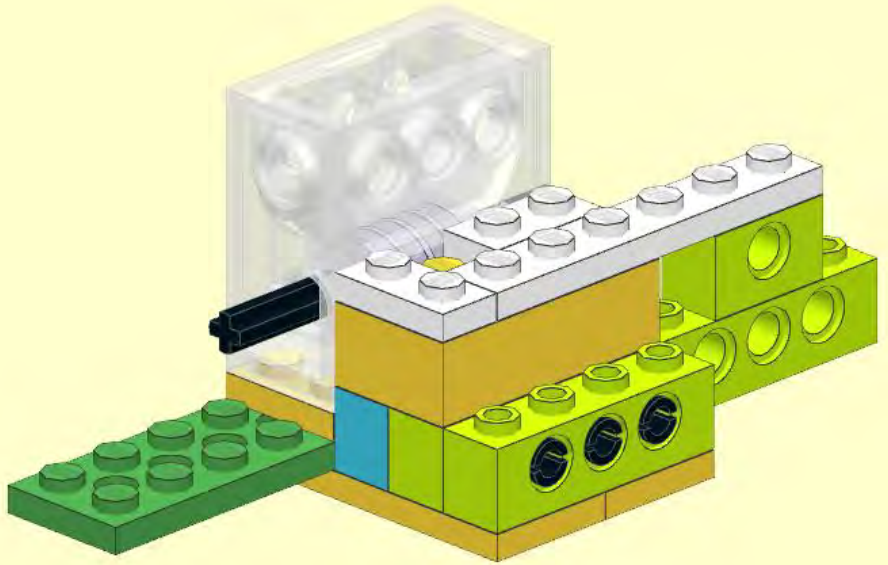
1x

1x

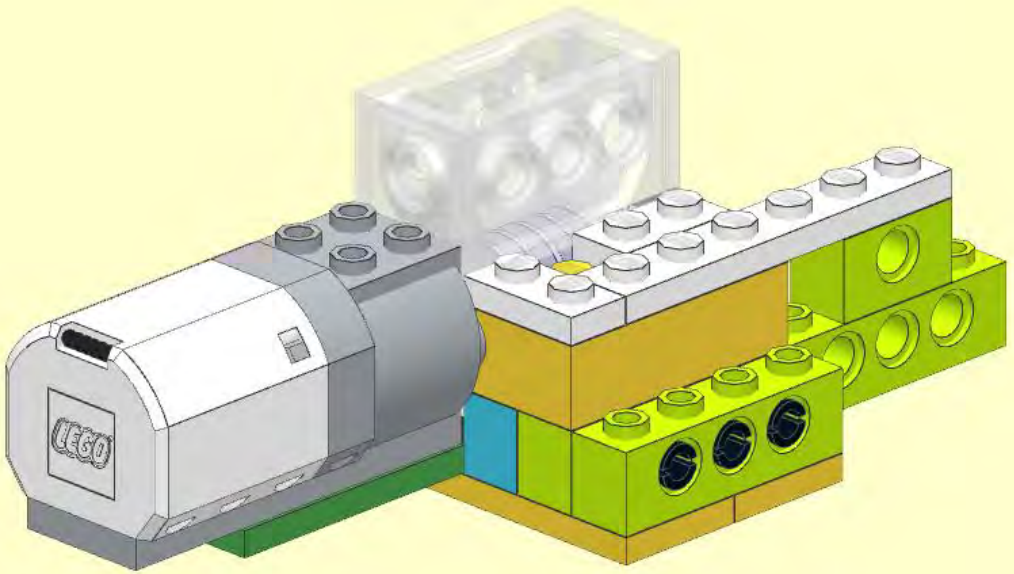


5

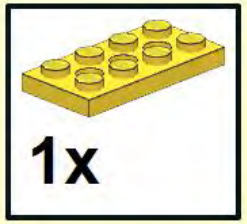


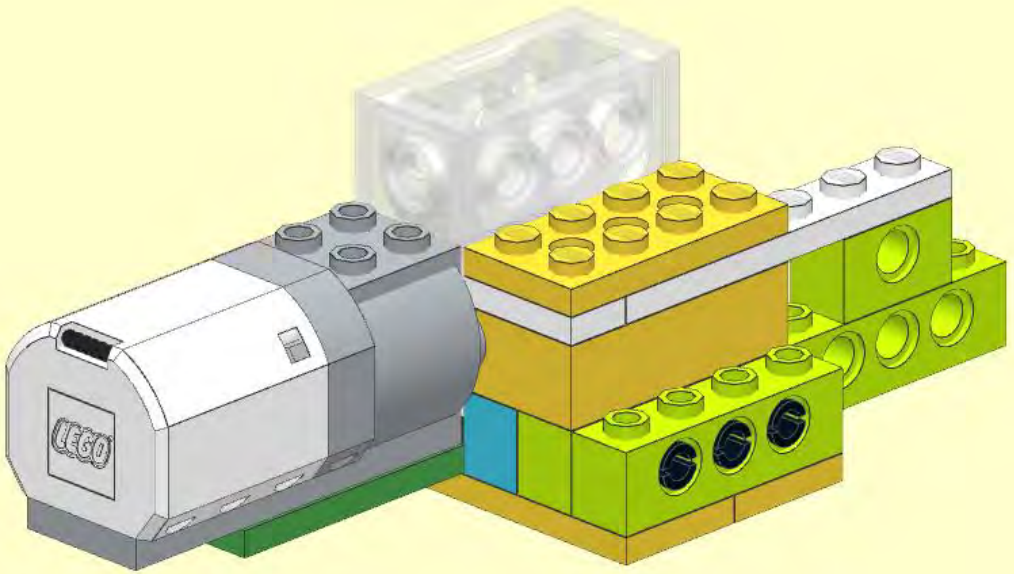


6

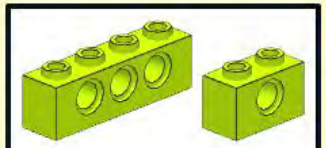


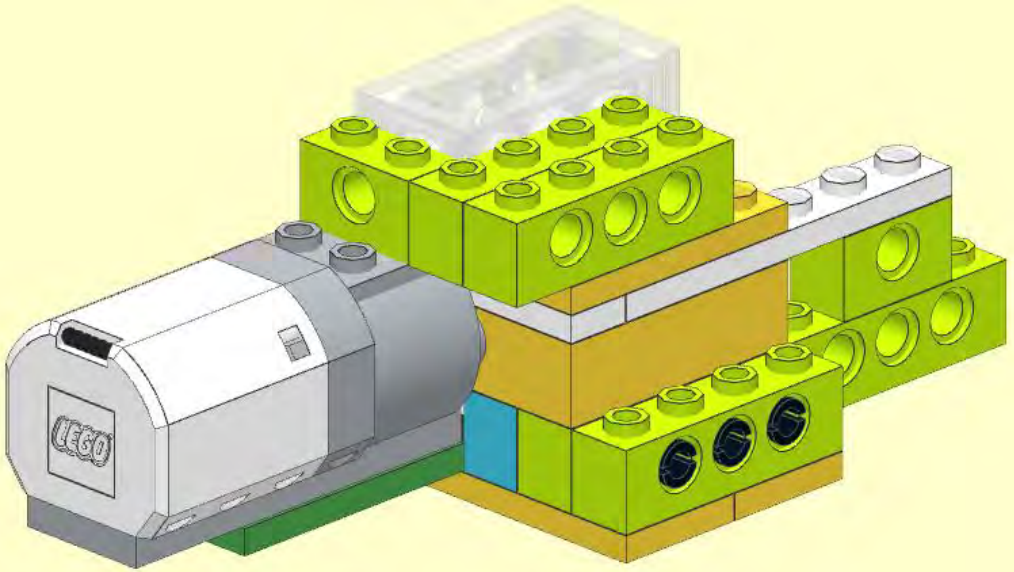
7



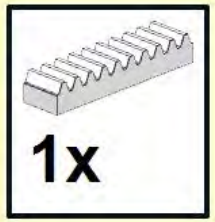


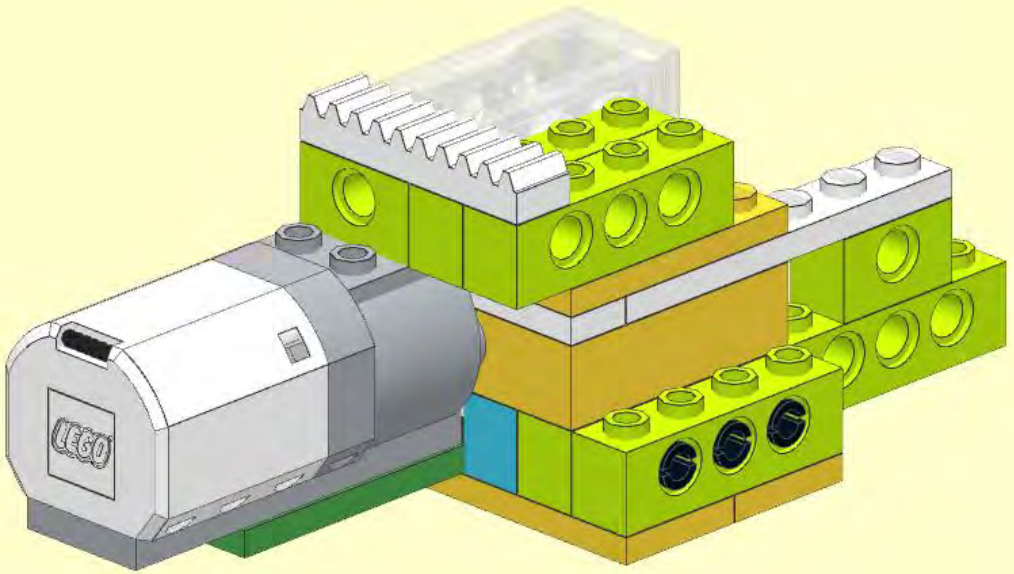
8



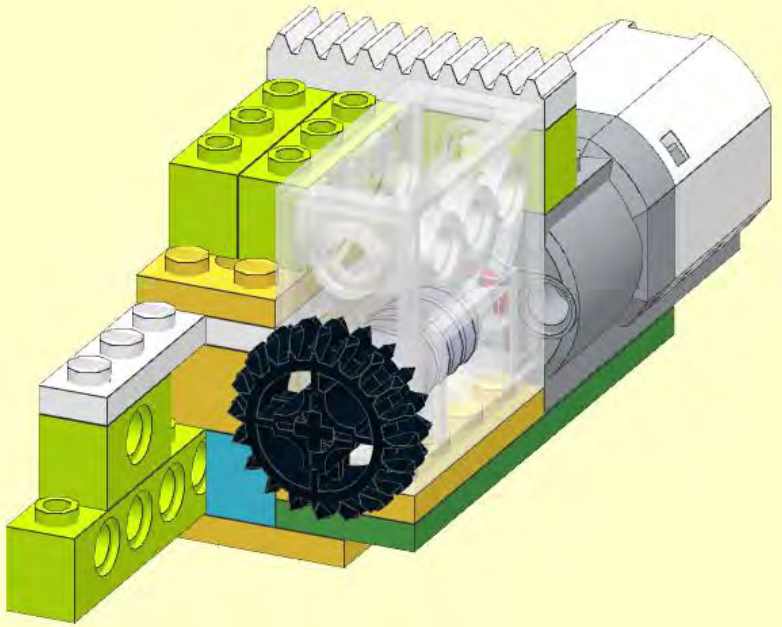


9

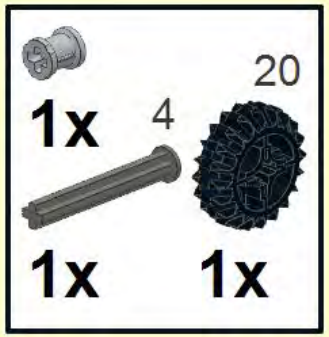


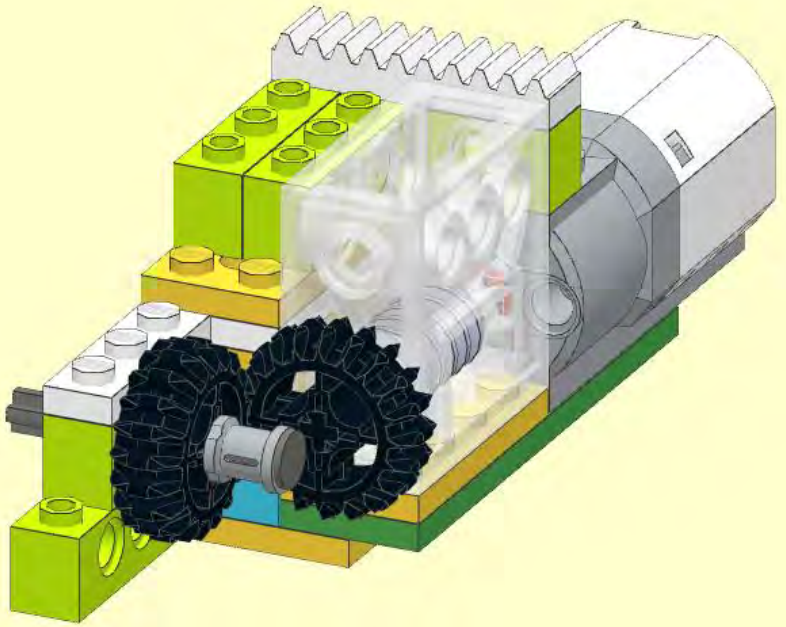


10

