

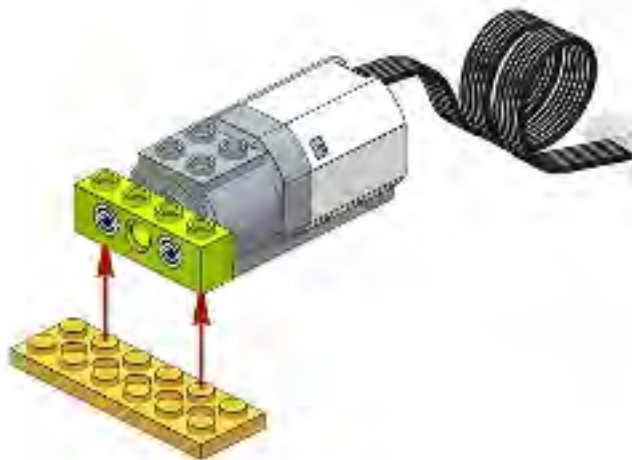


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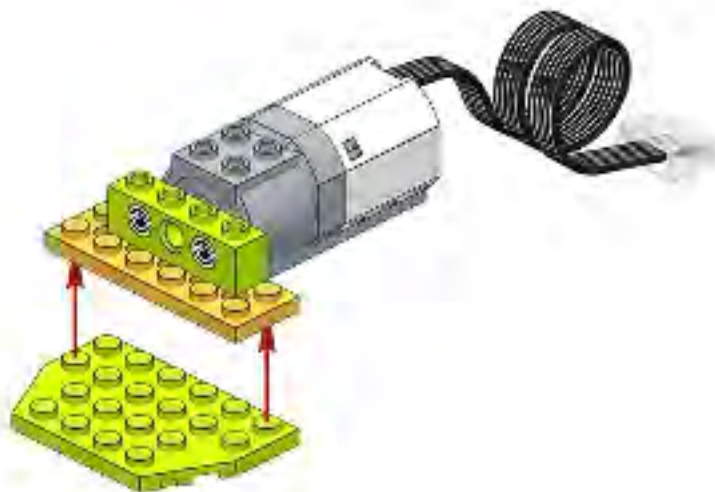
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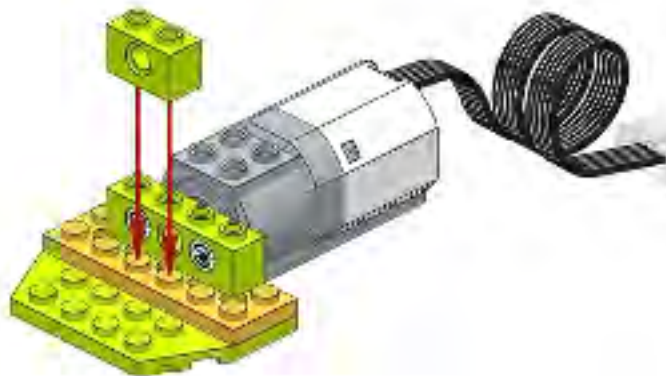
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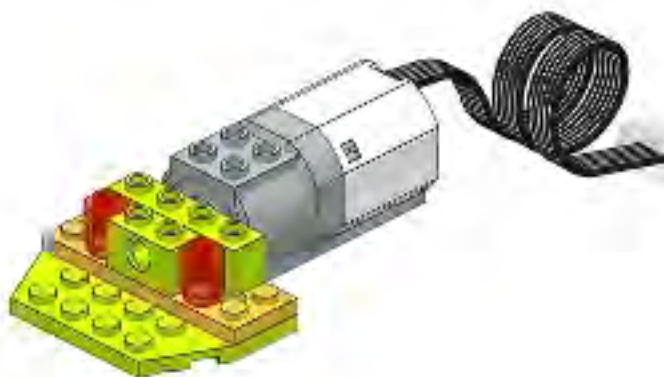
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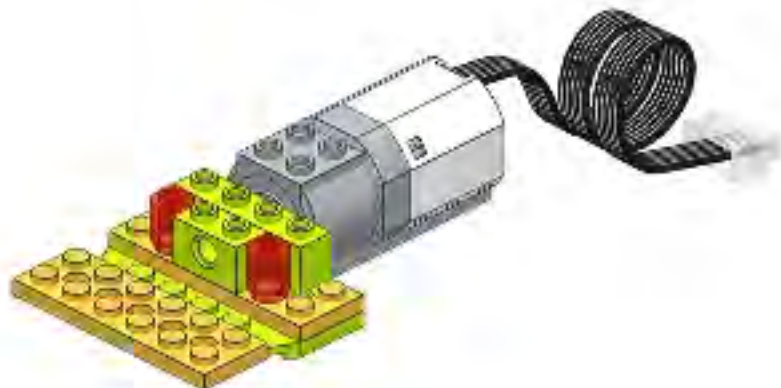
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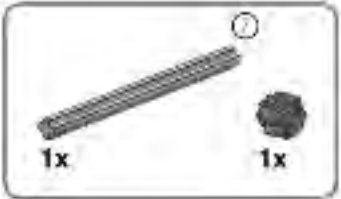




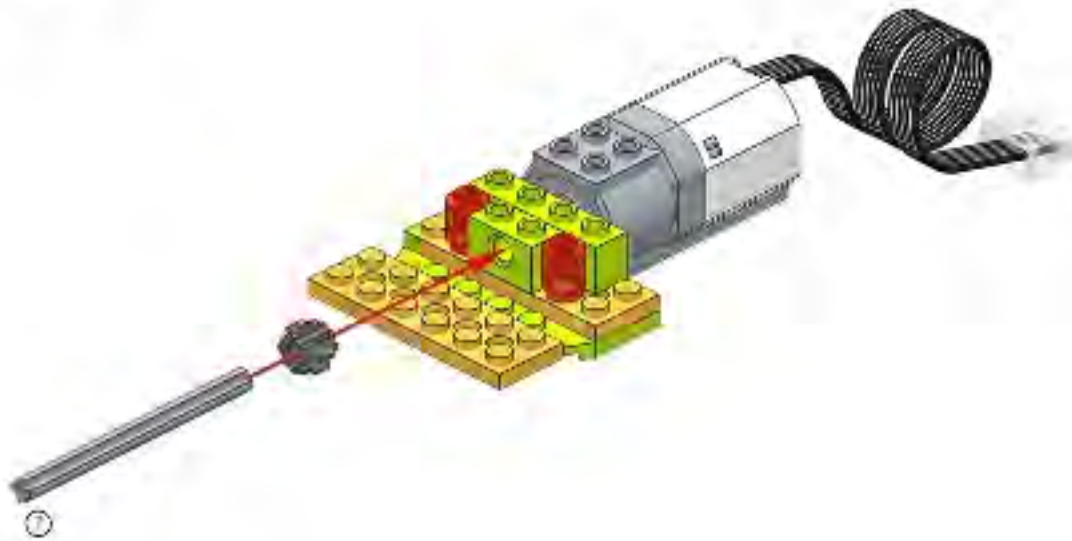
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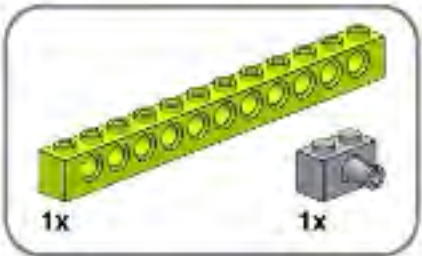
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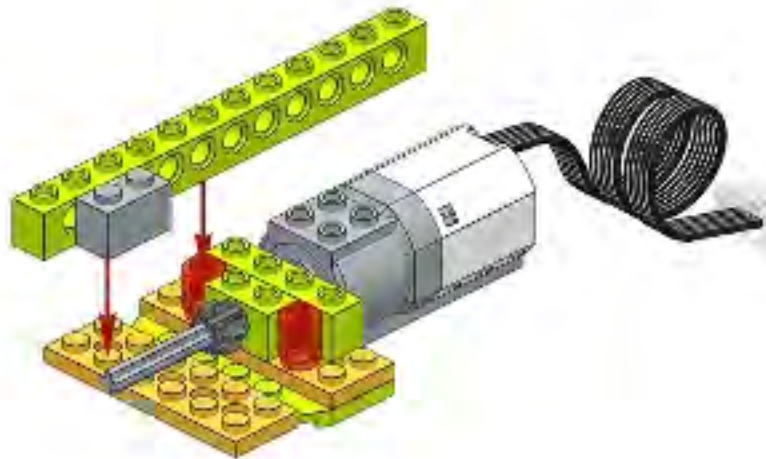


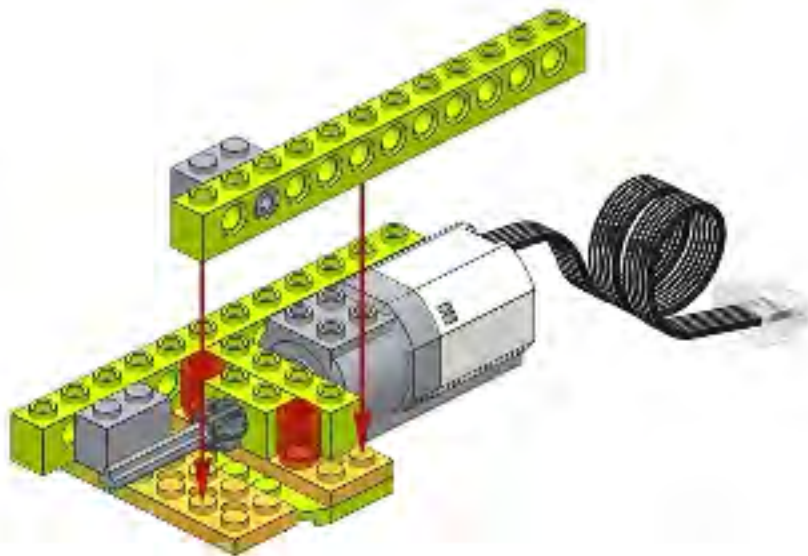
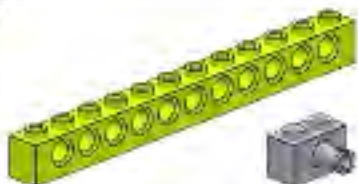
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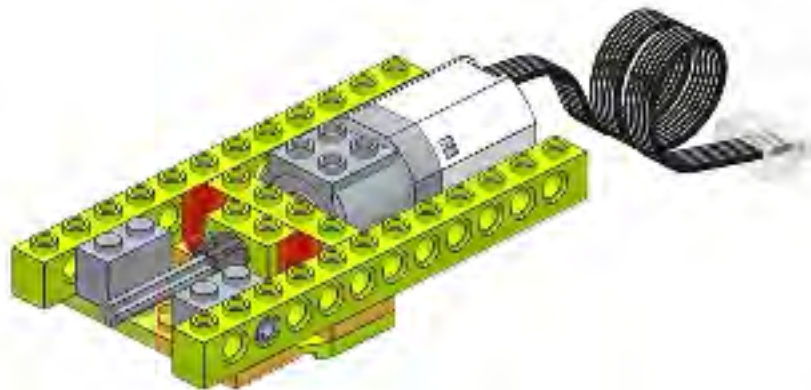
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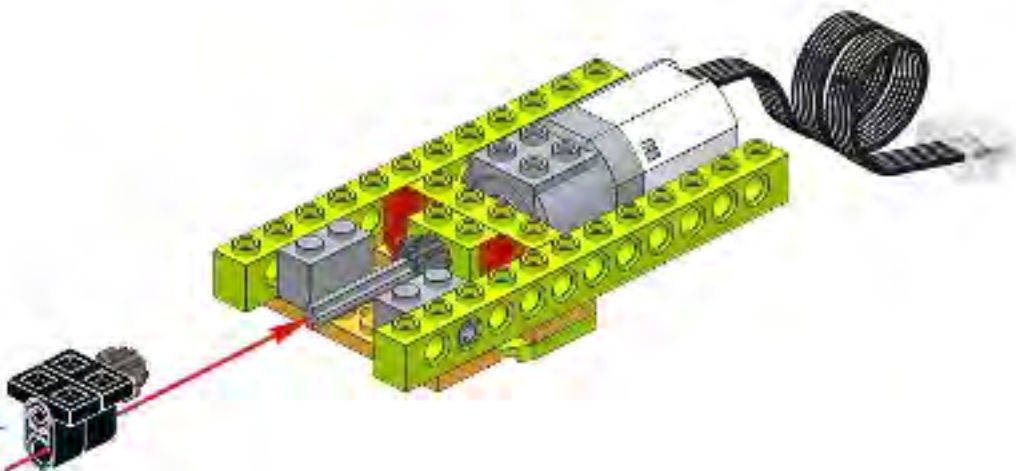