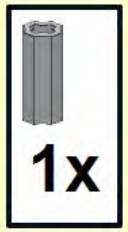


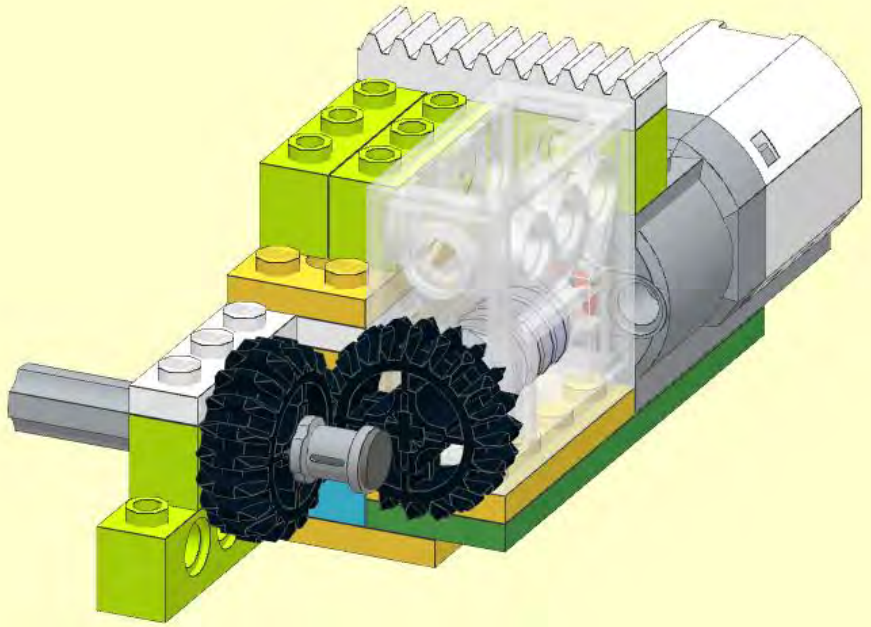
11



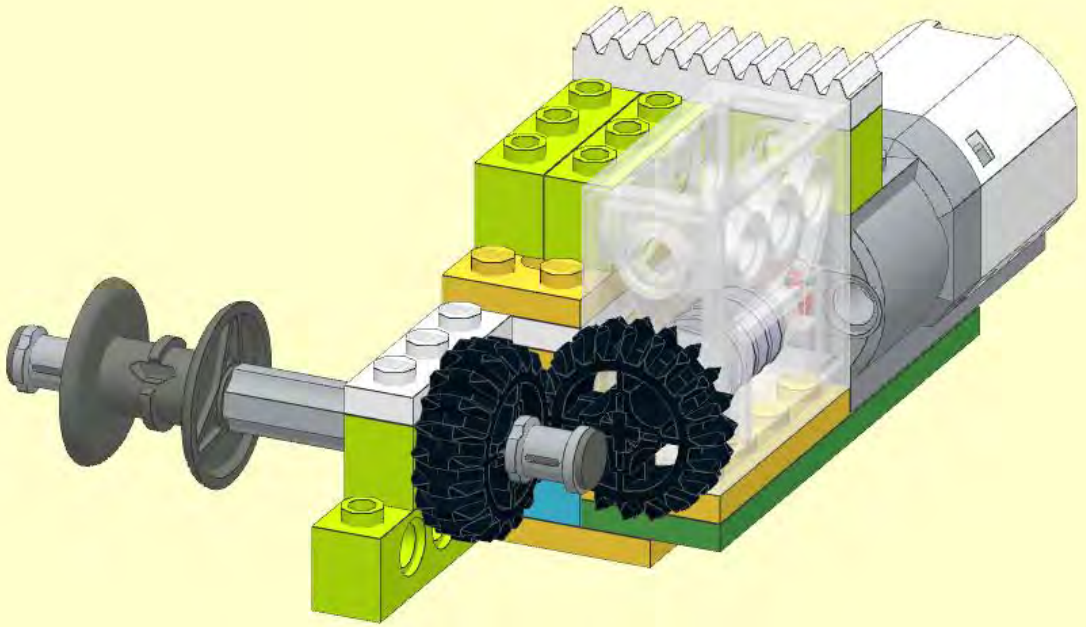


12

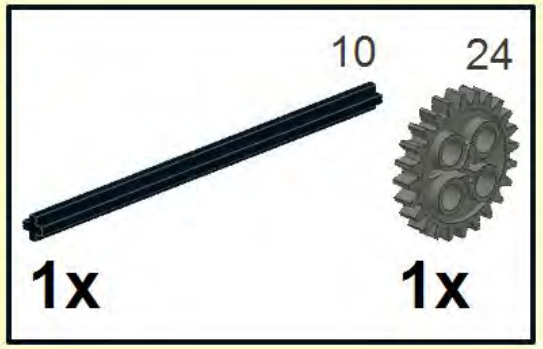


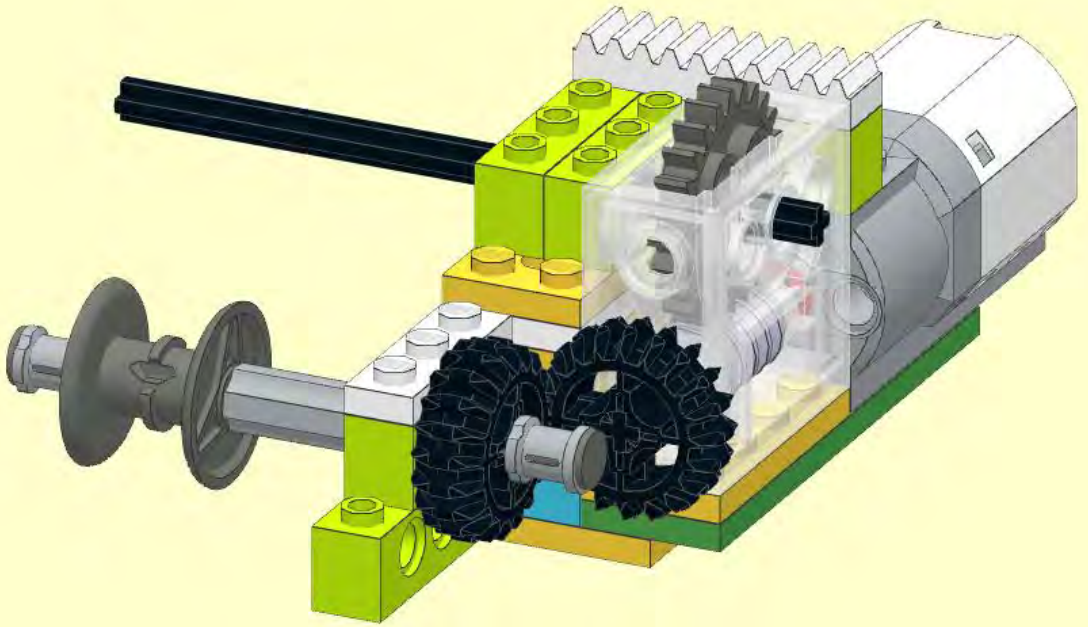


13

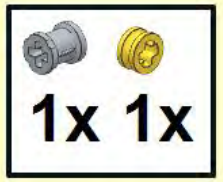


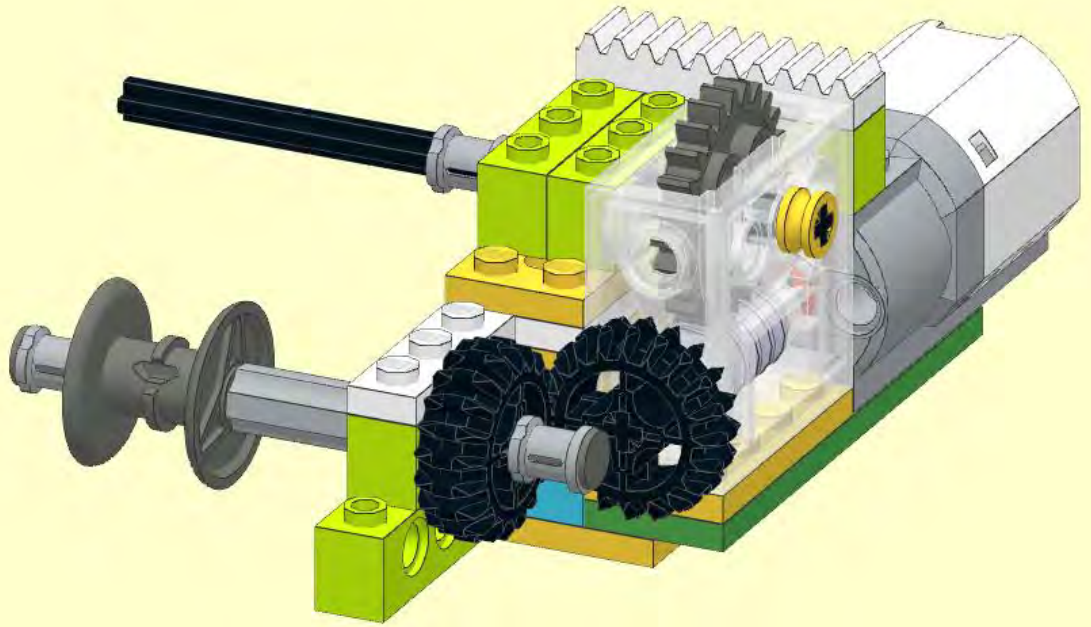
14

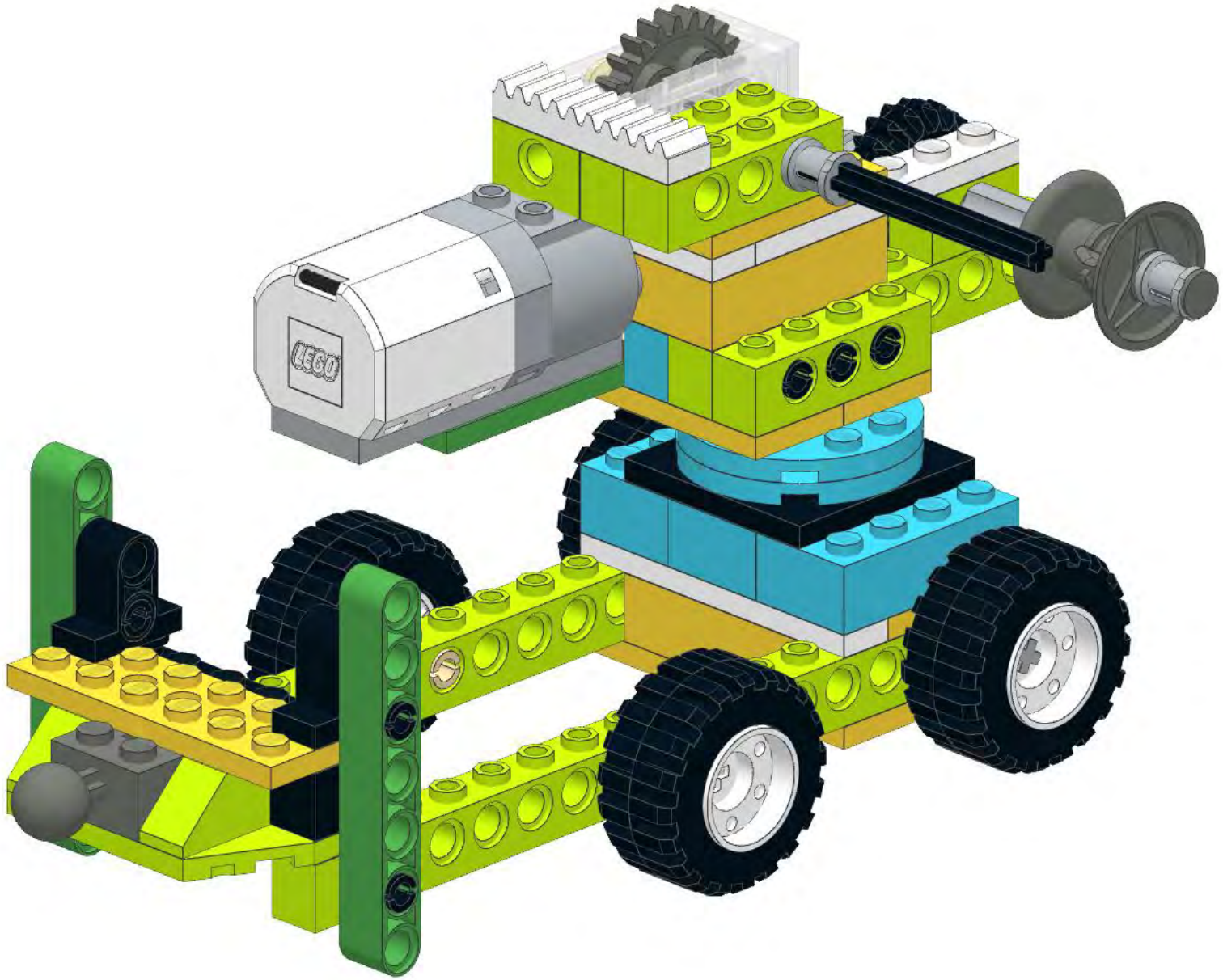




15

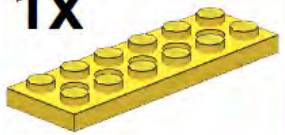




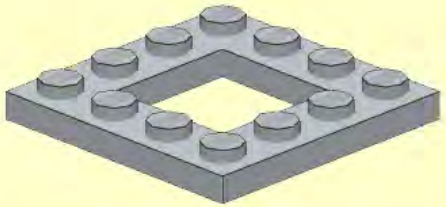

LEGO

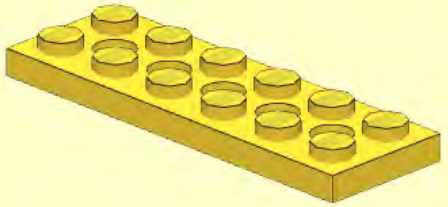
1

1x

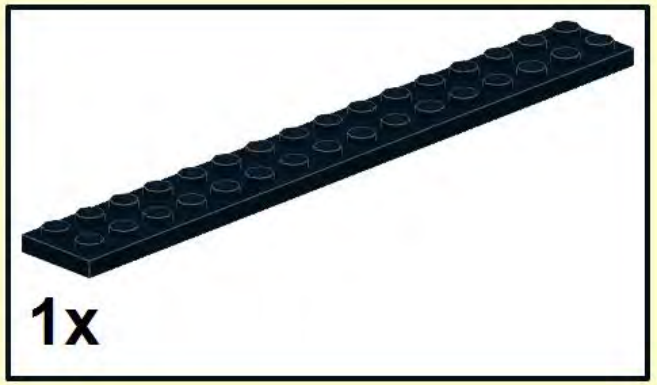


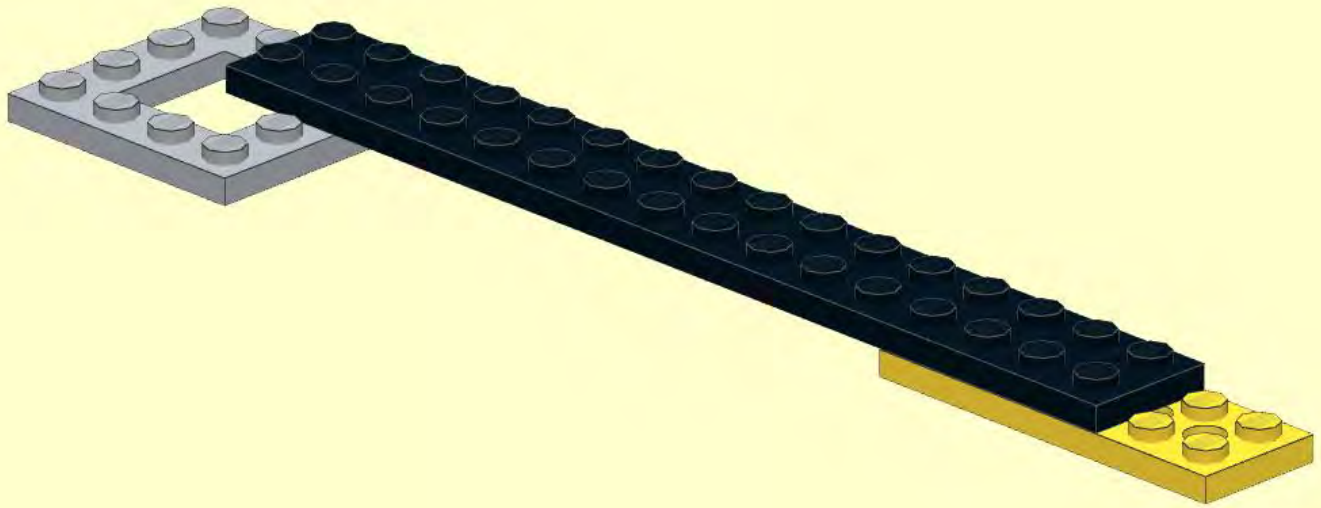
1x





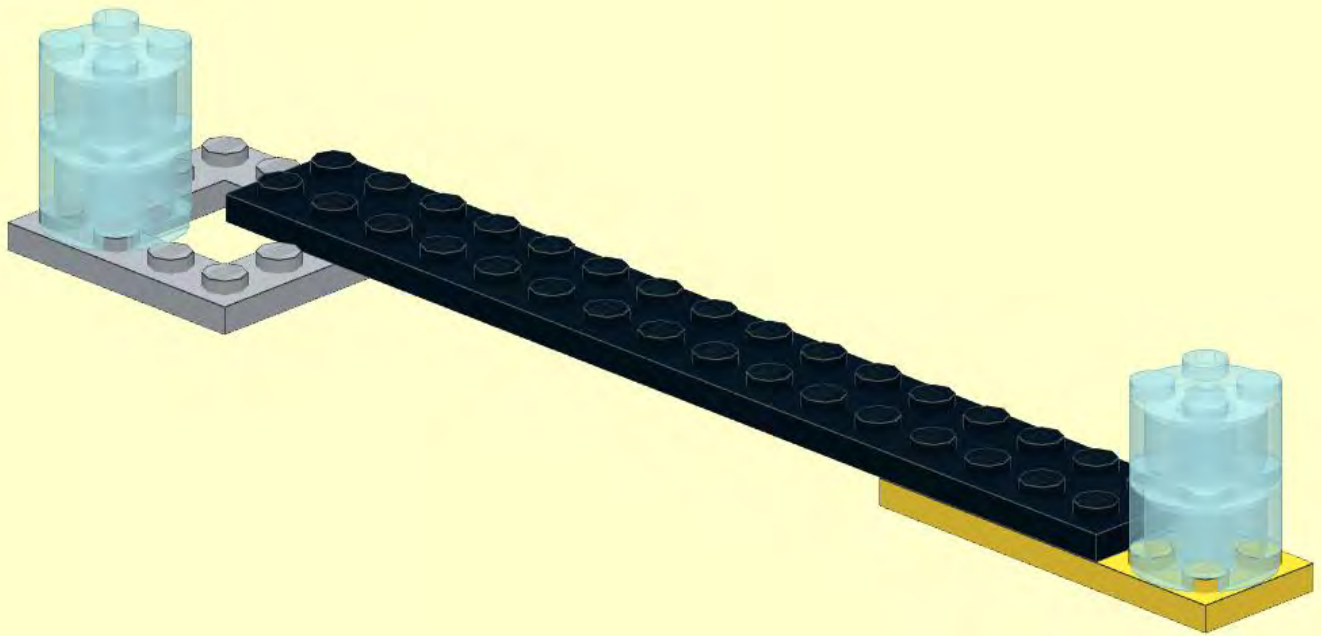
2



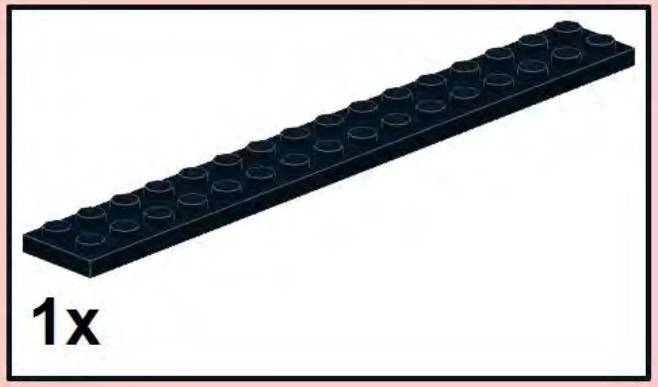


3

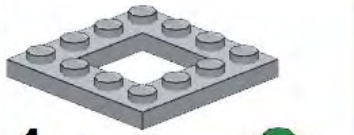
4x



1

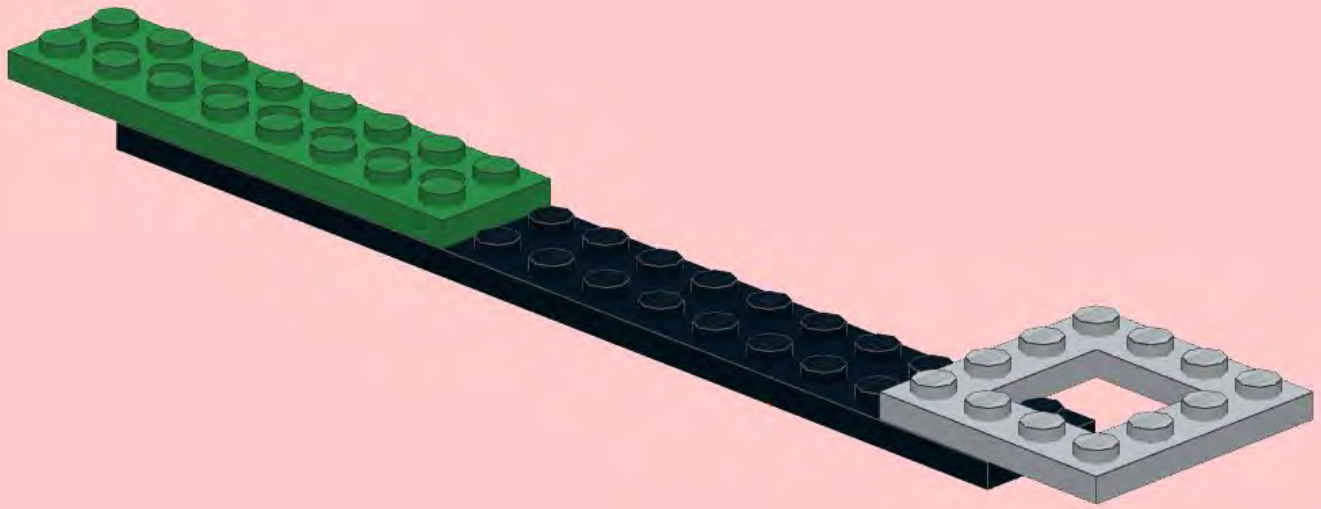


2

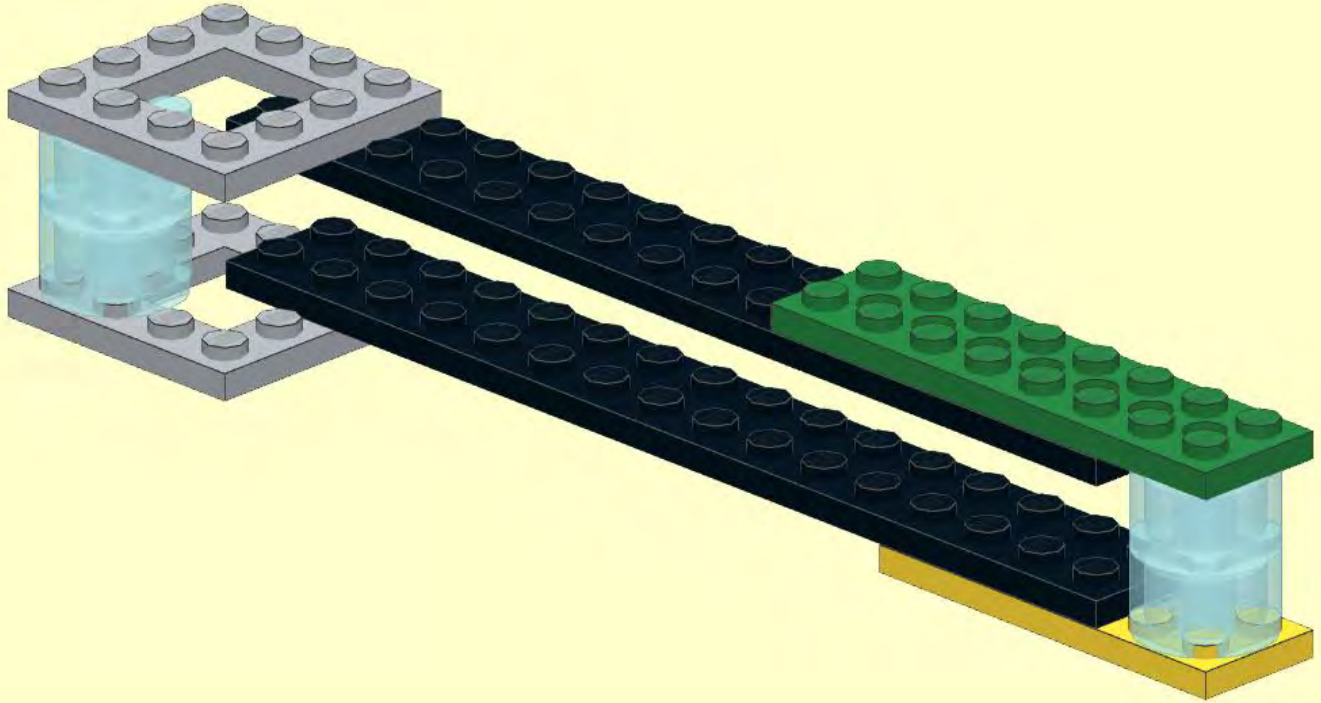


1x

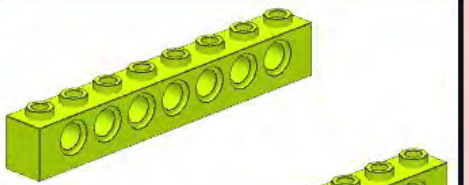
1x



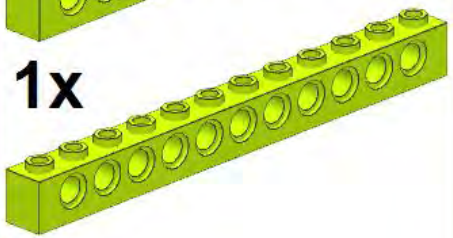
4



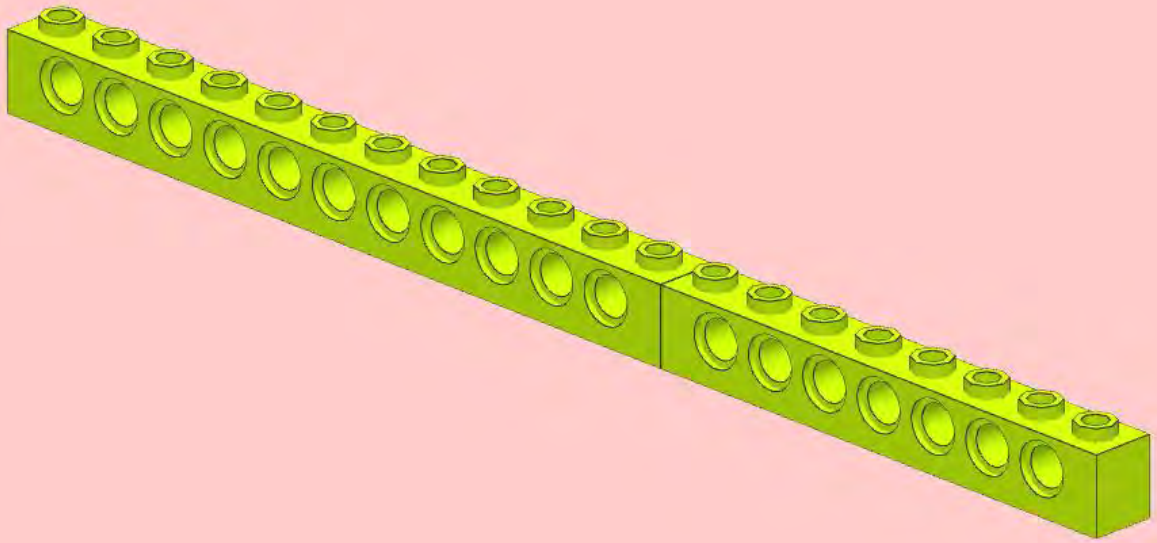
1



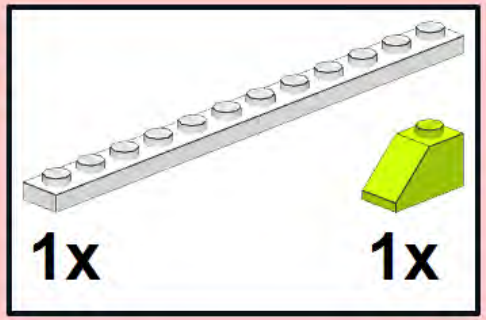