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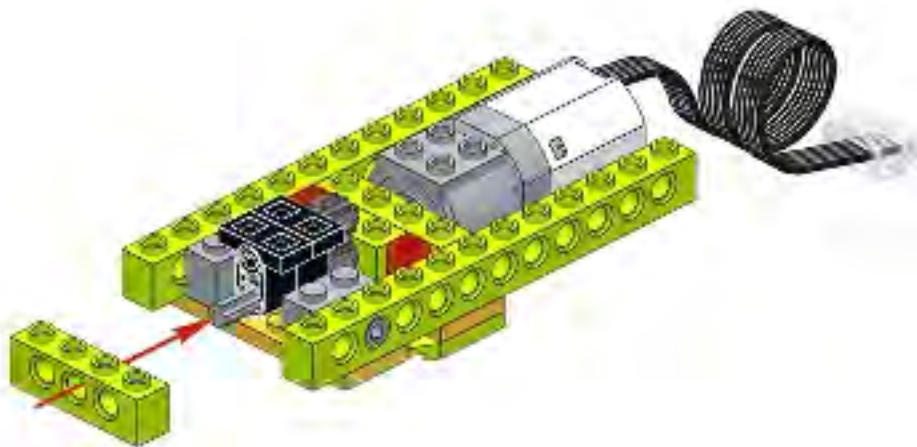
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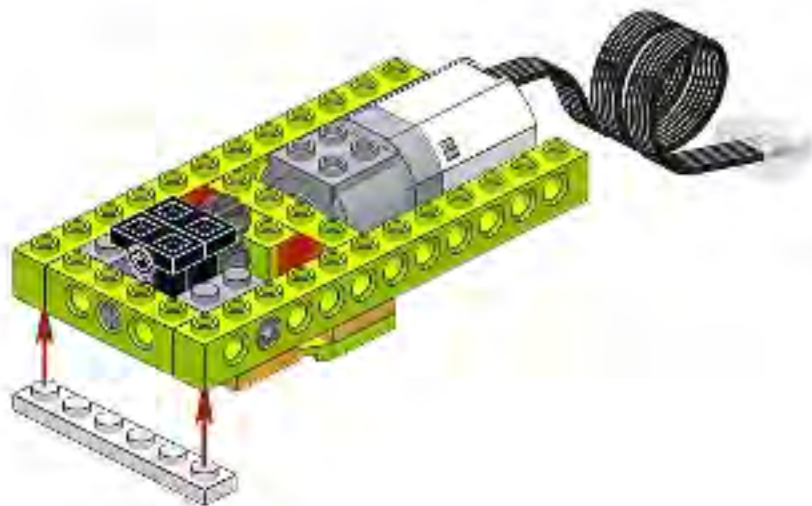
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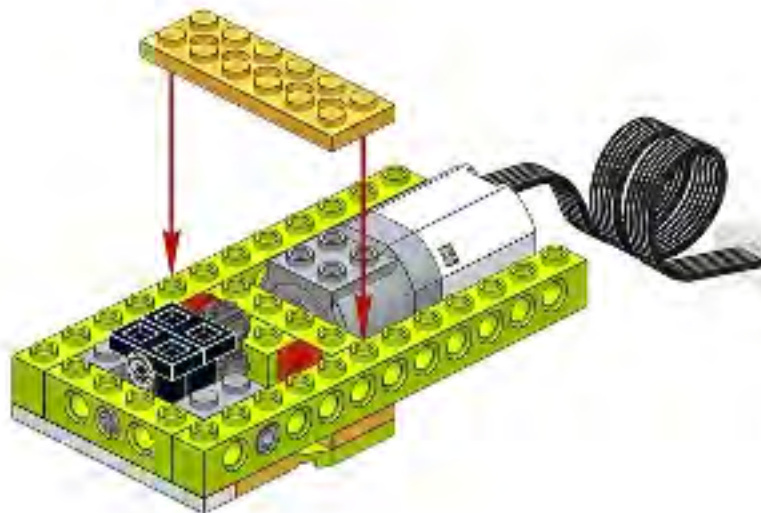
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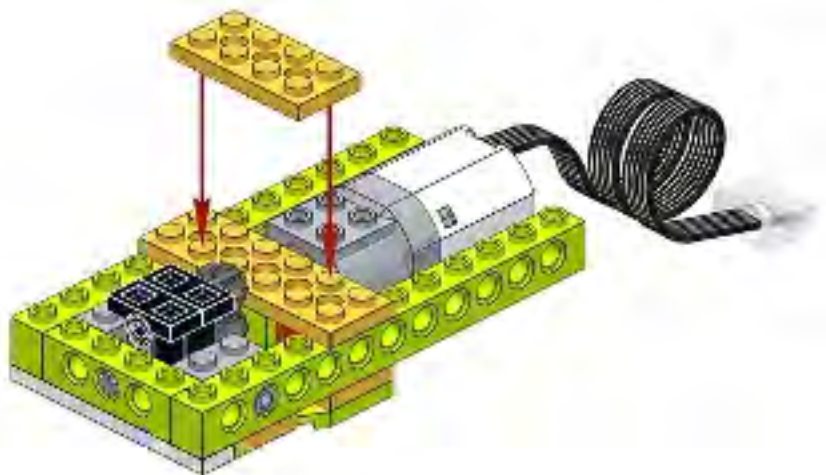
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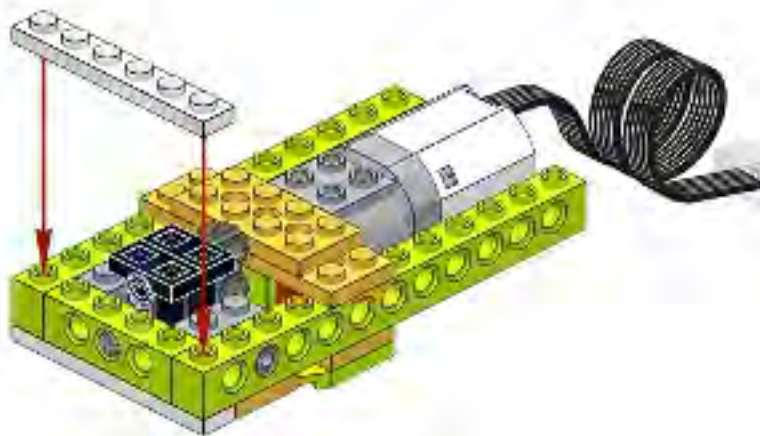
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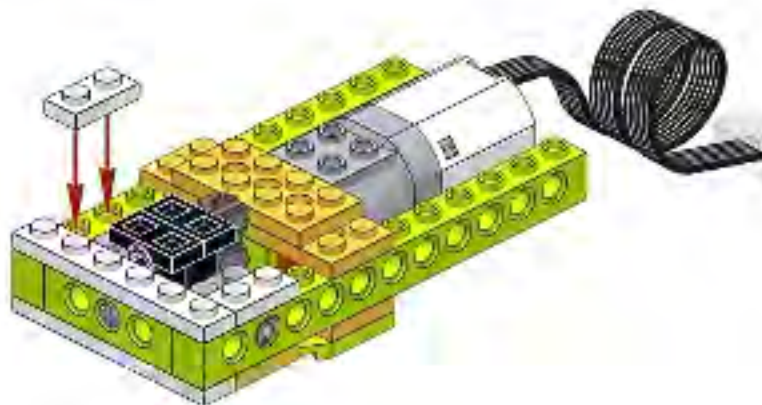
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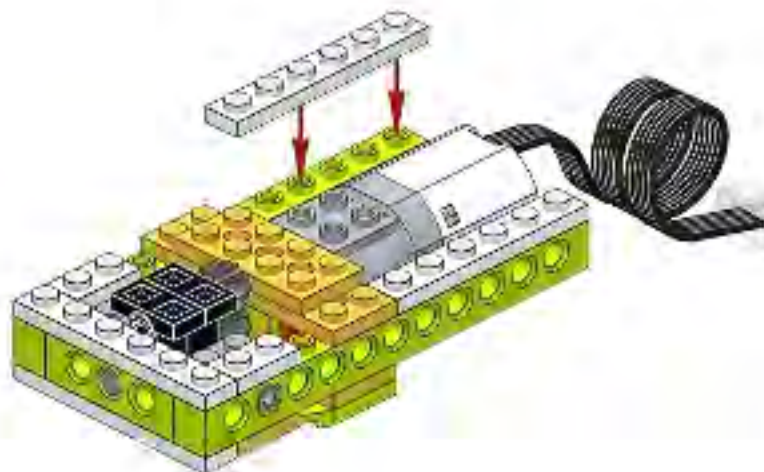
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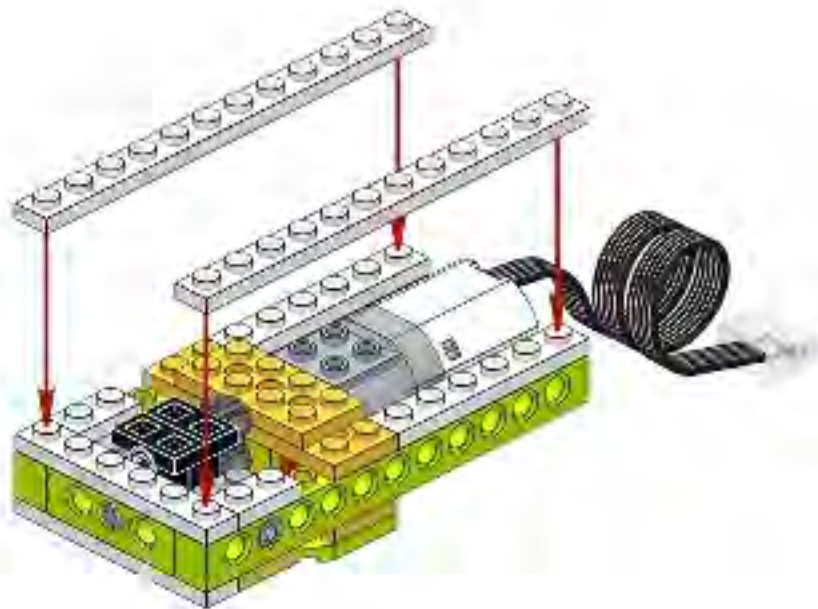
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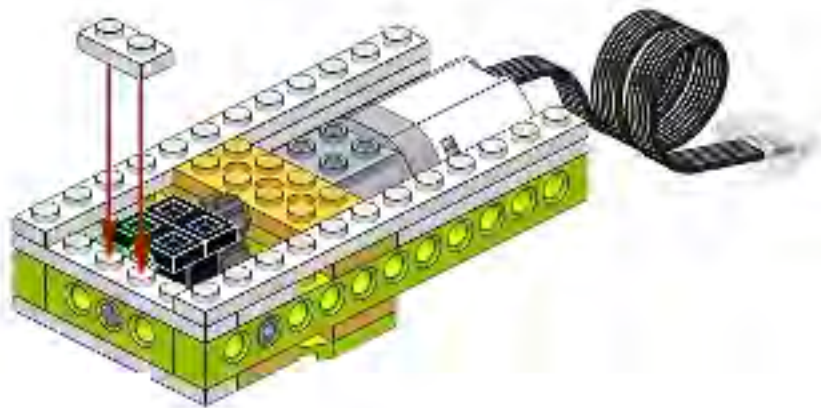
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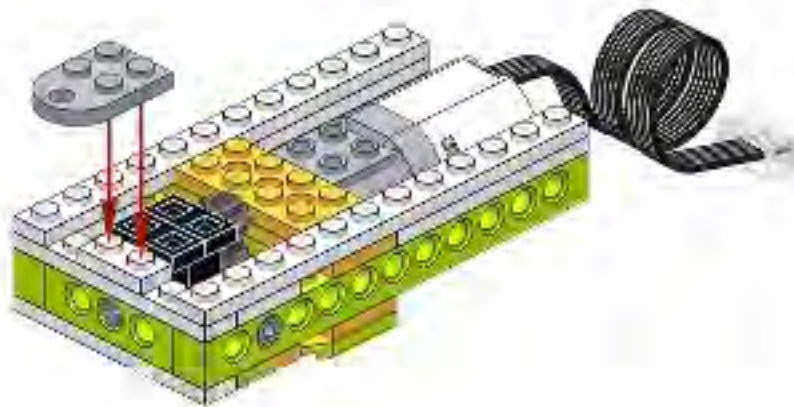
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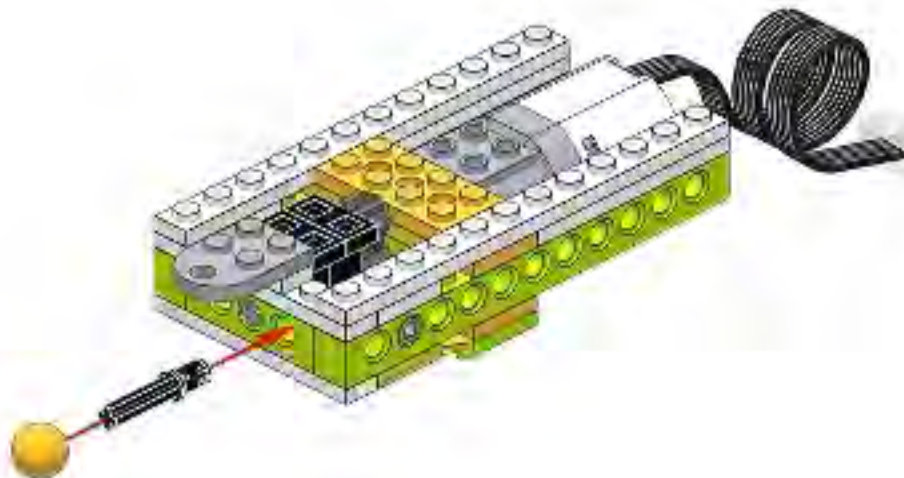


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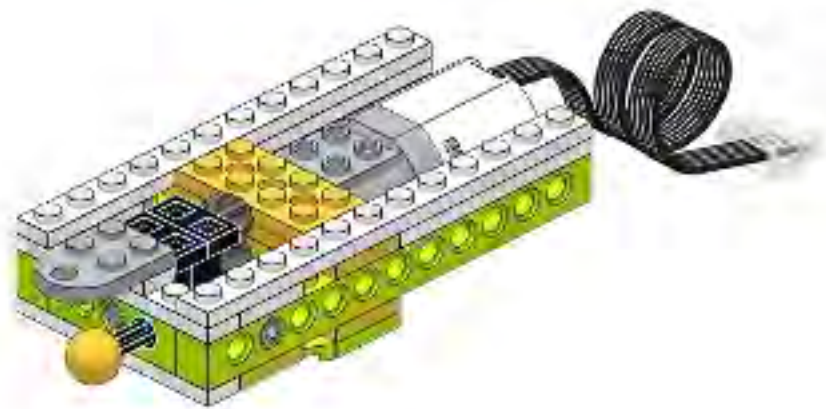