1x

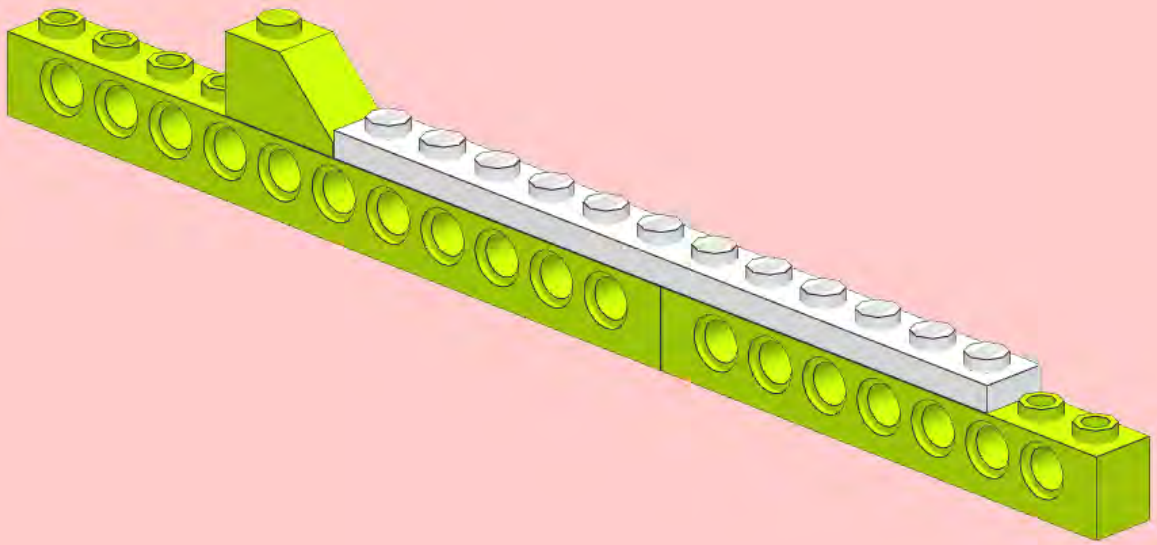


1x

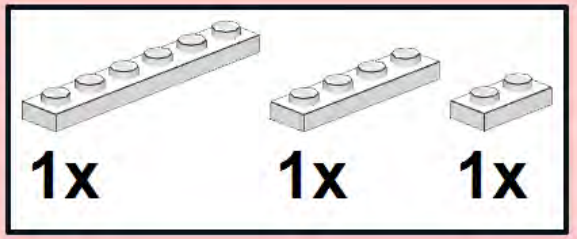


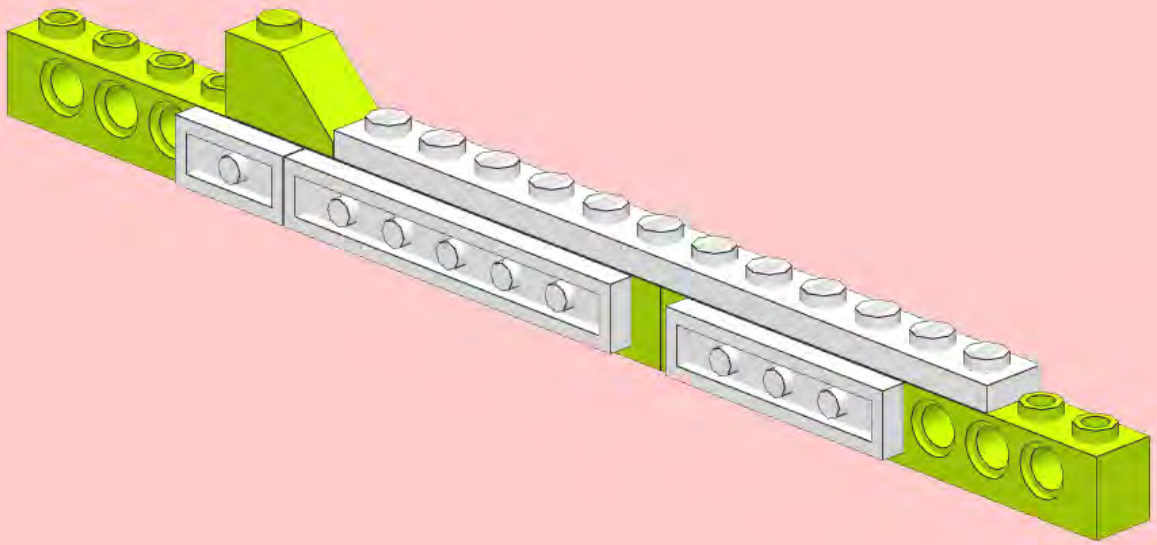
2



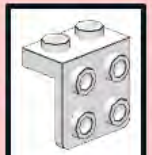


3

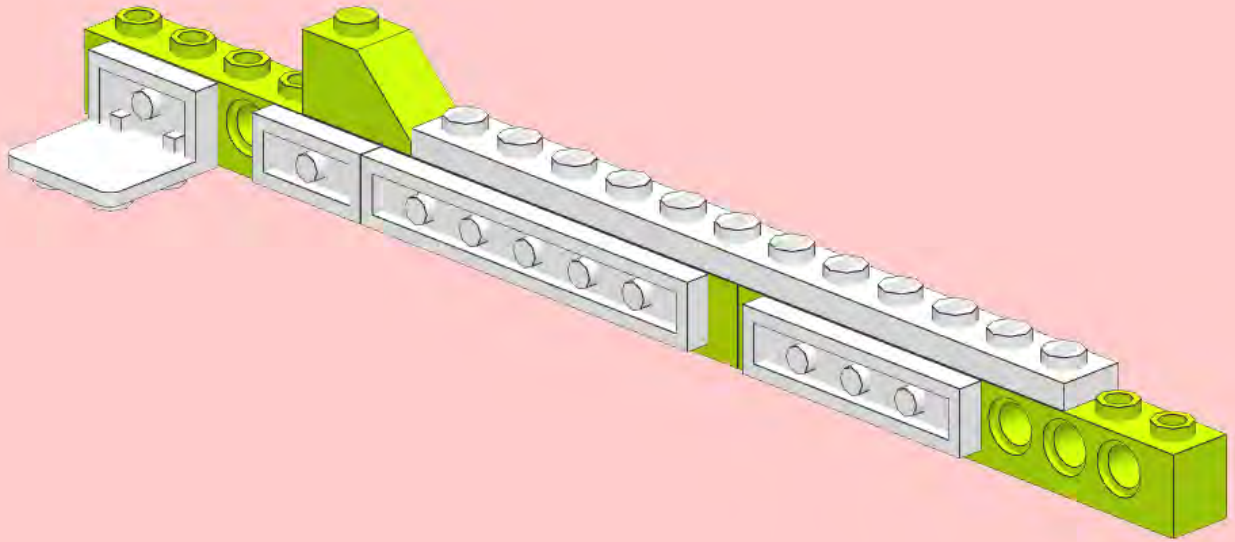




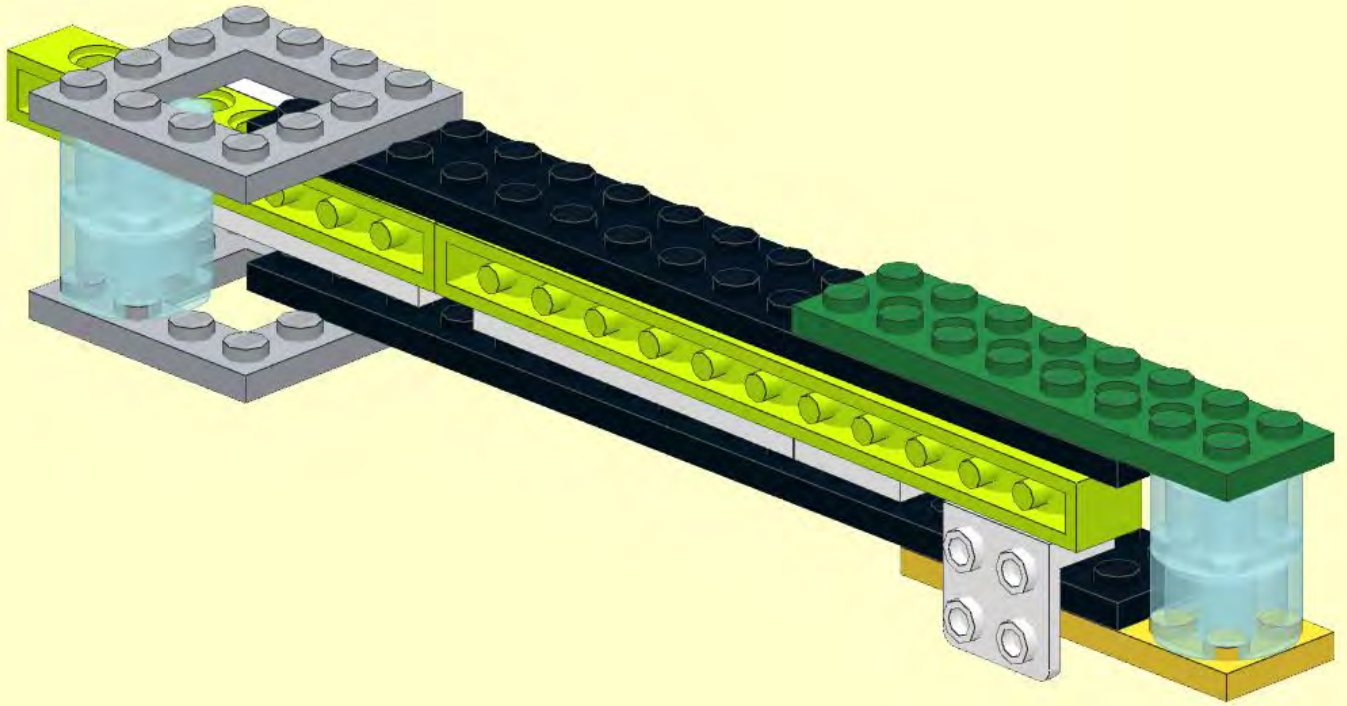
4



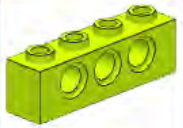
1x



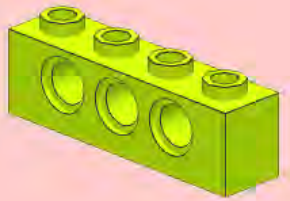
5



1

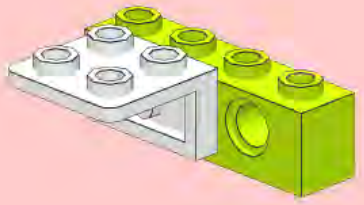


1x

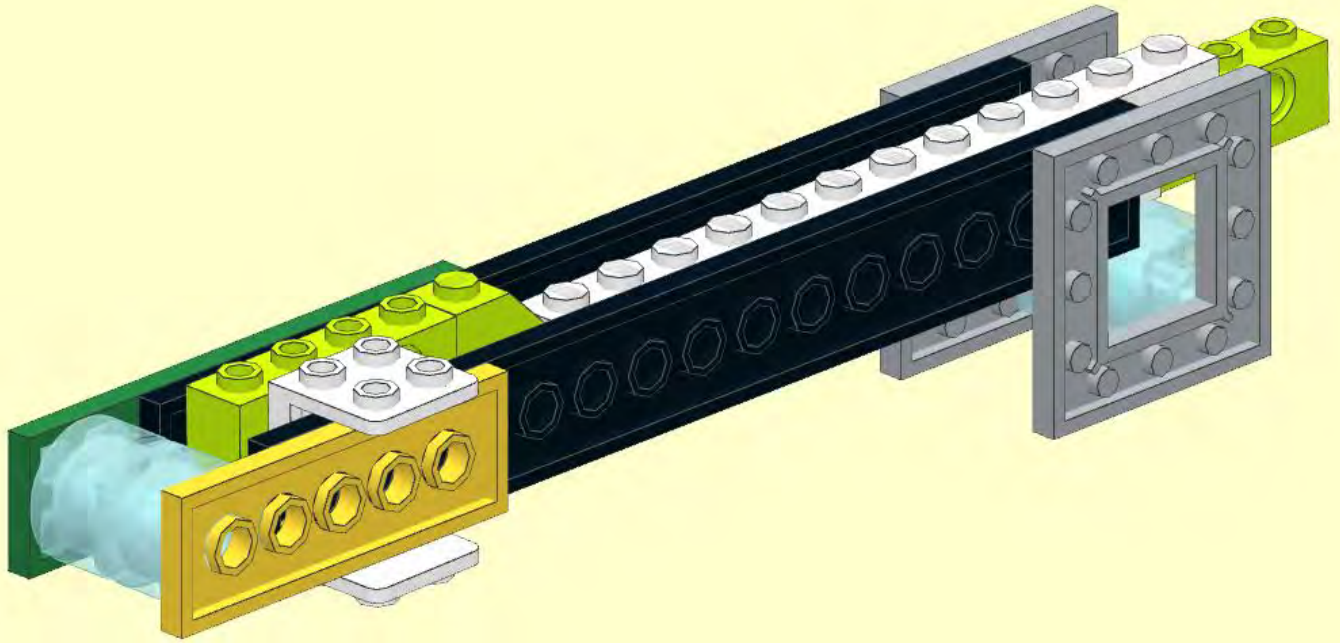


2

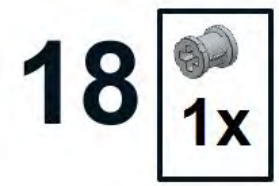
1x



6

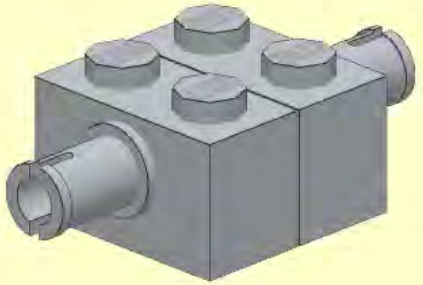


18

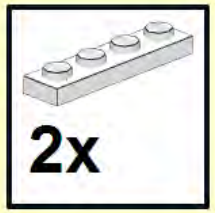


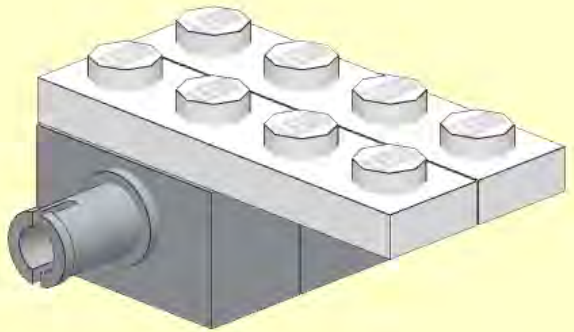
1

2x

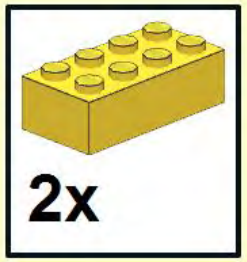


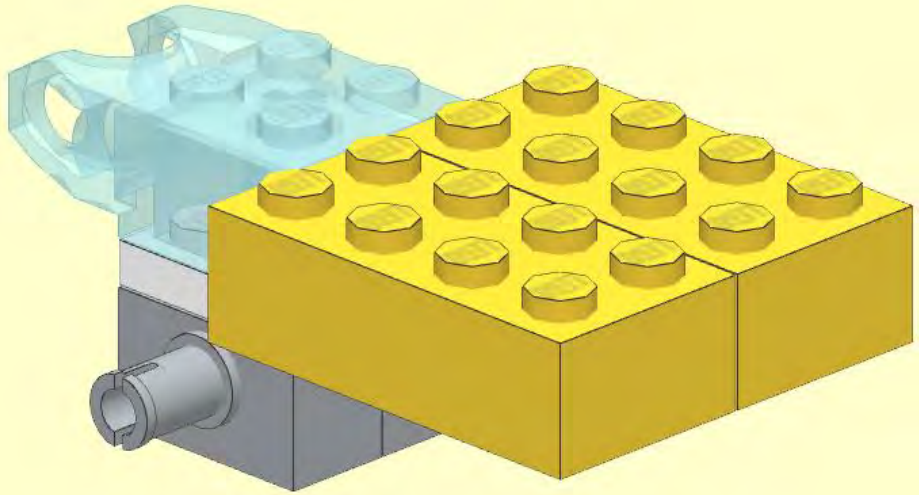
2



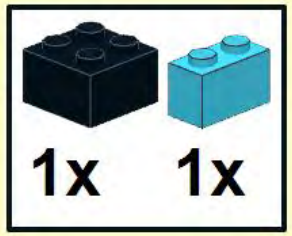


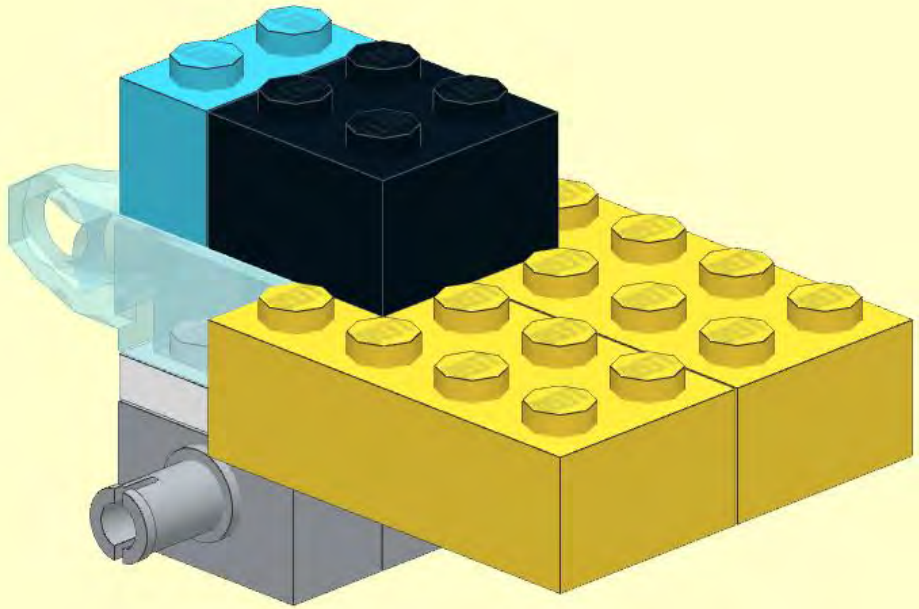
3



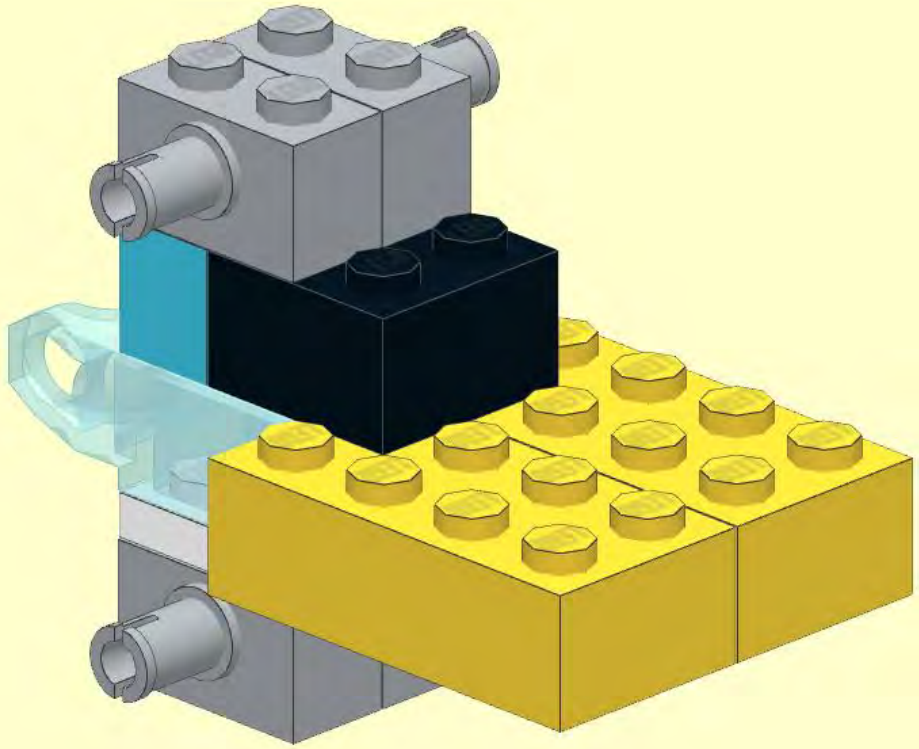


4

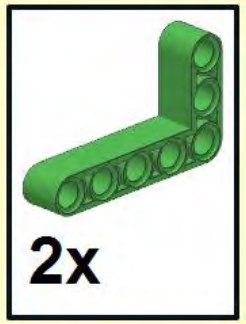


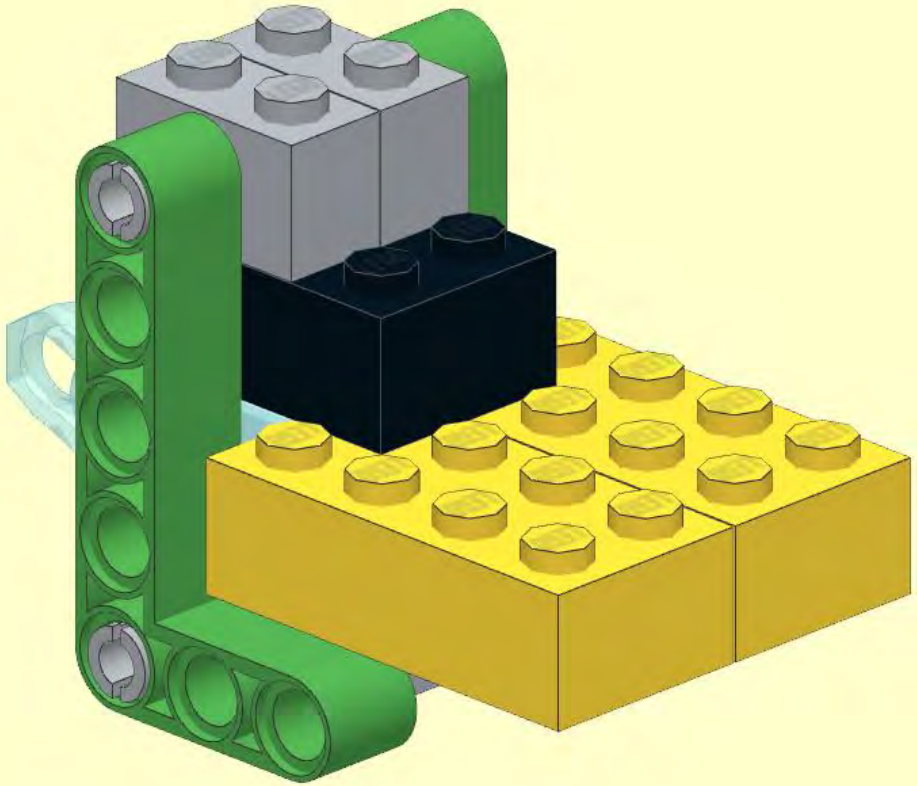


5

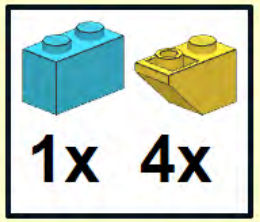