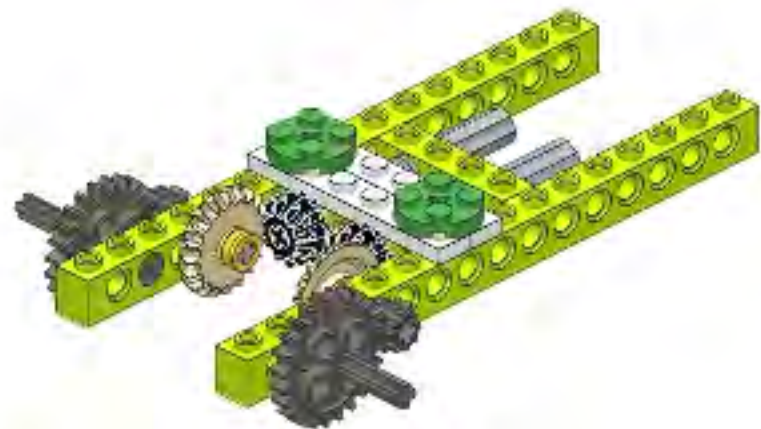
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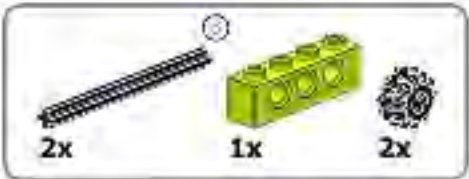
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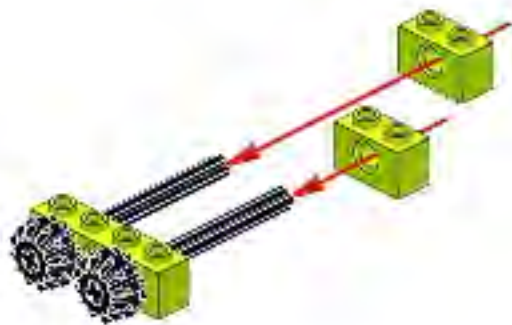
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2x

26





2x

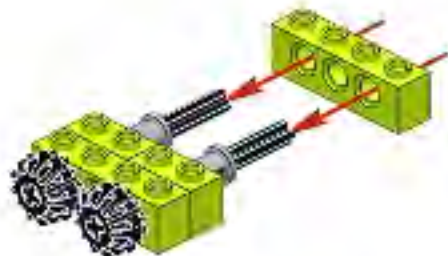
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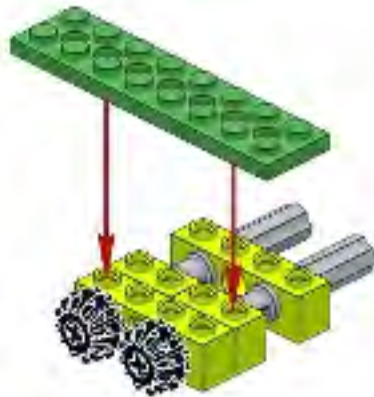
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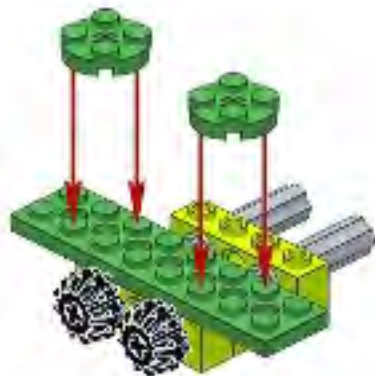
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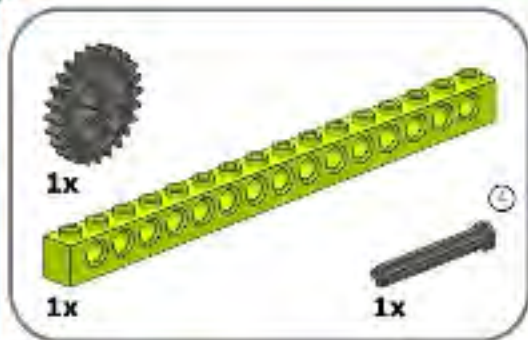


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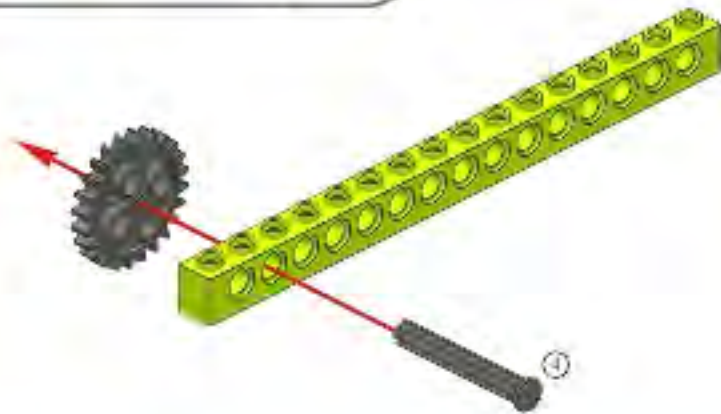
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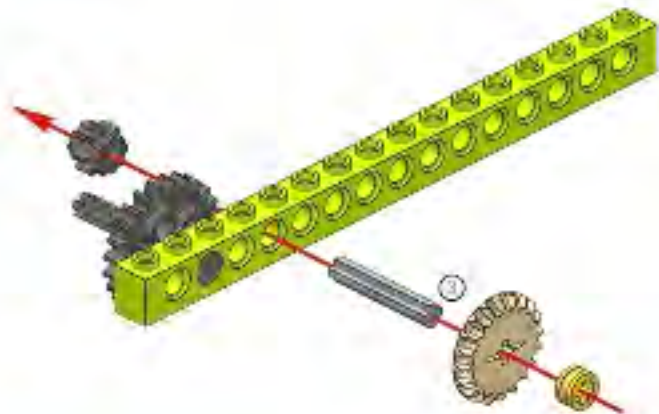




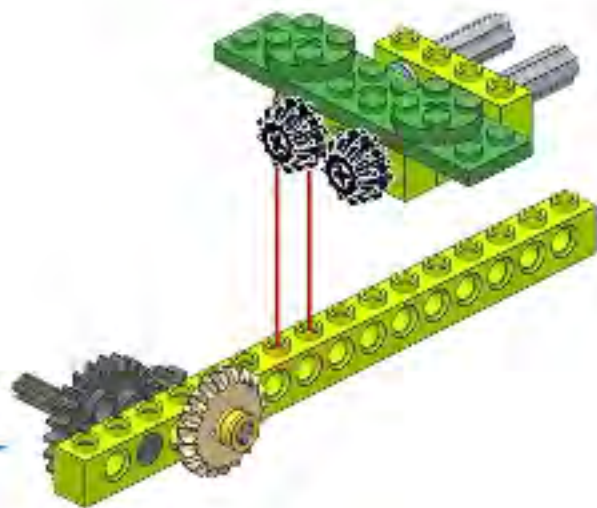
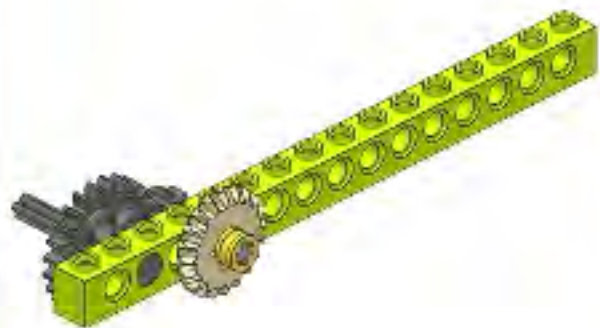
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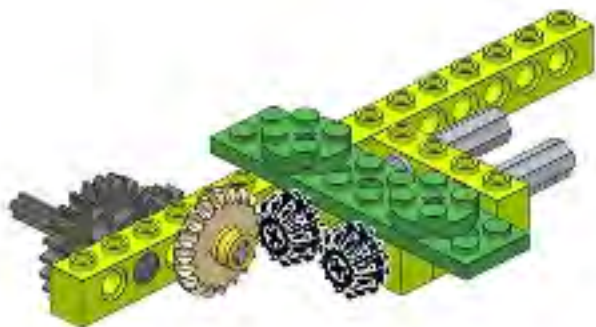


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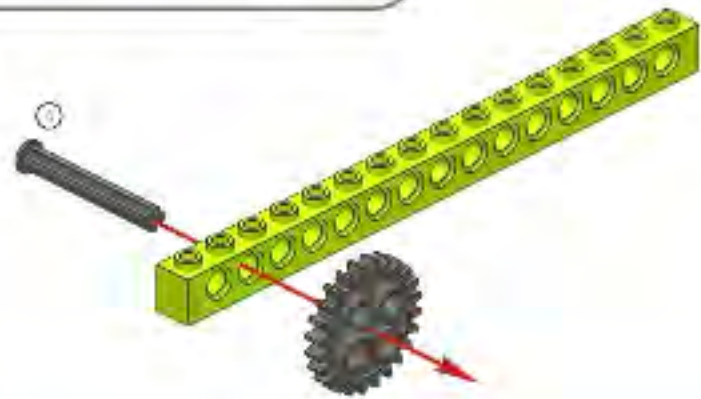
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1x

1x

④

1



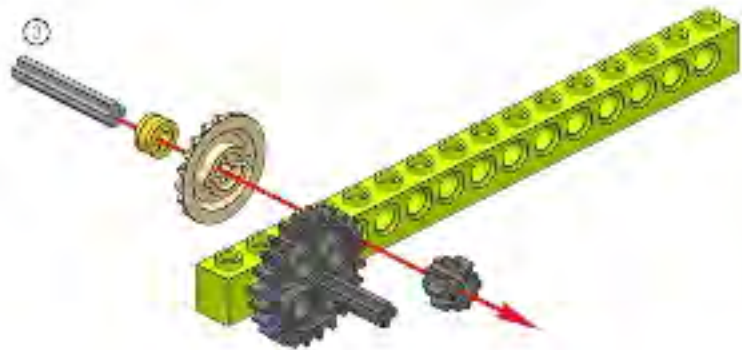
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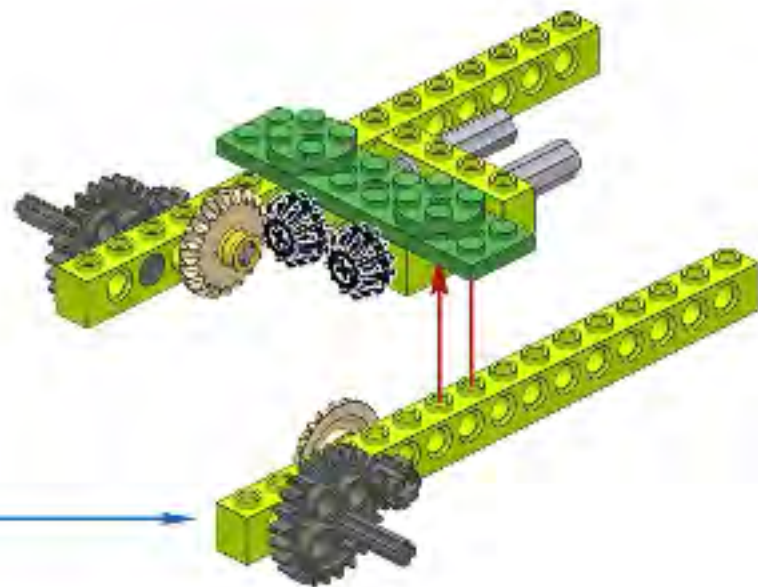
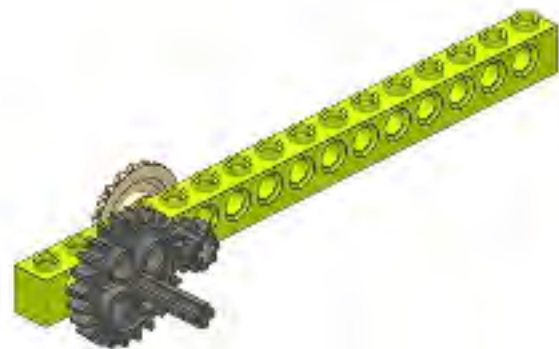
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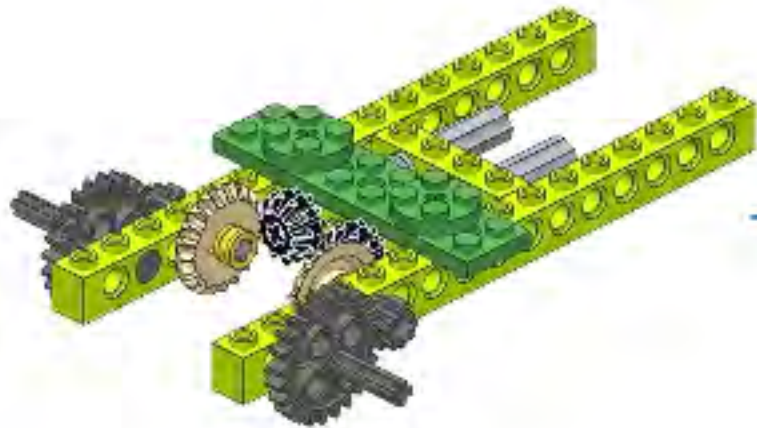
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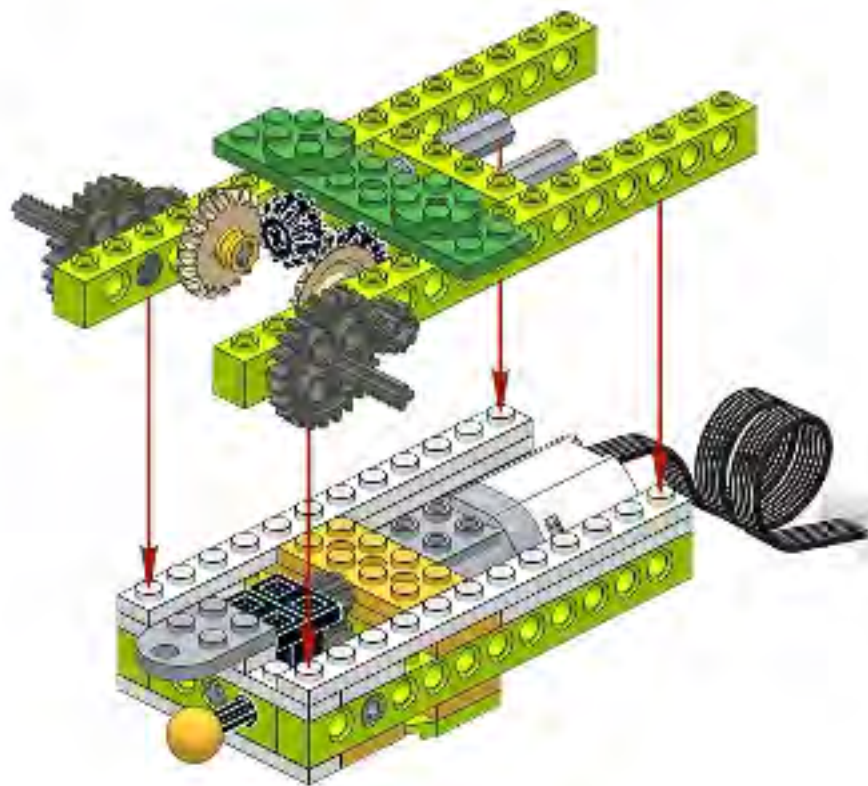