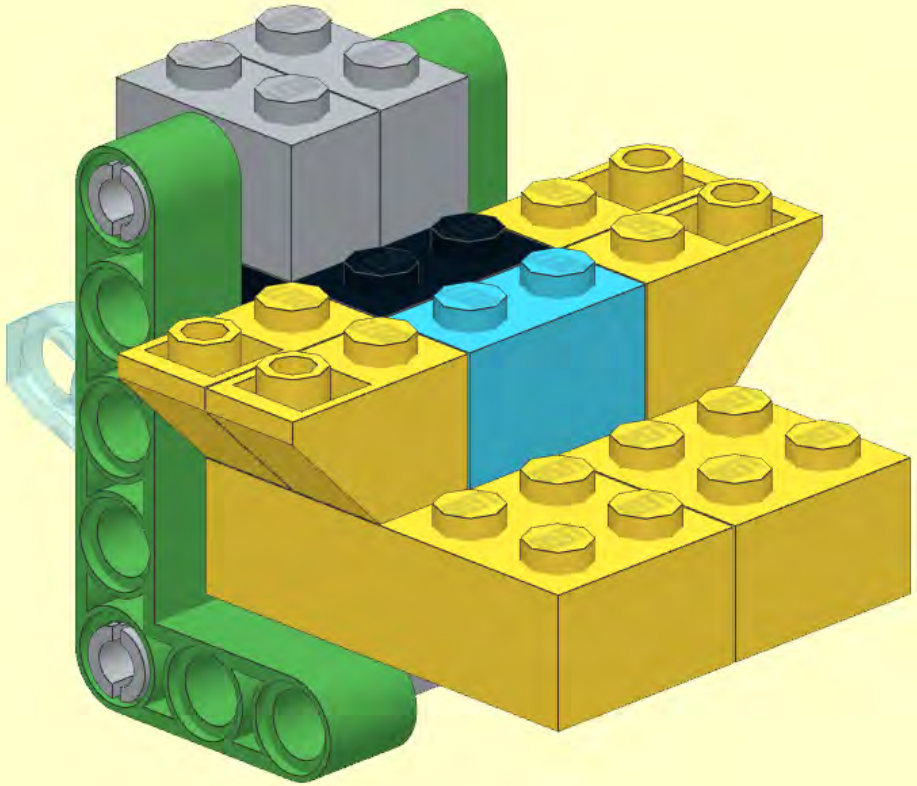
6





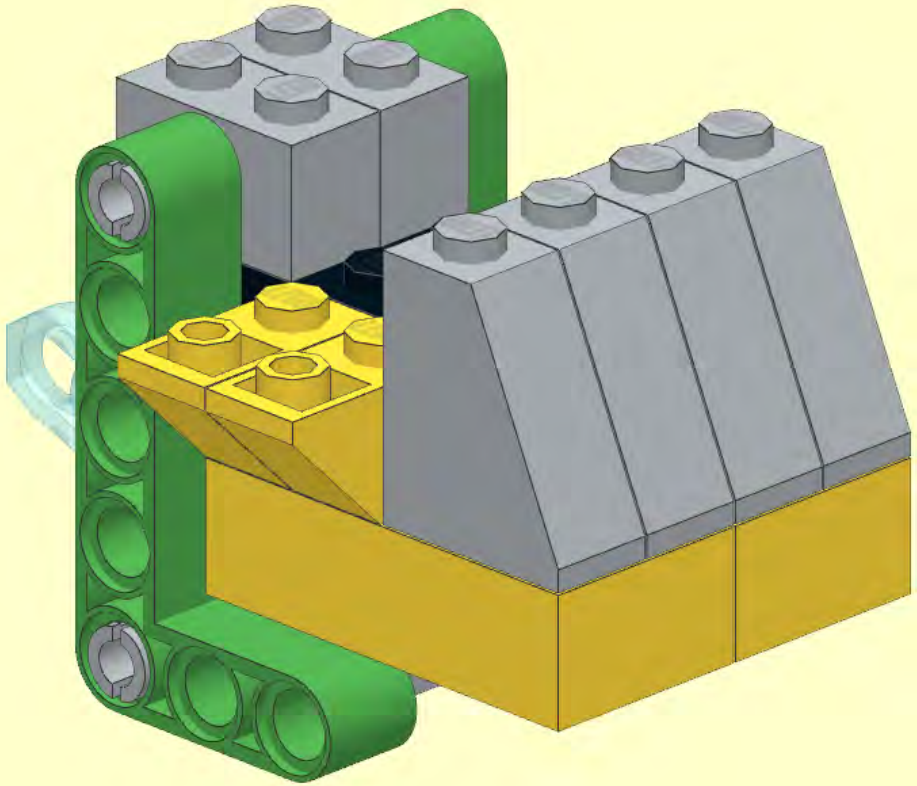
7



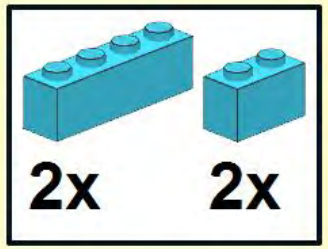


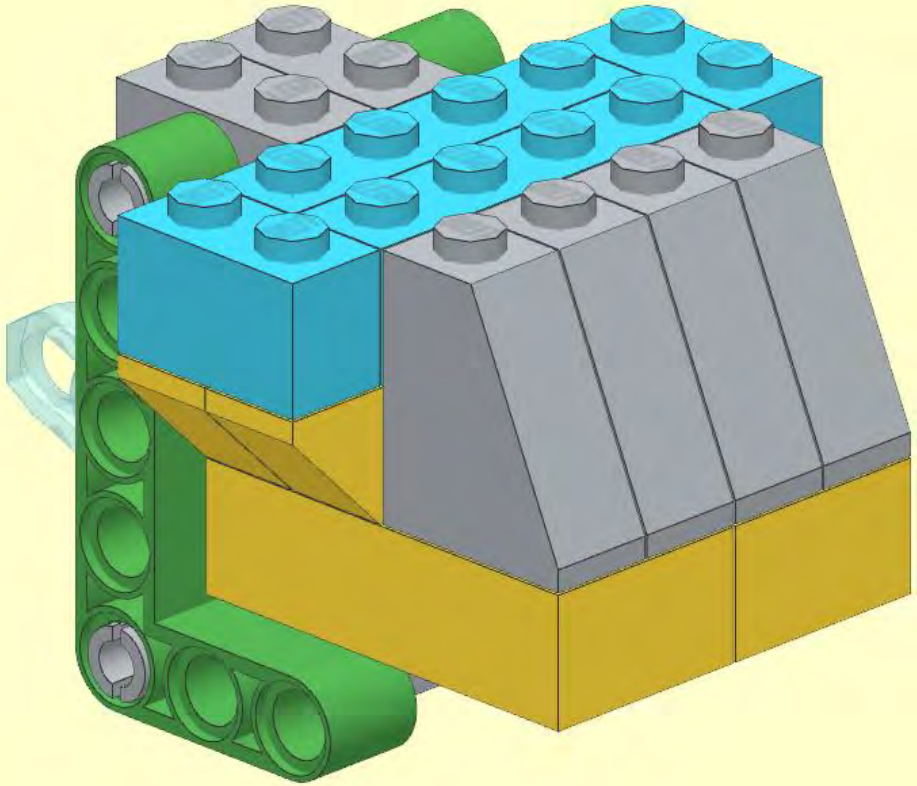
8

4x

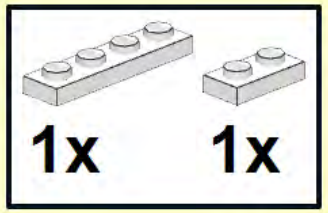


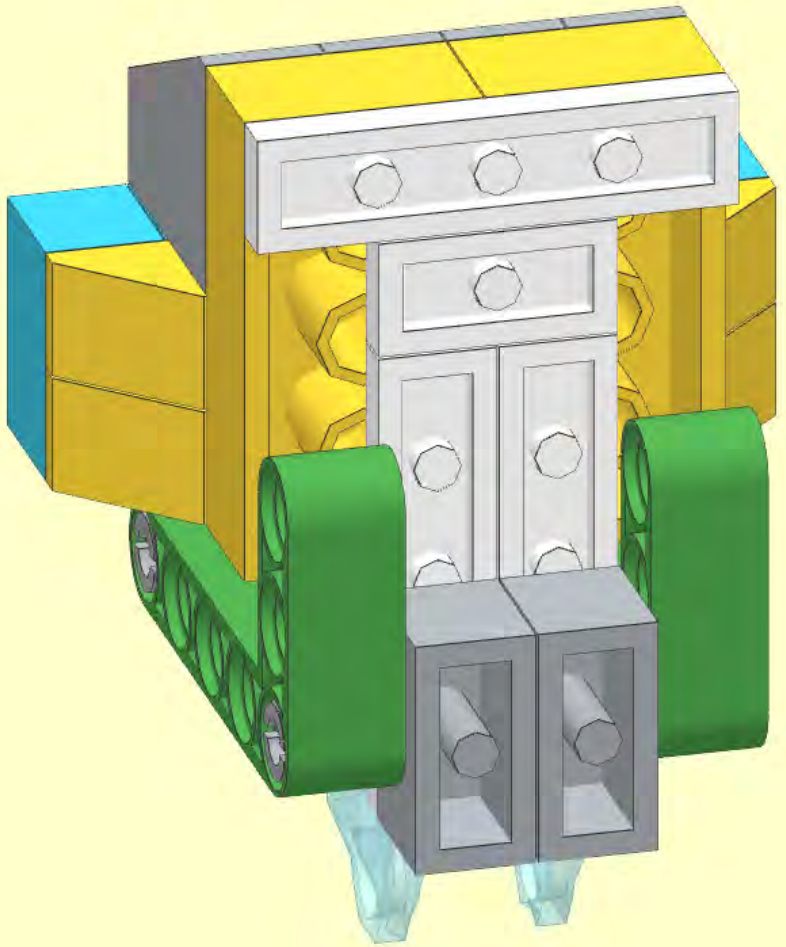
9



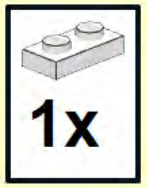


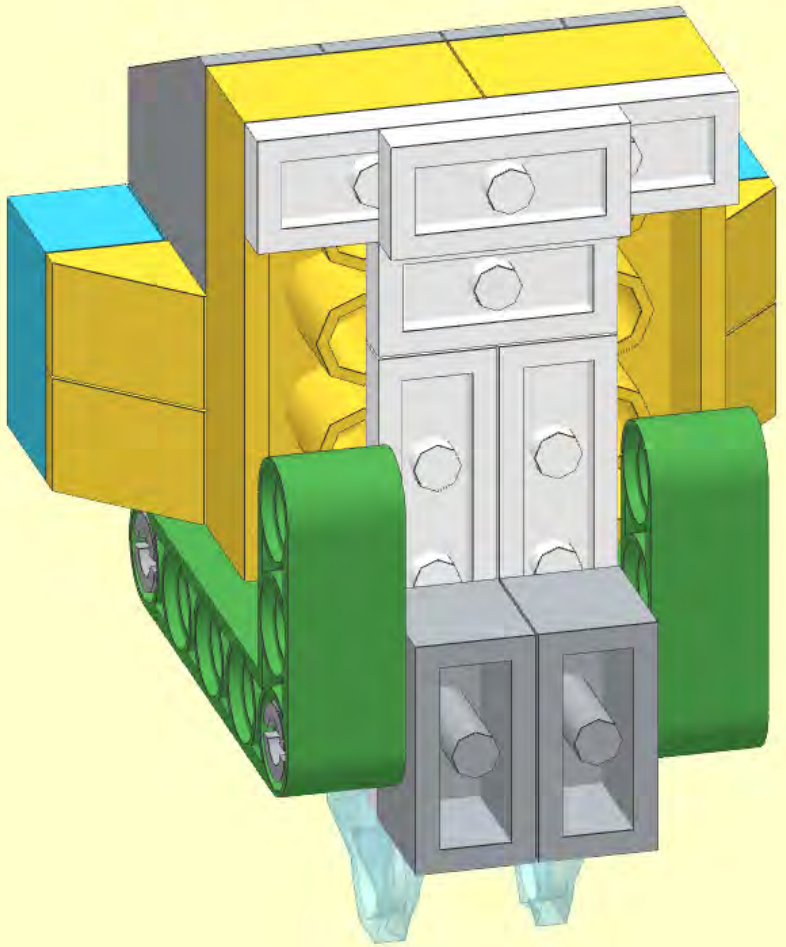
10



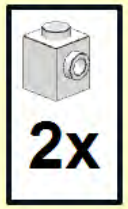


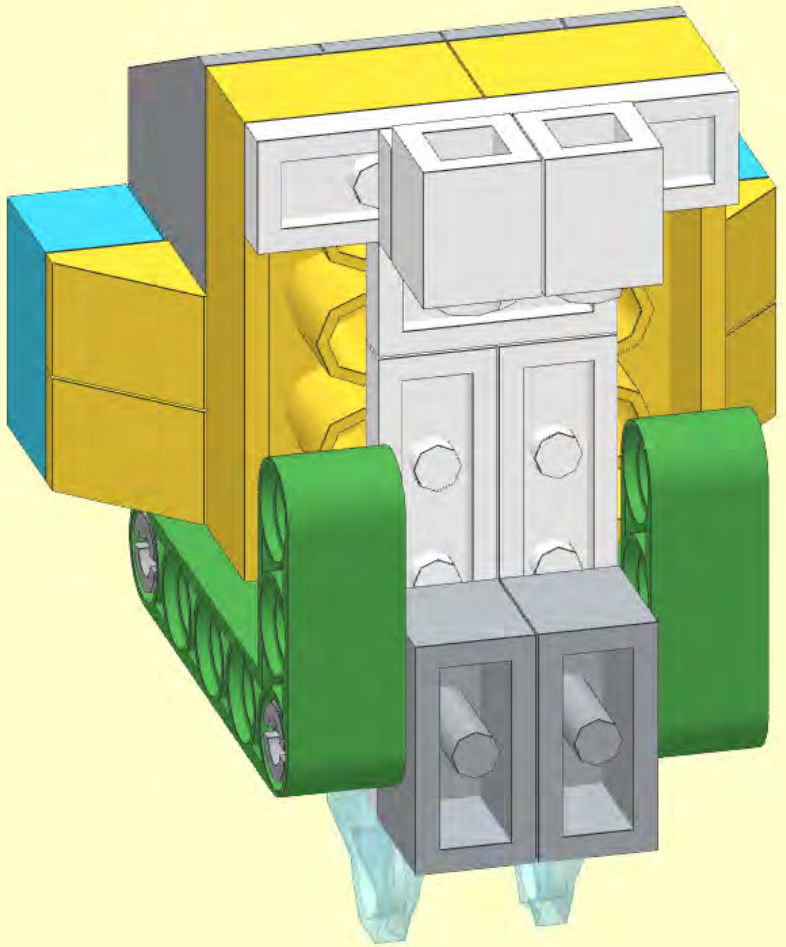
11



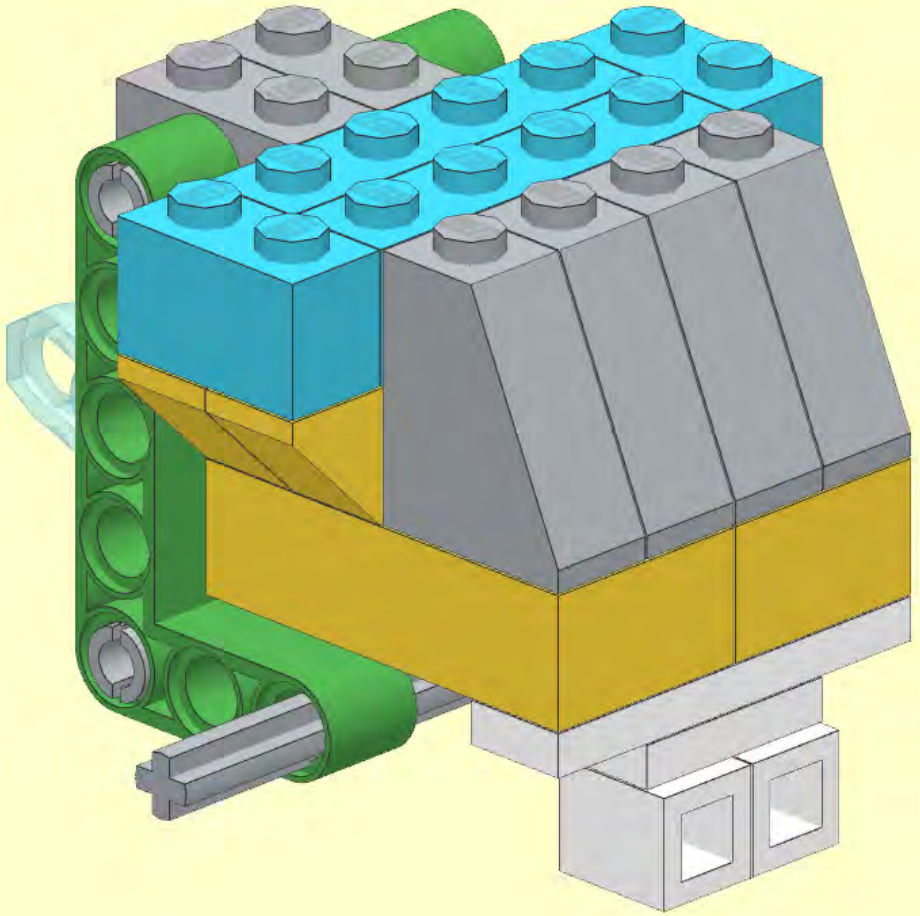