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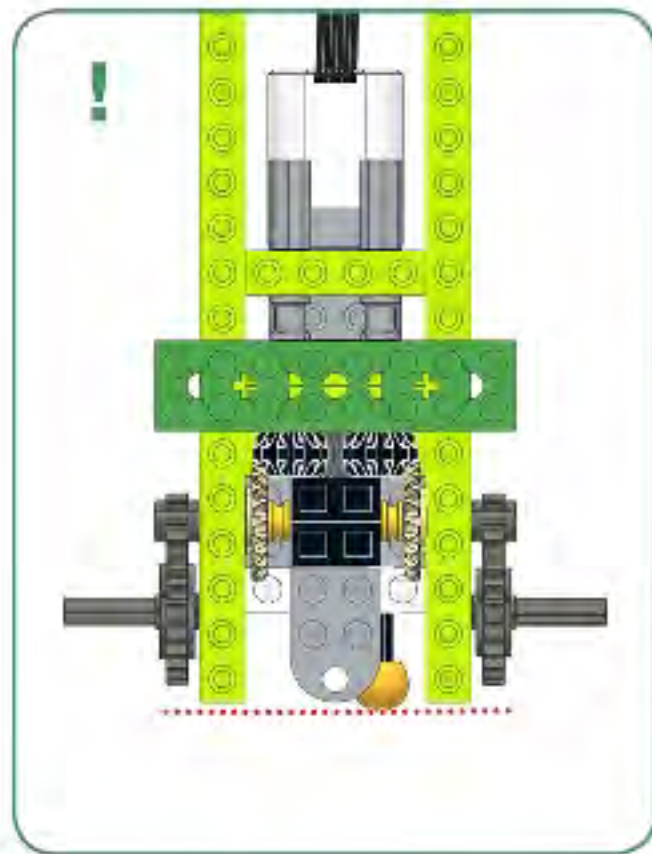
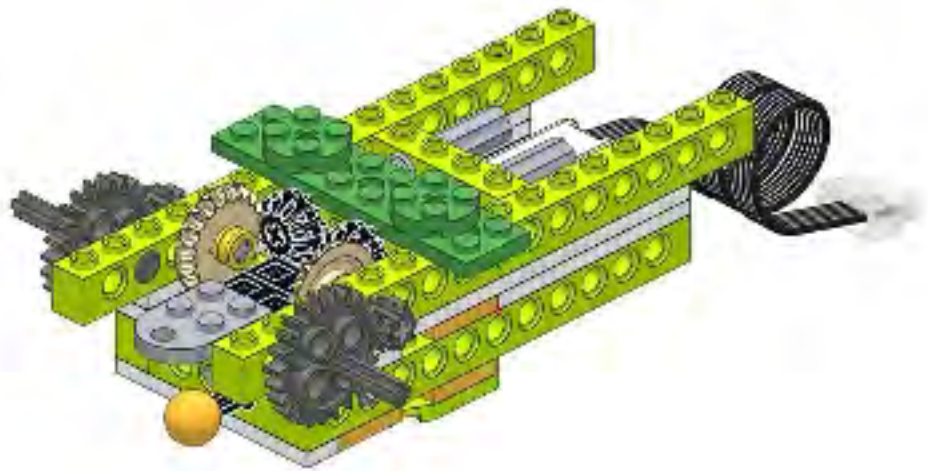




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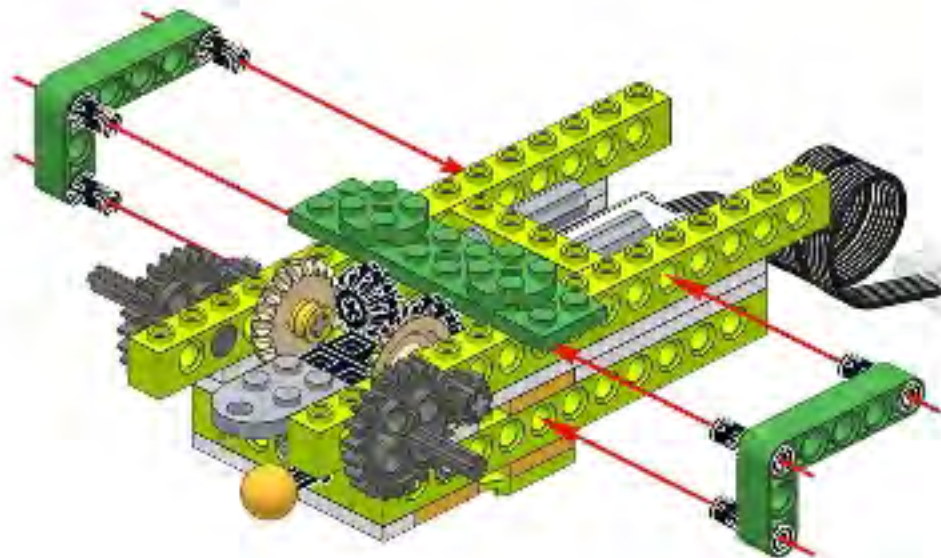
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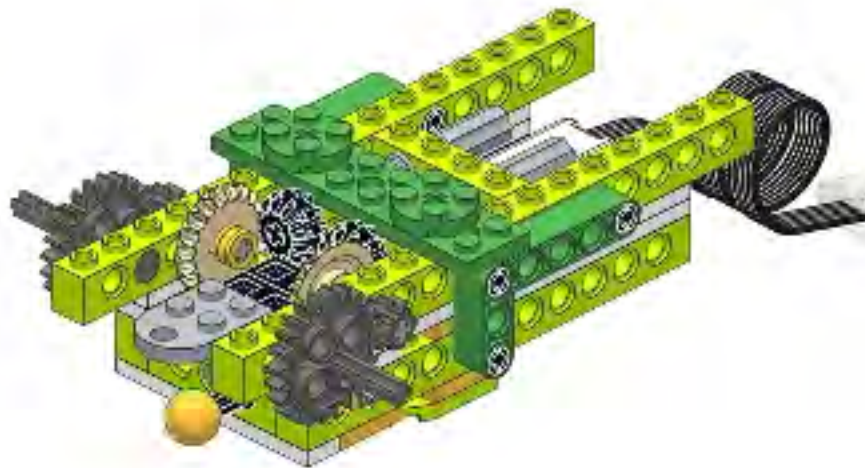


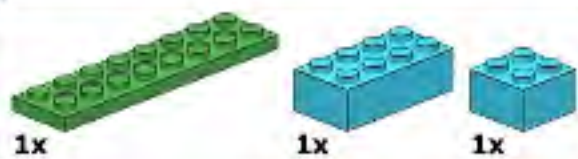
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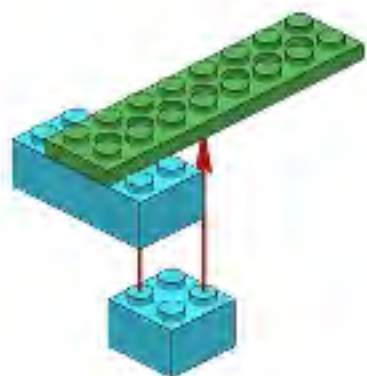


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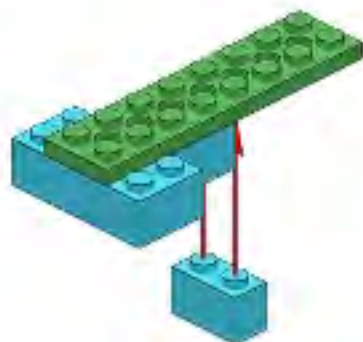




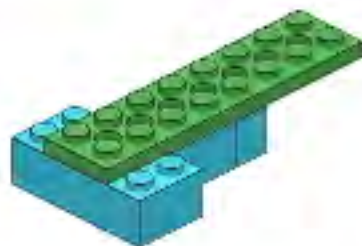
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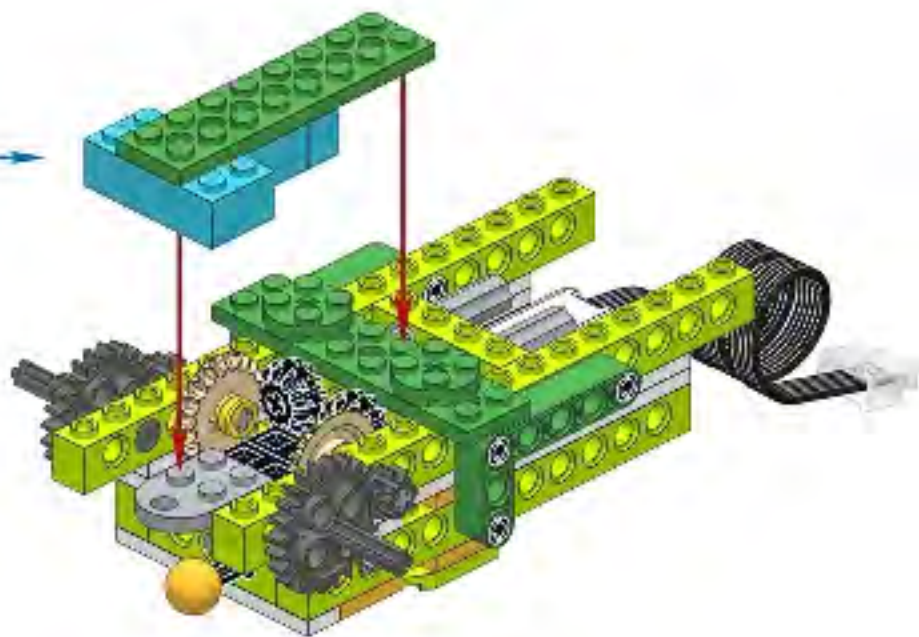


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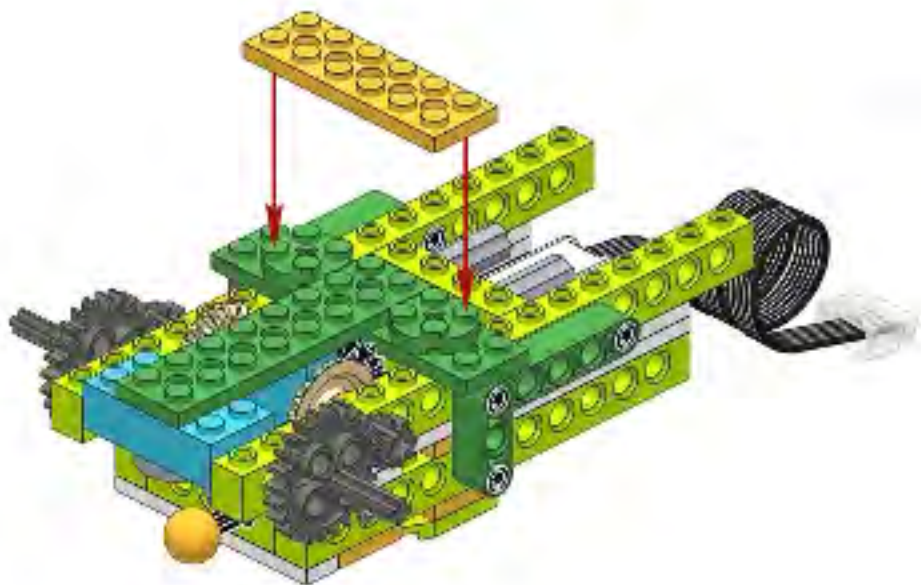






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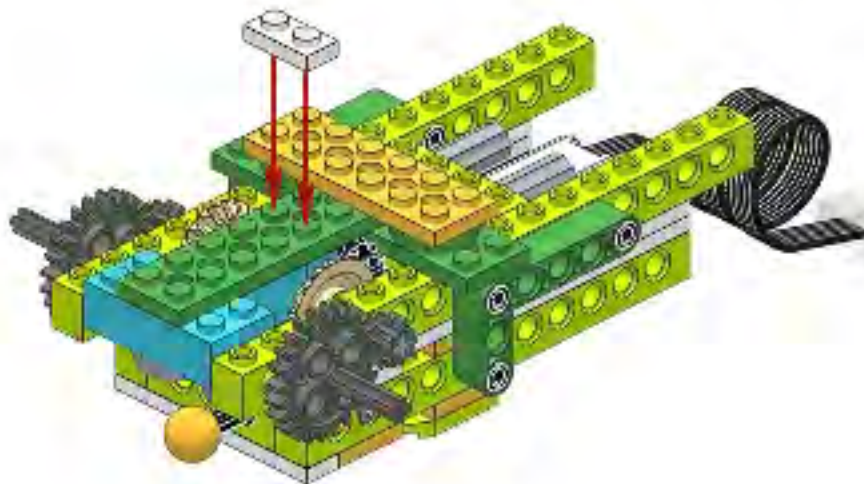
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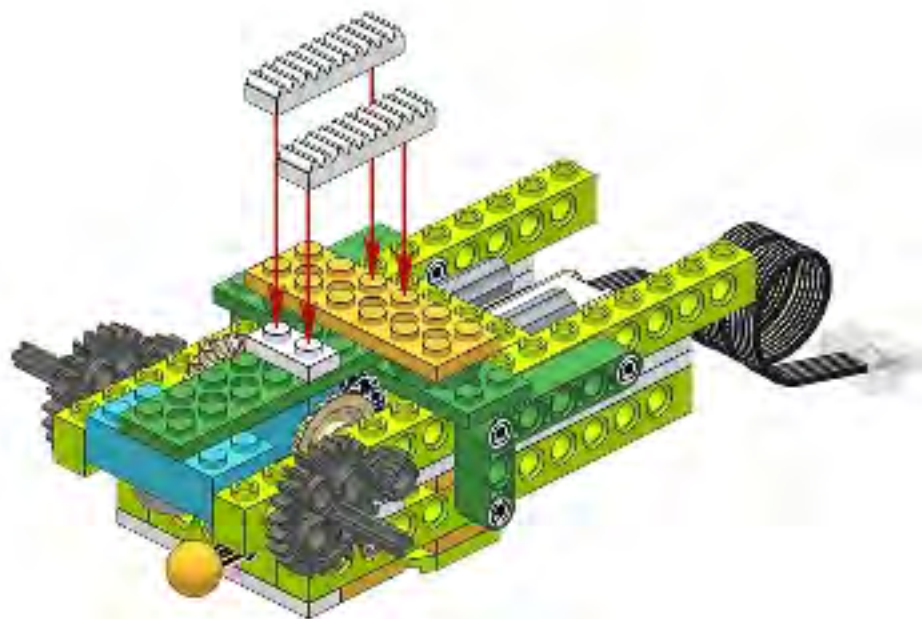
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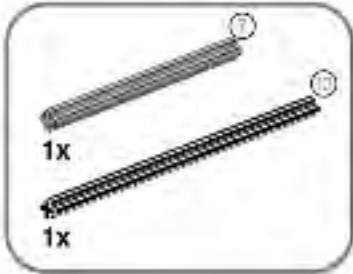




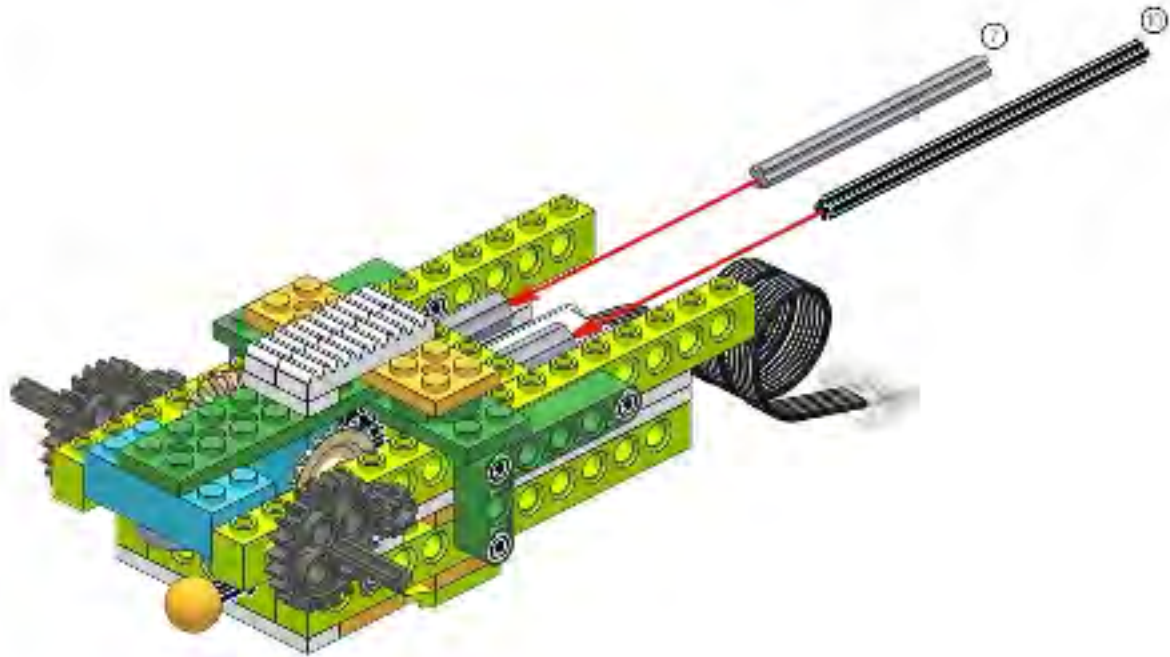
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47





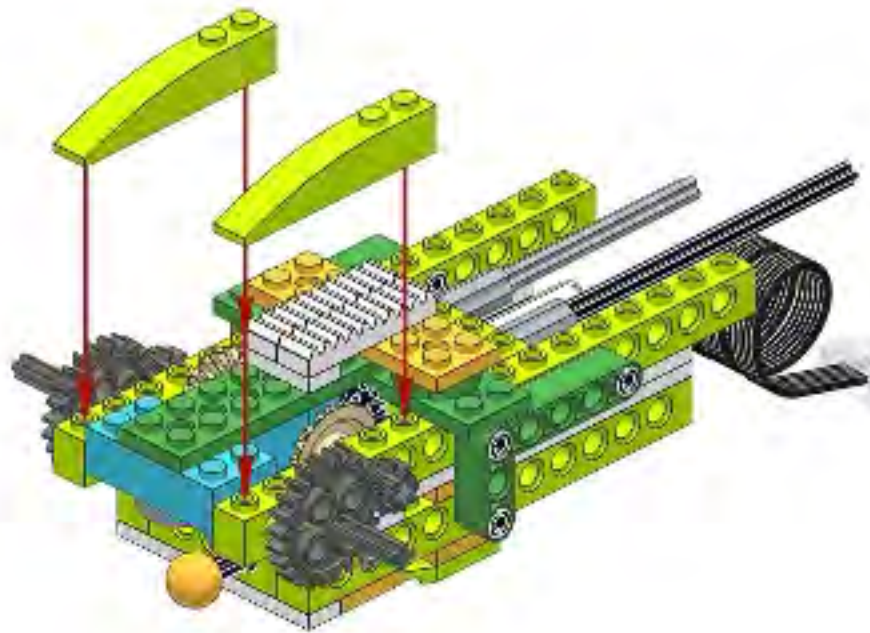
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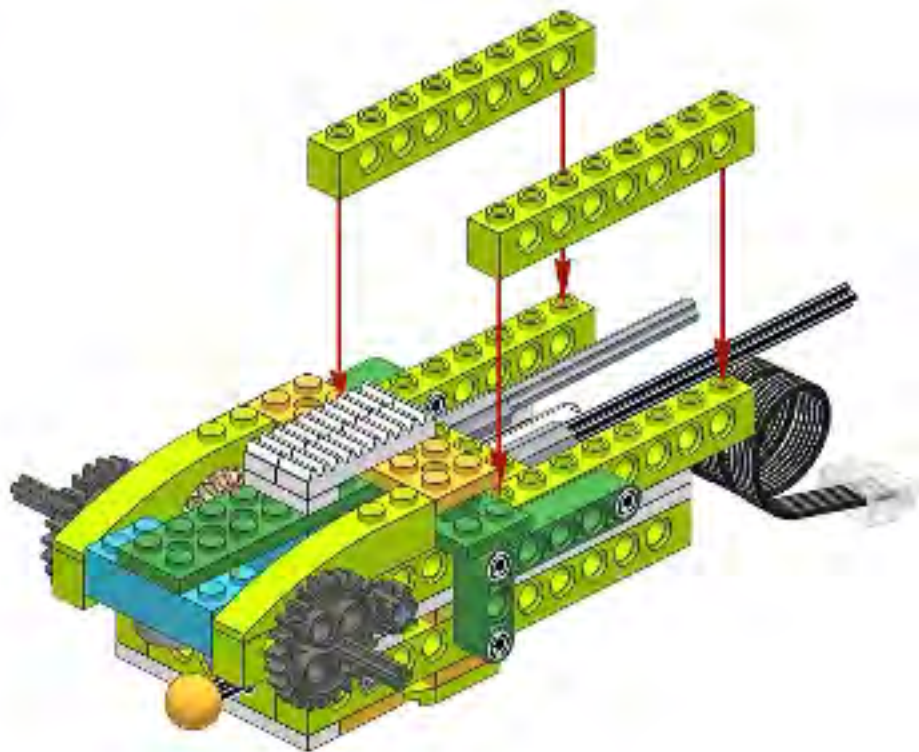
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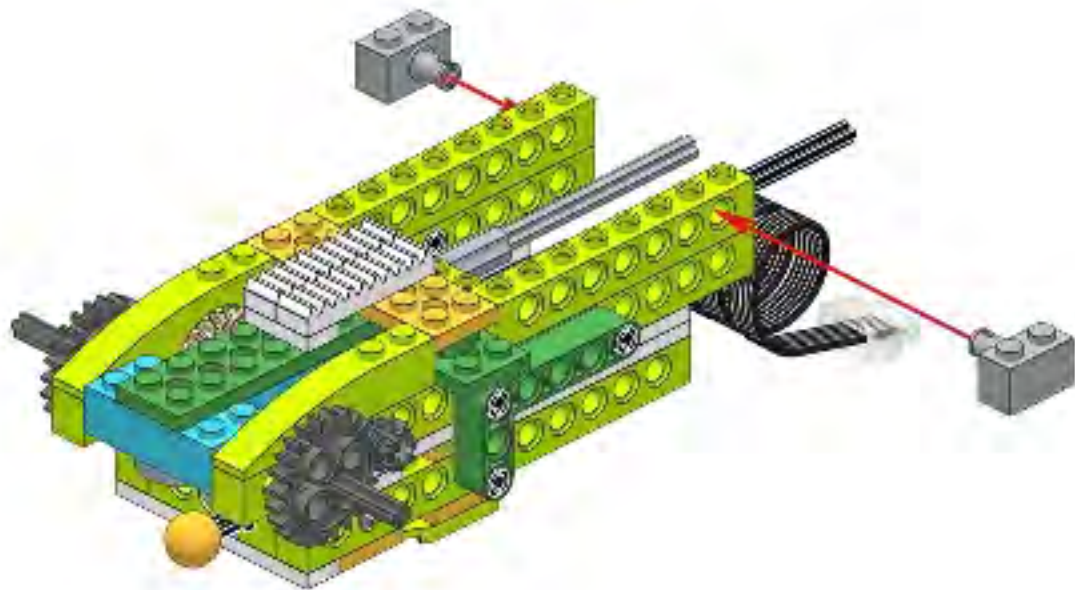
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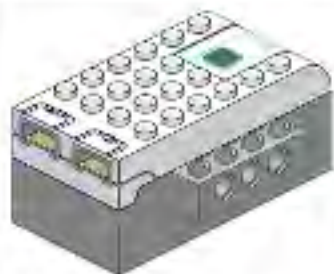