12

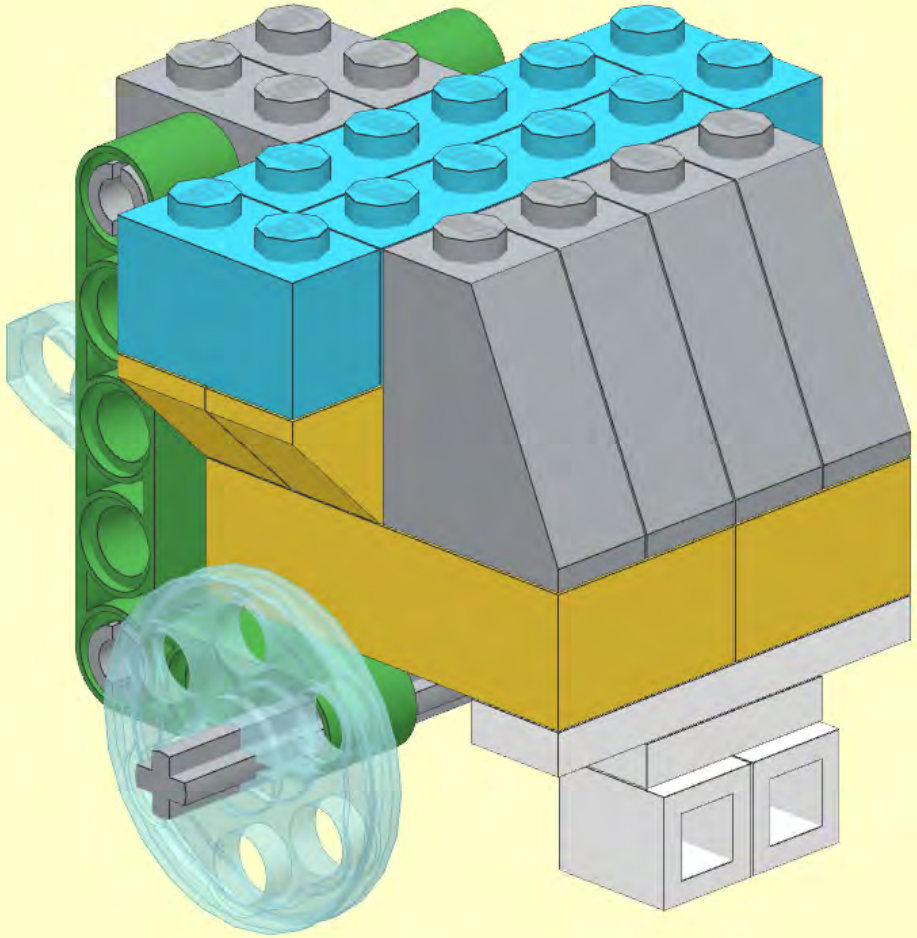




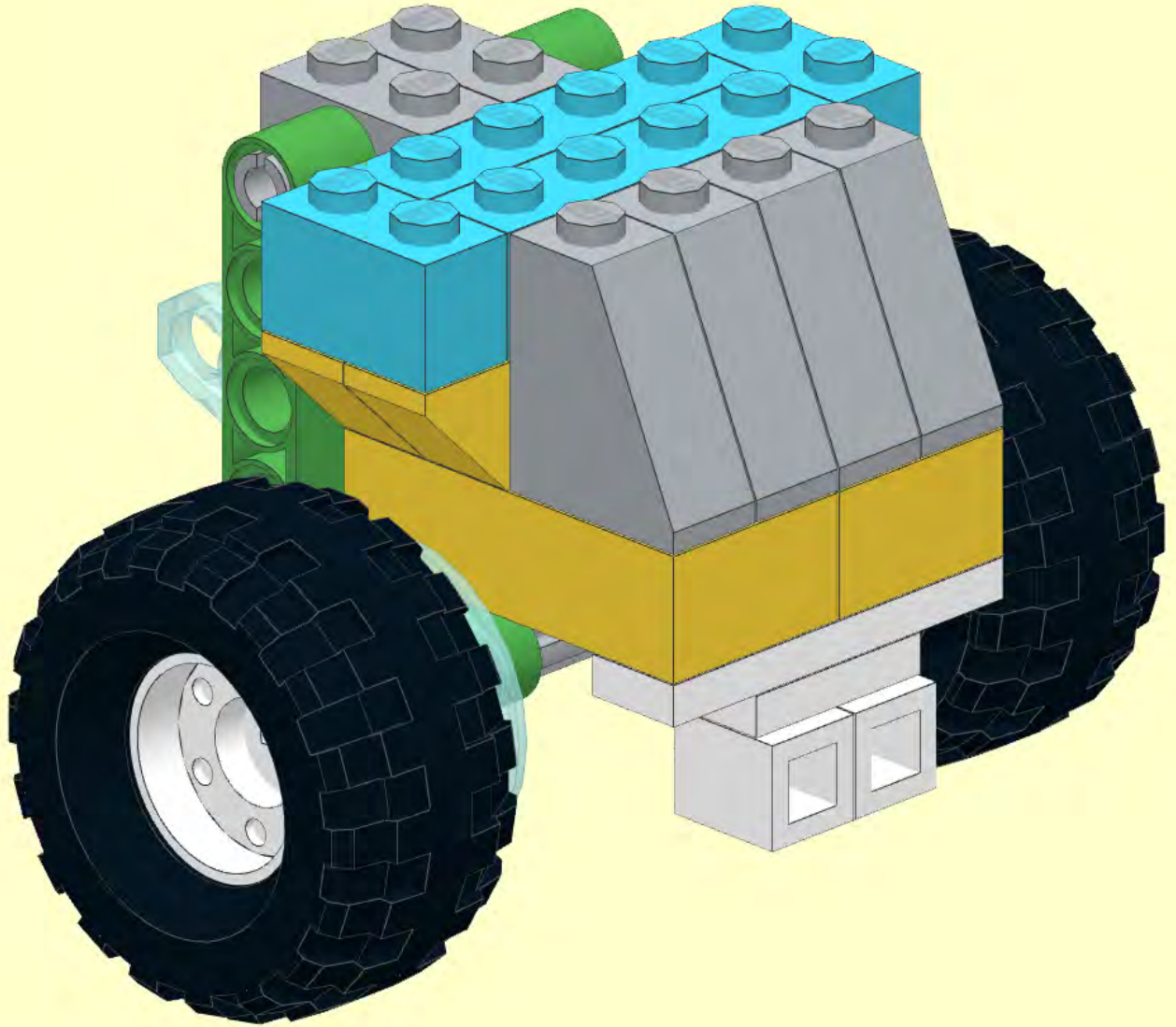
13



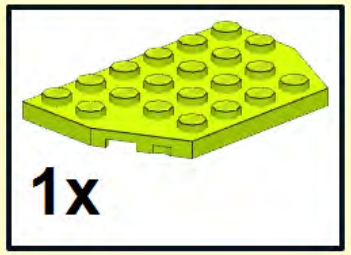
14

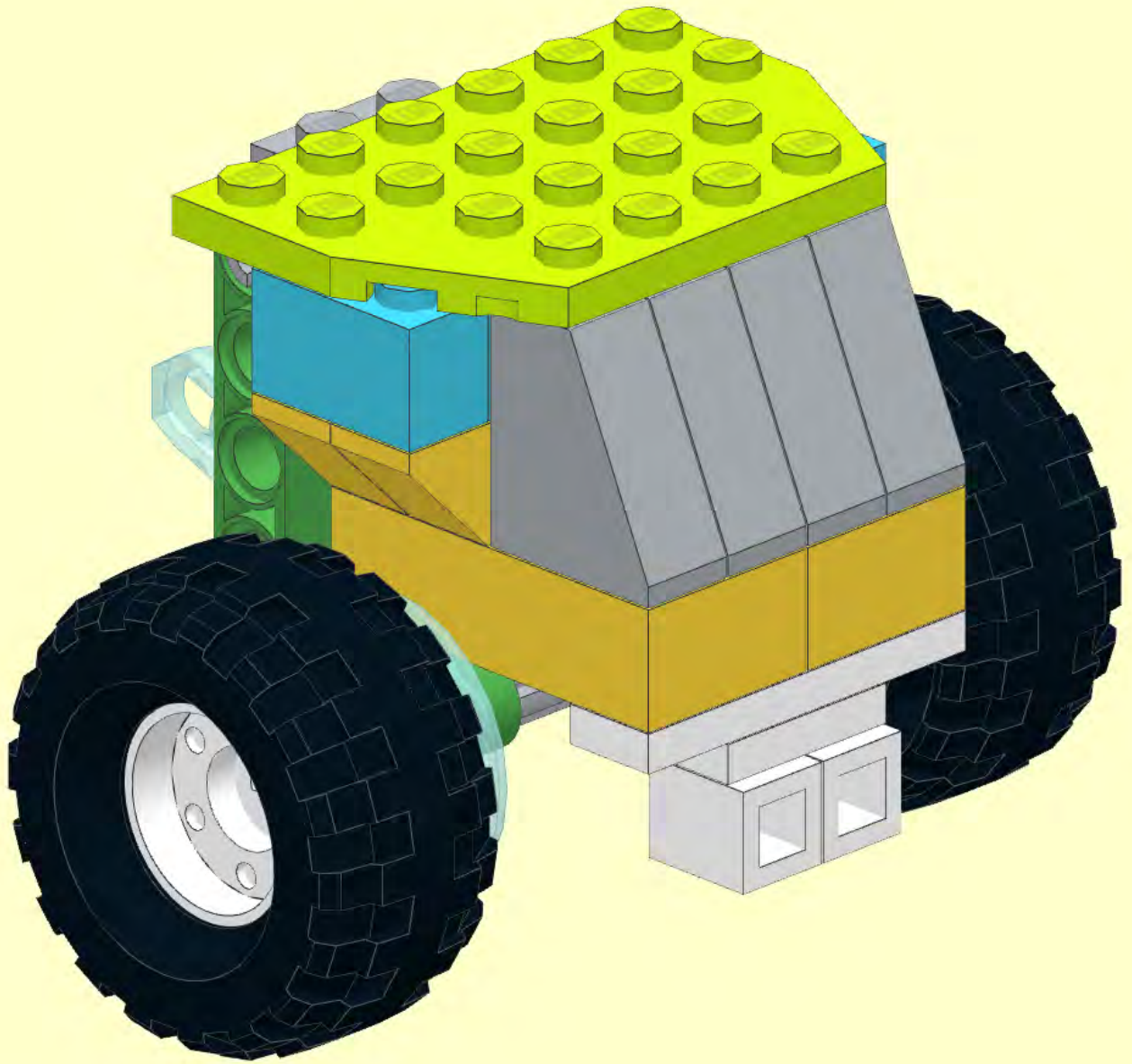


15

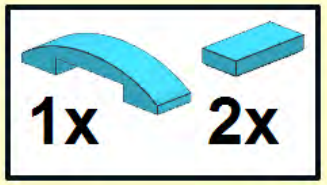


16





17



1. And now we will write a program for running the winch in one direction, the other and, which is VERY IMPORTANT - stops.

2

2

2. In order to remotely control our crane, we need a distance sensor. Write a program that turns on the hoist when the sensor shows an approximation. Includes the winch for lowering when the sensor shows a distance.

2
0.1
2
0.1

3. Now independently write the program that controls the winch like the previous one, but with the help of the tilt sensor.

Find the error.
The programmer wrote a program for the robot, which should include a motor for 9 seconds, but the engine somehow works longer.

Explain what this program does.

More buildings from Anger project on
https://play.google.com/store/apps/developer?id=AnGer+project