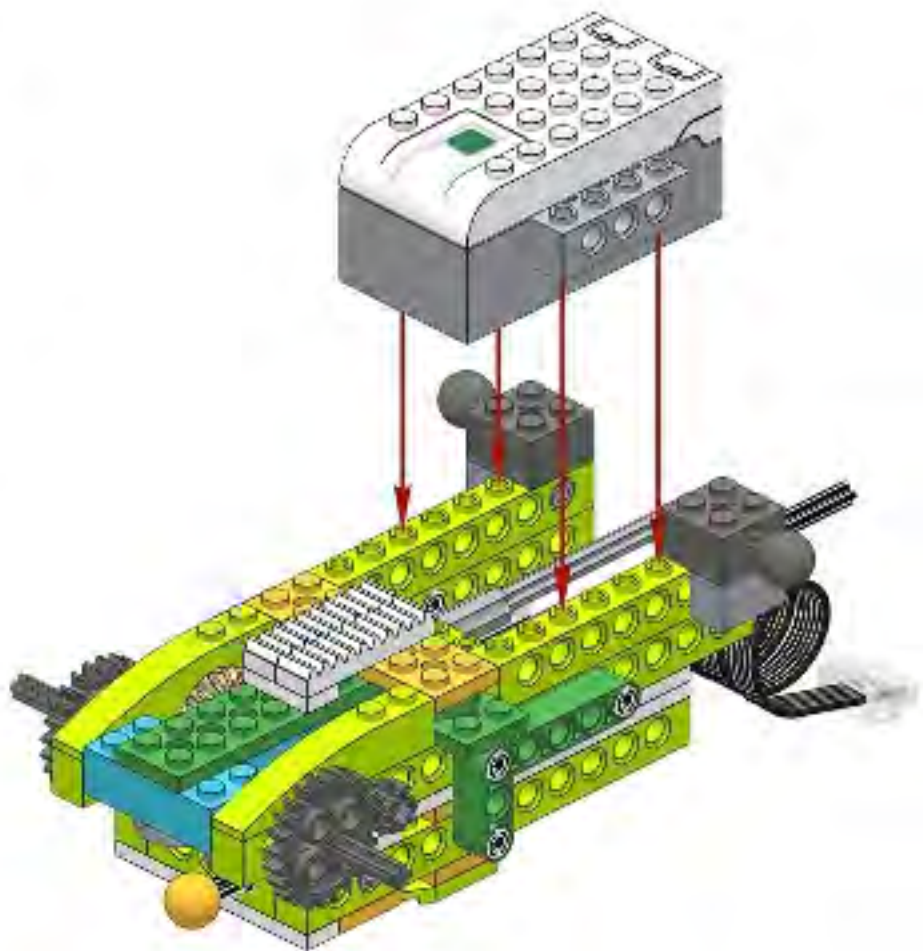
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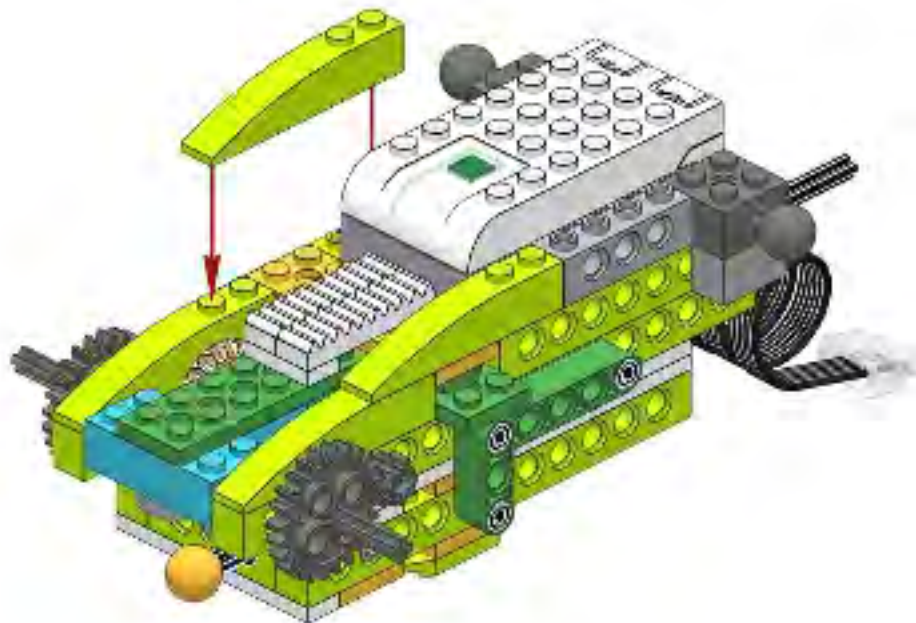
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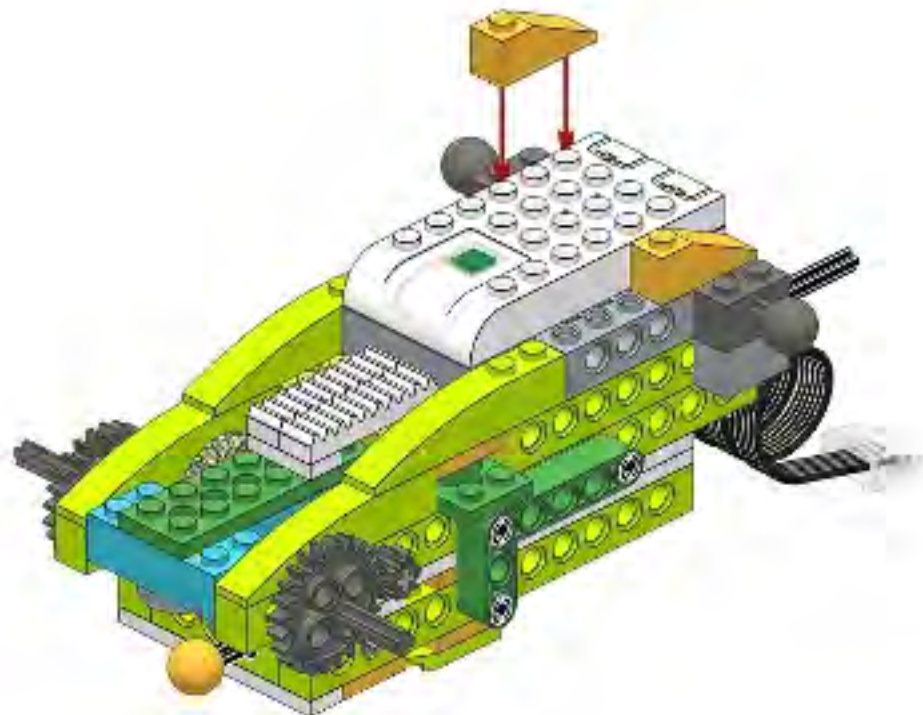
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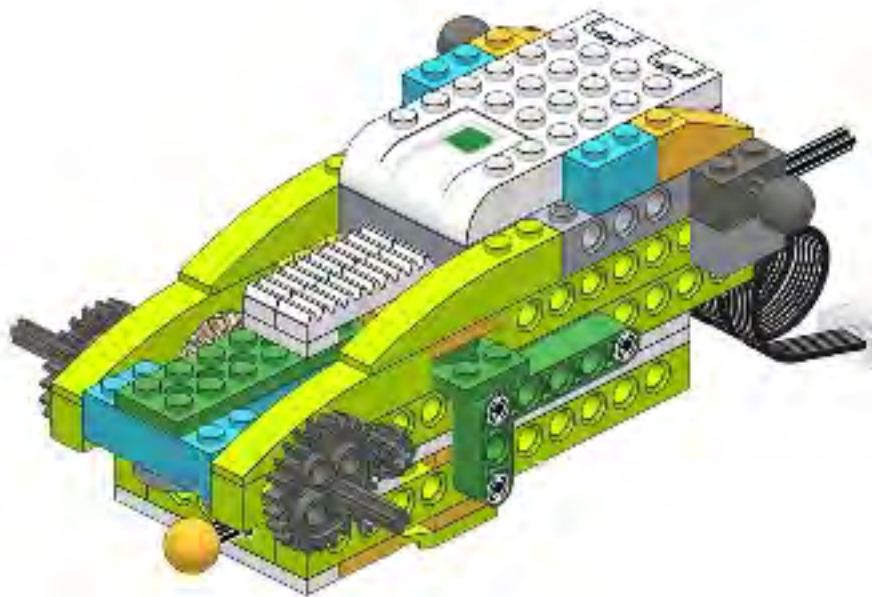
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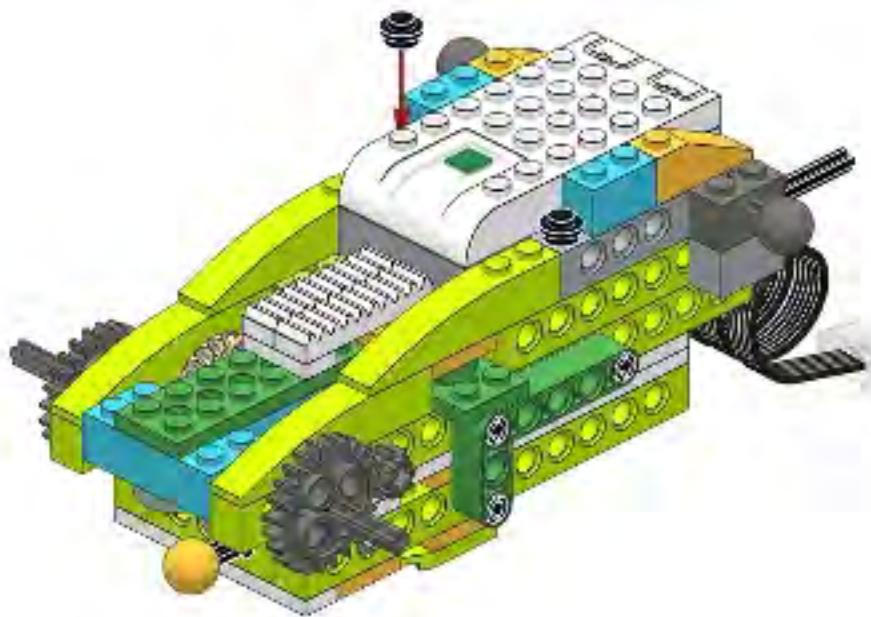
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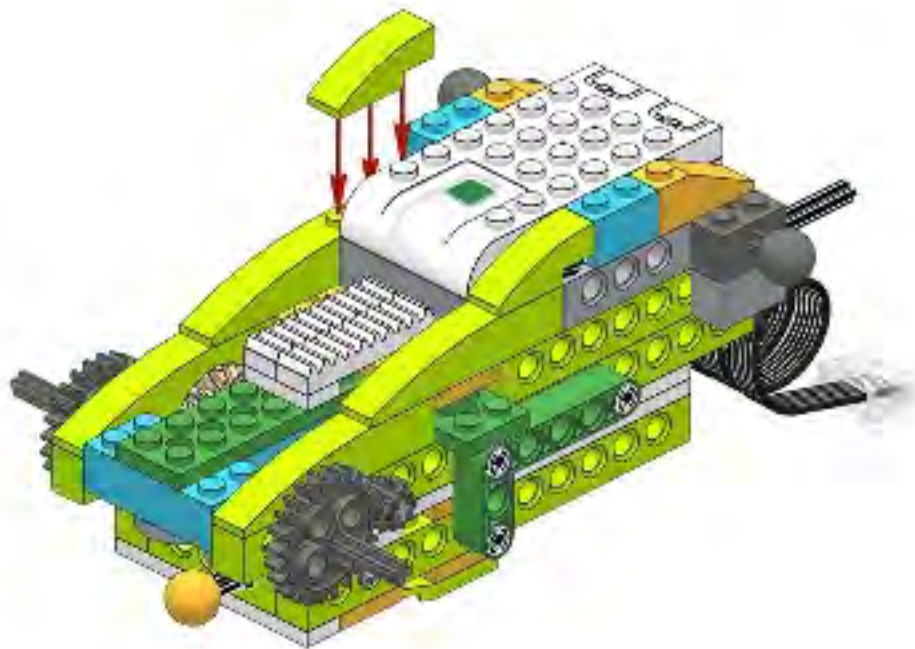
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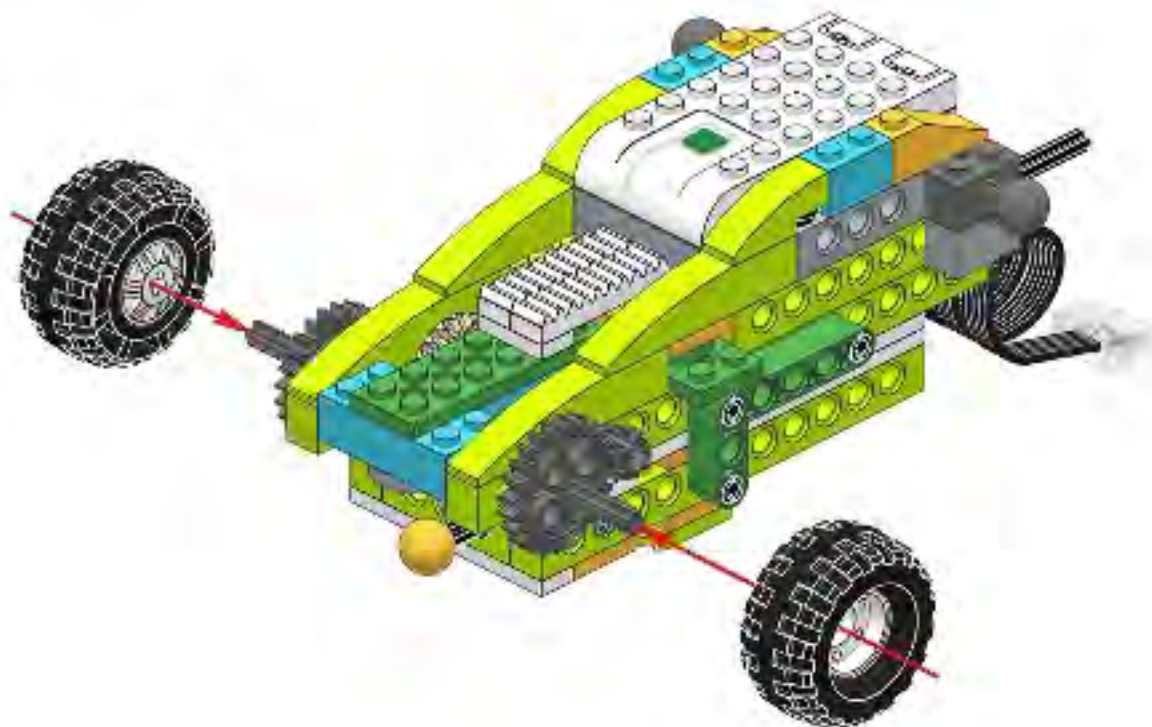
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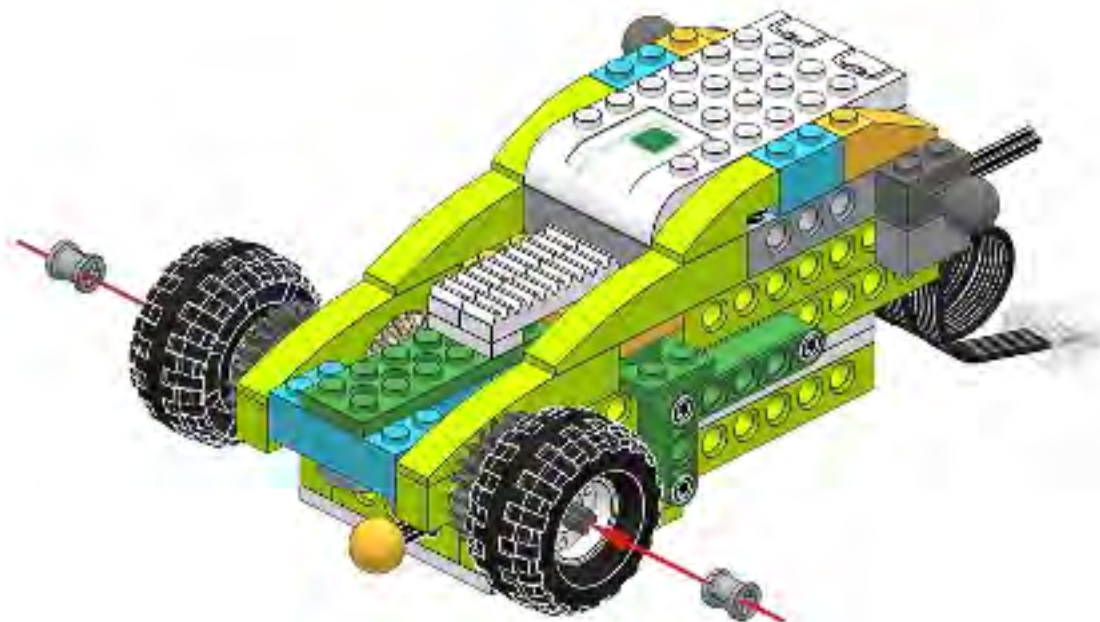
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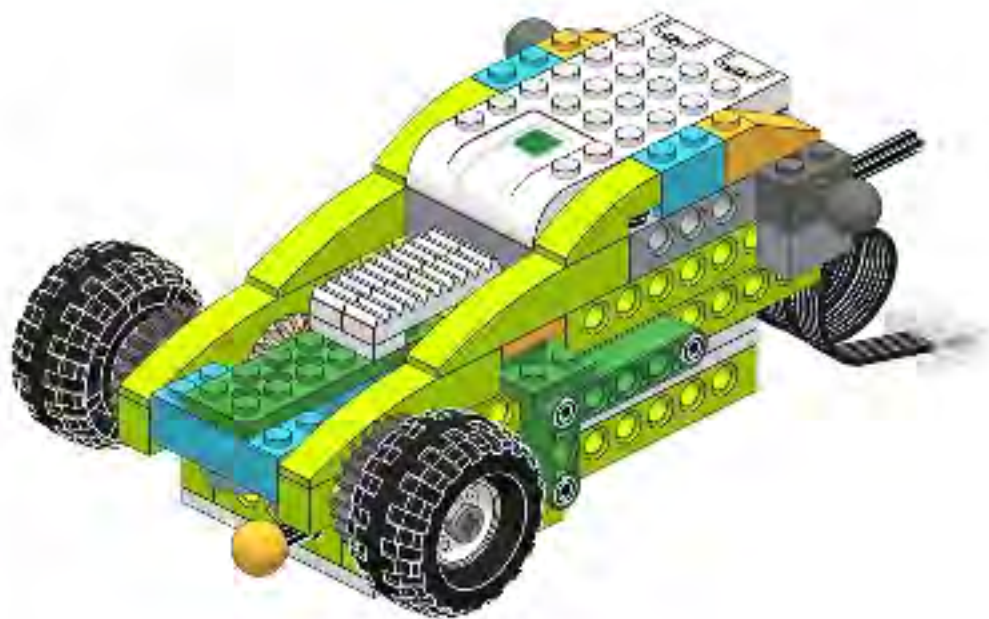




2x

60







1



1x

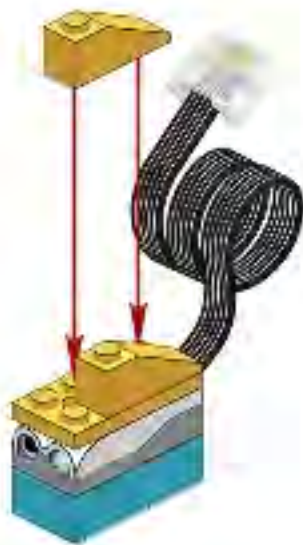
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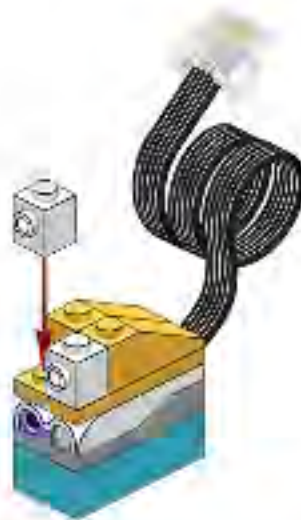
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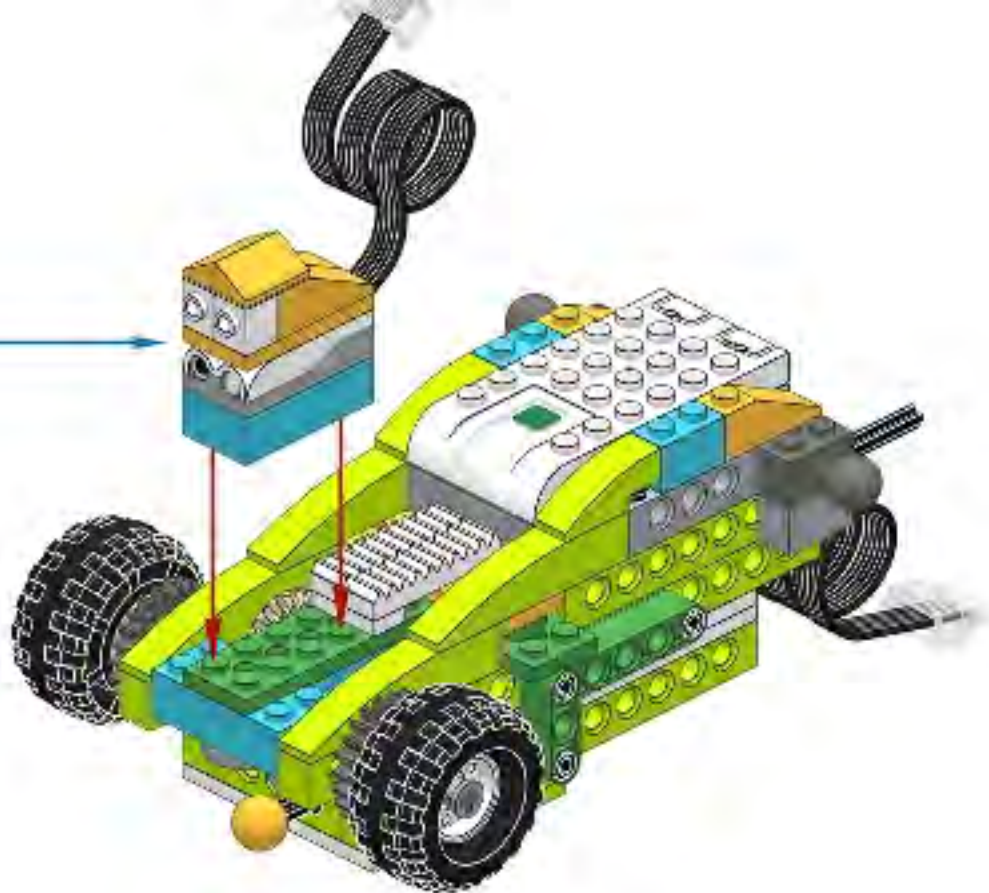
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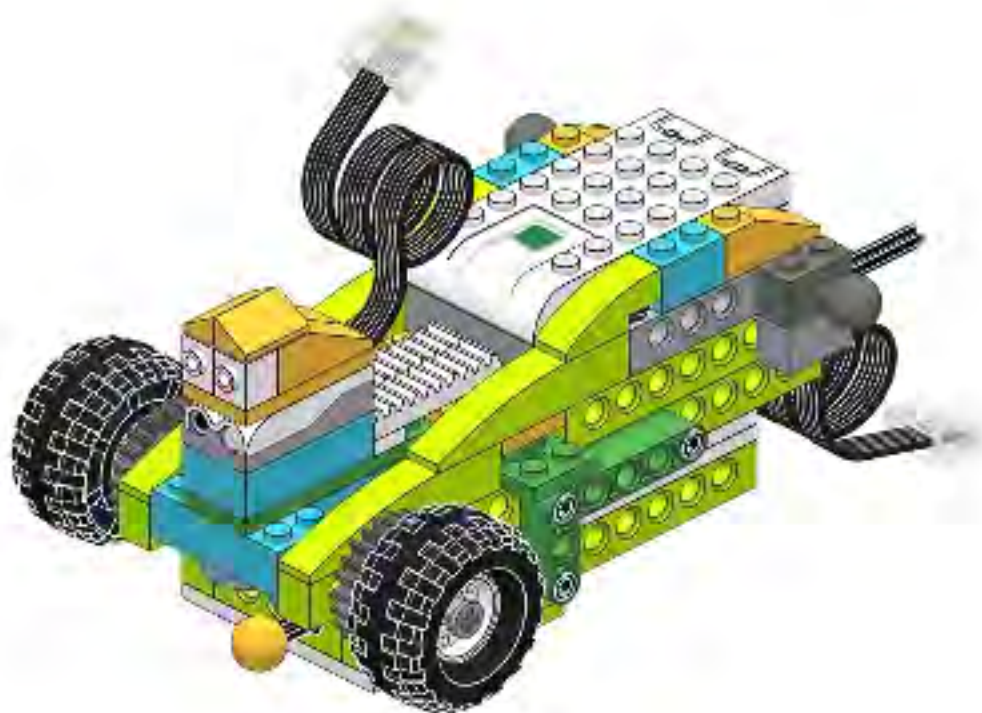
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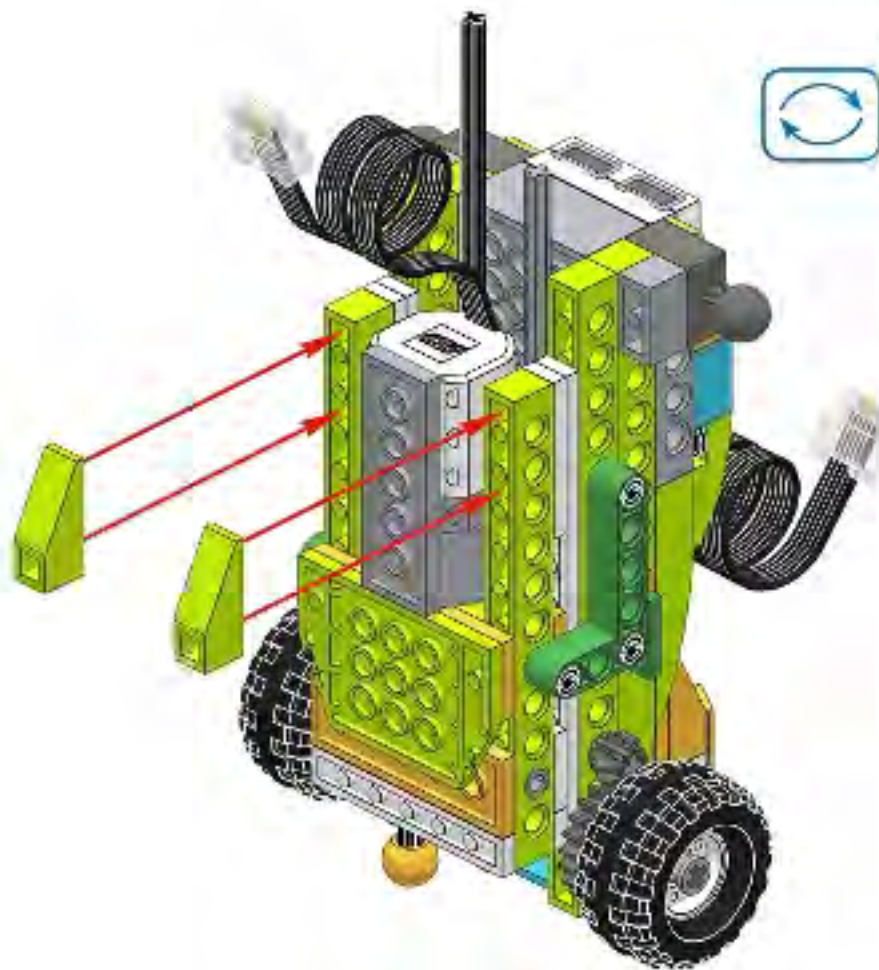




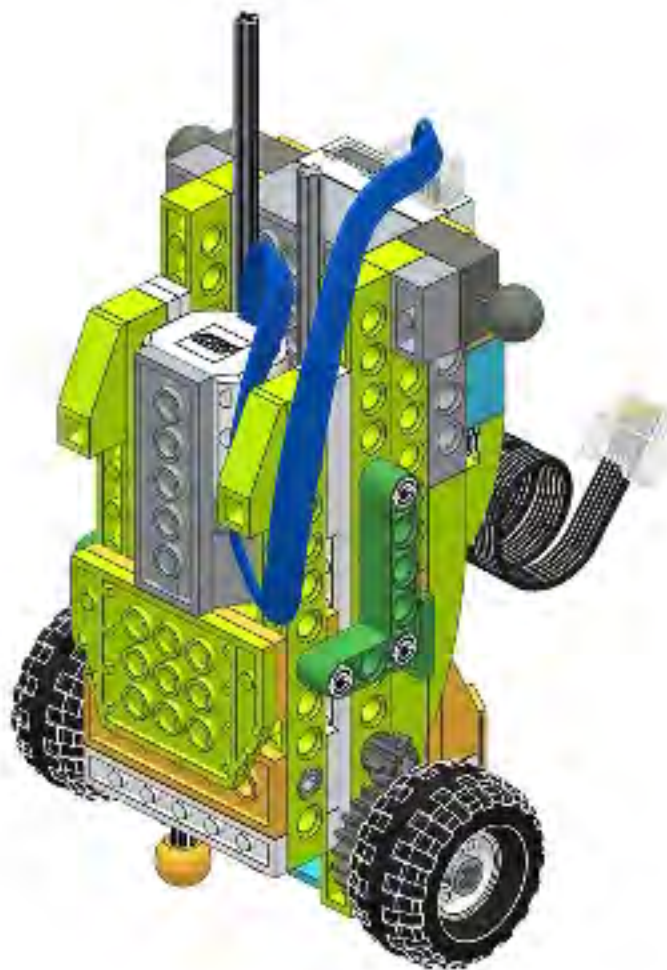
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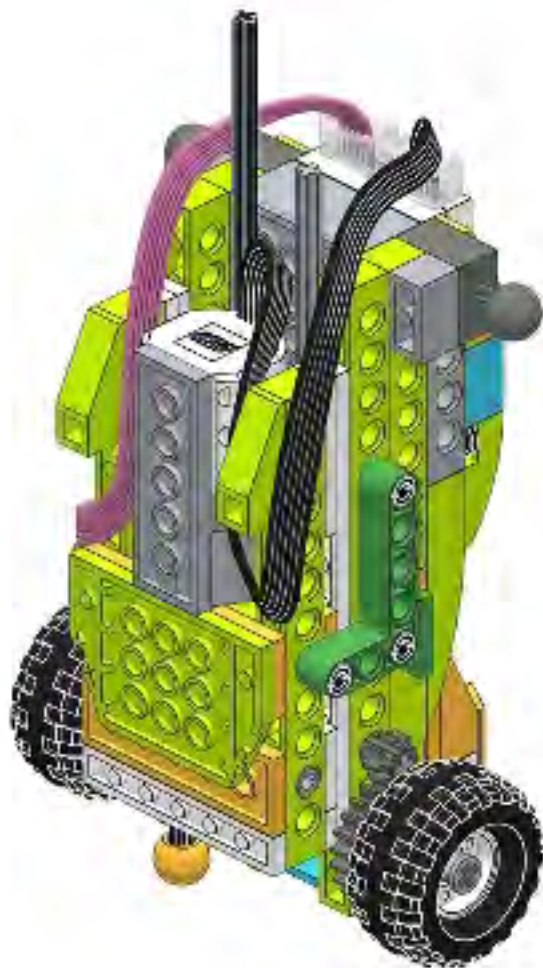


66



67

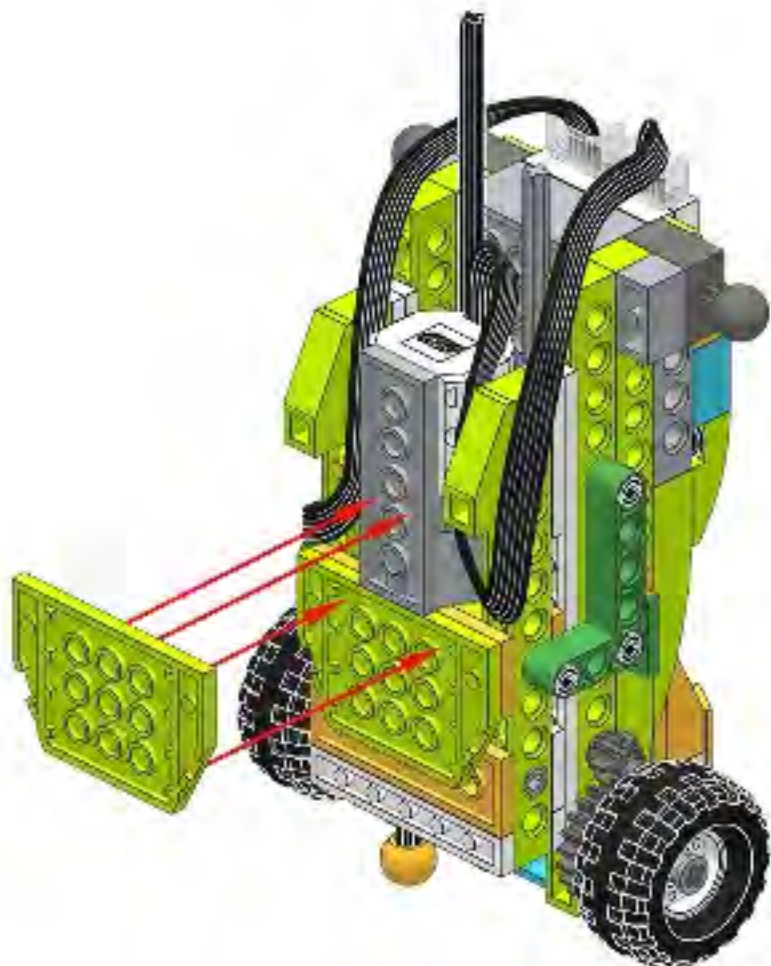


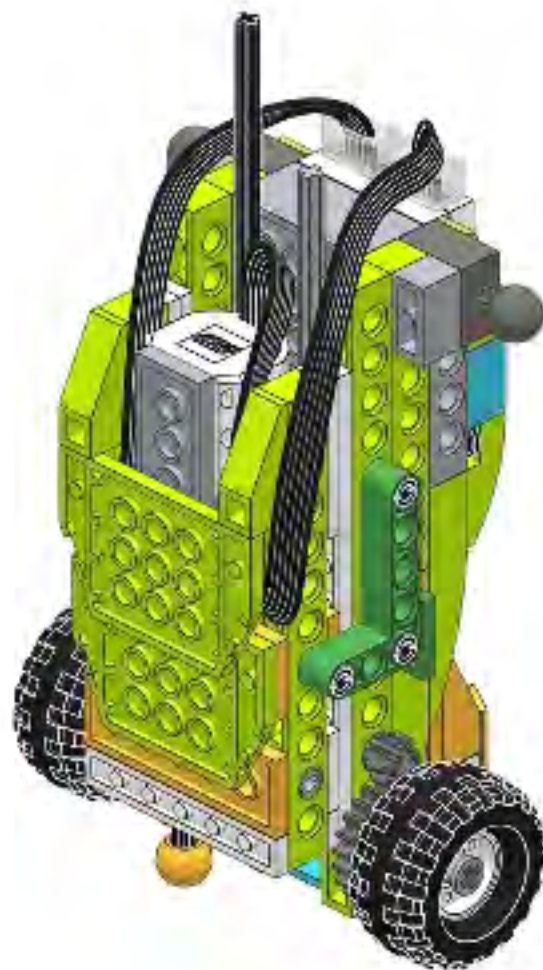




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69



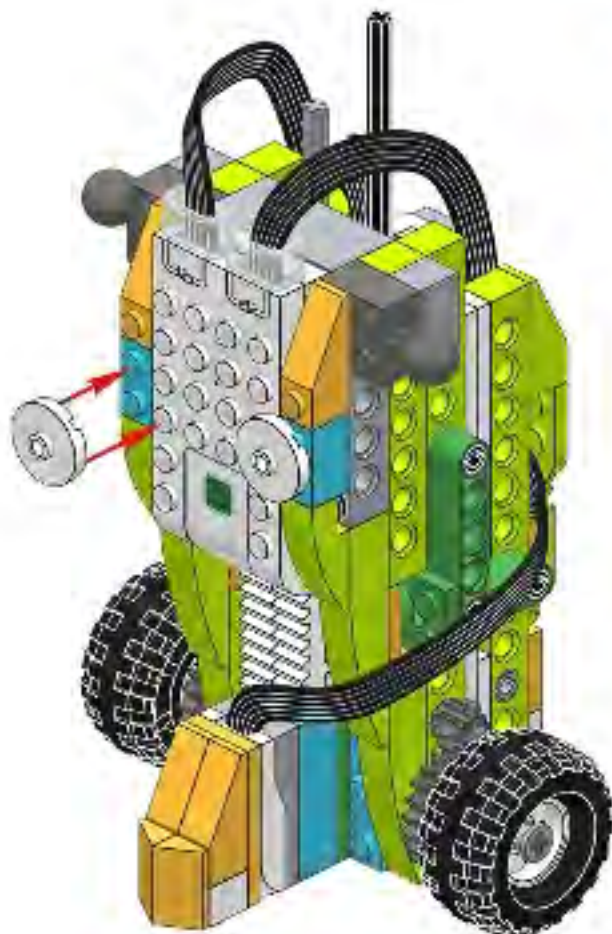




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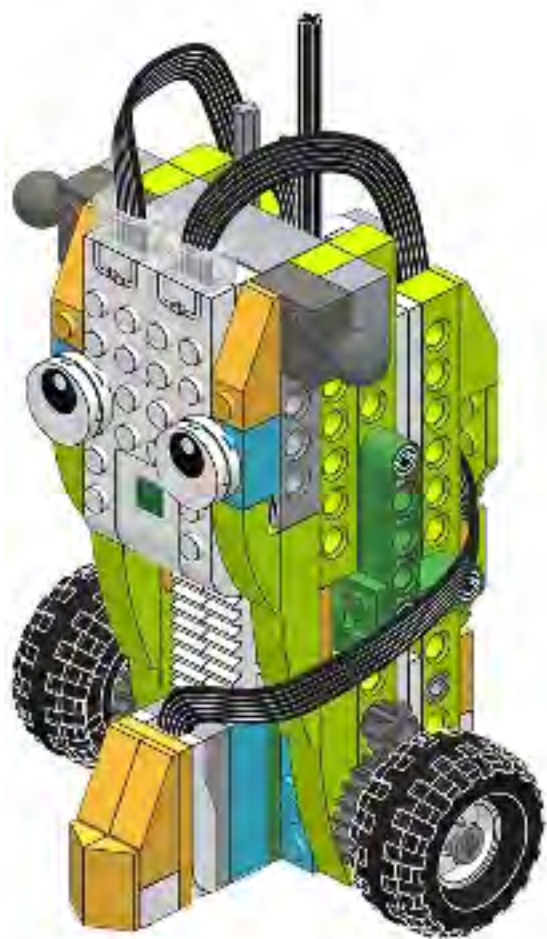


71





2x



72





88





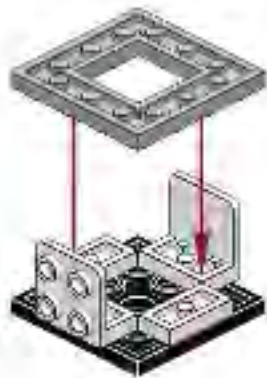
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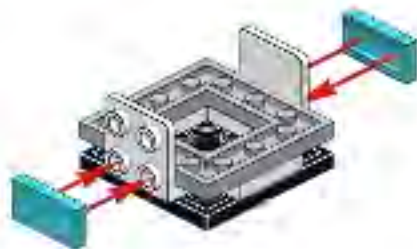
90





2x

91





92





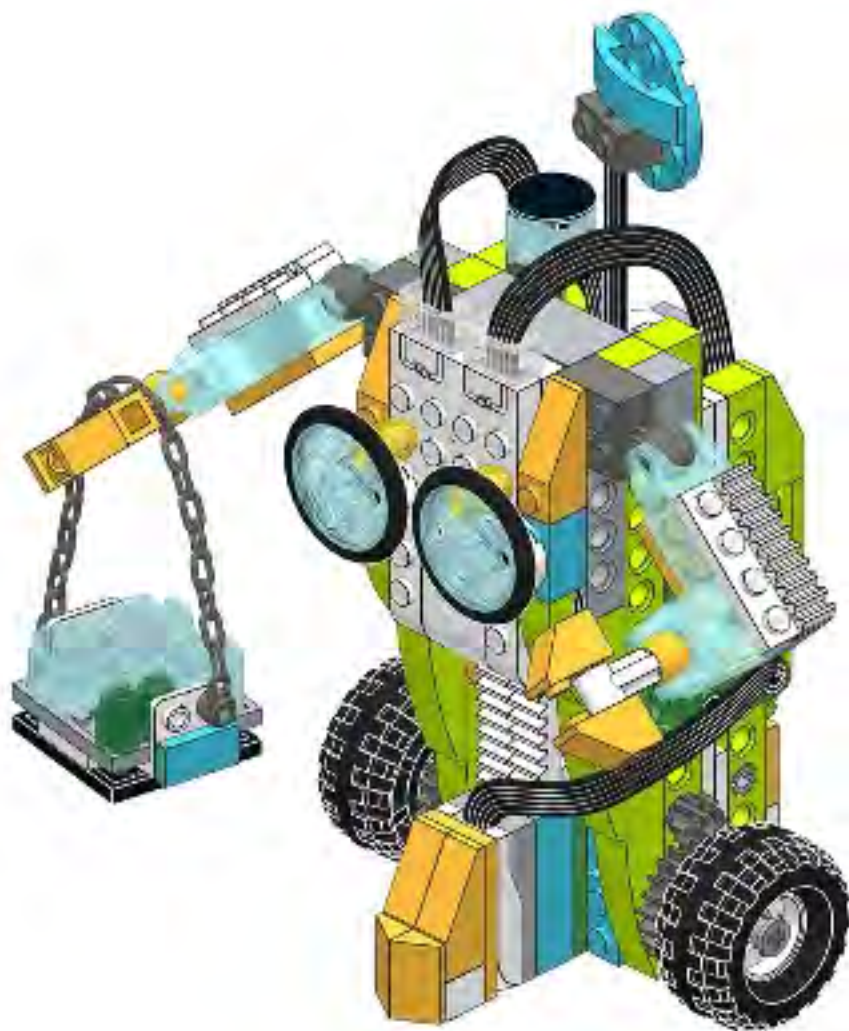
93





94







Task 4. Questions

What program blocks are used for crossing of the line?





Task 4

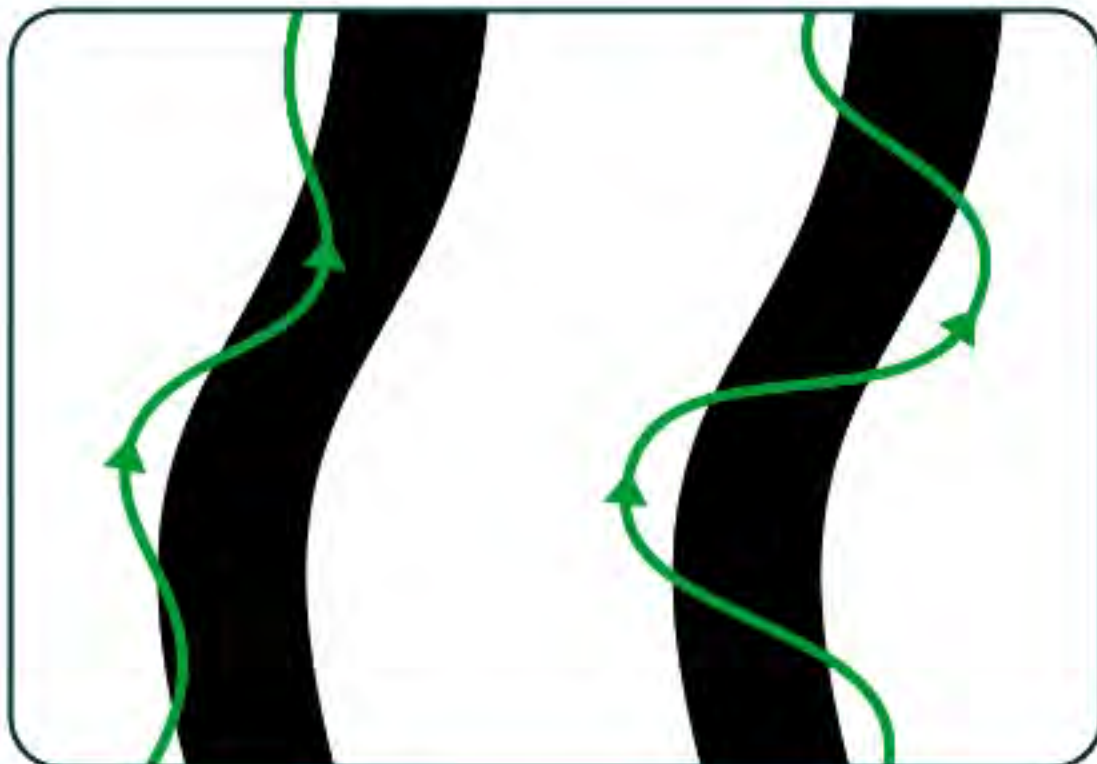
In order for the robot can move more stable, program such robot's movement along the black line, at which it crosses it from the left border to the right and the back.





Trajectory of movement

Trajectory of the movement of your robot resembled a snake. On the picture below it is depicted on the left. In order for the robot to move more stable, its trajectory must cross the line:





Trajectory of movement

Trajectory of the movement of your robot resembled a snake. On the picture below it is depicted on the left. In order for the robot to move more stable, its trajectory must cross the line:

